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**Nishikage et al.**

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(45) **Date of Patent:** **May 17, 2016**

(54) **PRESSURE SENSOR AND METHOD FOR  
MANUFACTURING PRESSURE SENSOR**

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(73) Assignee: **ROHM CO., LTD**, Kyoto (JP)

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patent is extended or adjusted under 35  
U.S.C. 154(b) by 200 days.

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(2), (4) Date: **Apr. 23, 2012**

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Nov. 4, 2009	(JP)	2009-252903
Nov. 10, 2009	(JP)	2009-256759
Nov. 10, 2009	(JP)	2009-256760
Nov. 12, 2009	(JP)	2009-258710

(51) **Int. Cl.**

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<b>H01L 29/10</b>	(2006.01)
<b>H01L 31/036</b>	(2006.01)
<b>G01L 9/00</b>	(2006.01)

(52) **U.S. Cl.**

CPC ..... **G01L 9/0047** (2013.01); **G01L 9/0045**  
(2013.01); **G01L 9/0054** (2013.01)

(58) **Field of Classification Search**

CPC ..... H01L 29/84; B81C 1/00158  
USPC ..... 257/414, 419; 438/50, 51  
See application file for complete search history.

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*Primary Examiner* — John C Ingham

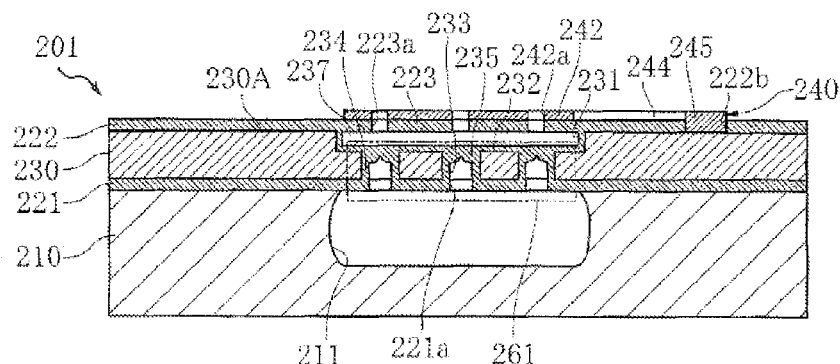
*Assistant Examiner* — Ismail Muse

(74) *Attorney, Agent, or Firm* — Hamre, Schumann, Mueller  
& Larson, P.C.

(57) **ABSTRACT**

A pressure sensor 1 comprises a semiconductor substrate 10, insulating layers 21, 22, 23 formed on the semiconductor substrate 10, a semiconductor layer 30 formed on the semiconductor substrate 10 with the insulating layers 21, 23 intervening therebetween, and a cavity portion 13 provided between the semiconductor substrate 10 and the semiconductor layer 30. The portion of the semiconductor layer 30 which overlaps the cavity portion 13 as viewed in a lamination direction serves as a movable portion 31. The cavity portion 13 is surrounded by the insulating layers 22, 23. With this arrangement, the pressure sensor 1 can be manufactured easily with high precision.

**8 Claims, 77 Drawing Sheets**



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FIG. 1

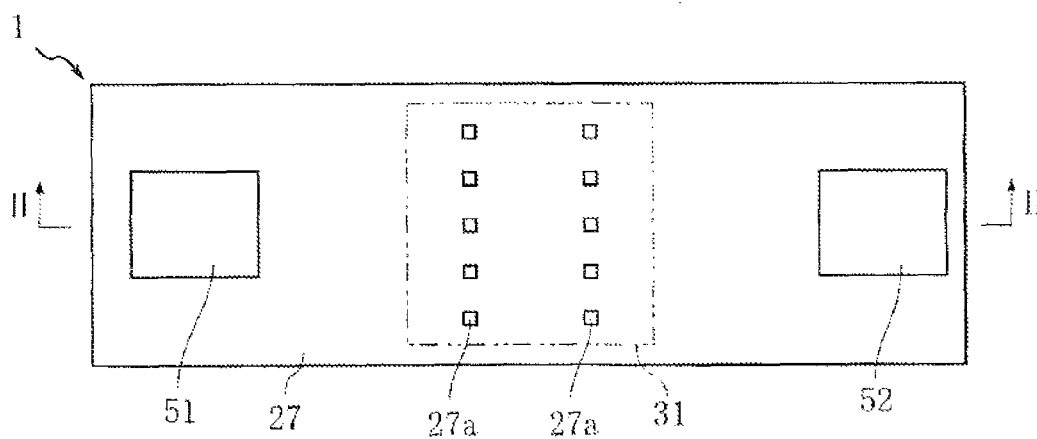


FIG. 2

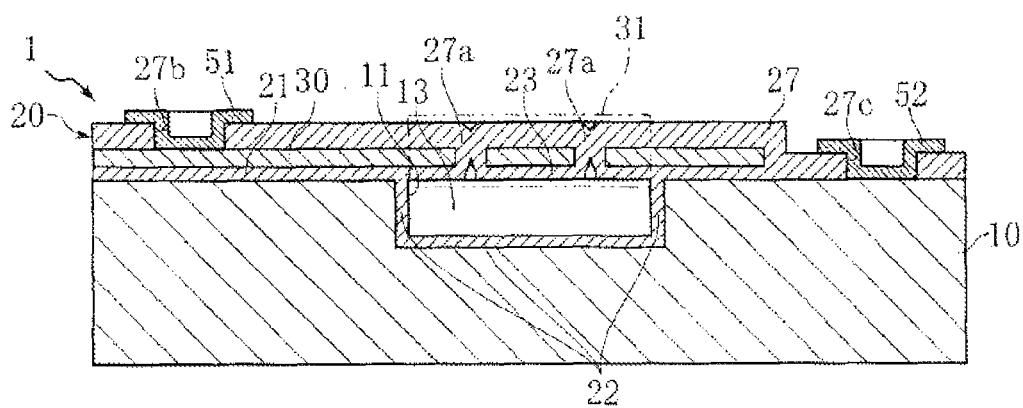


FIG.3

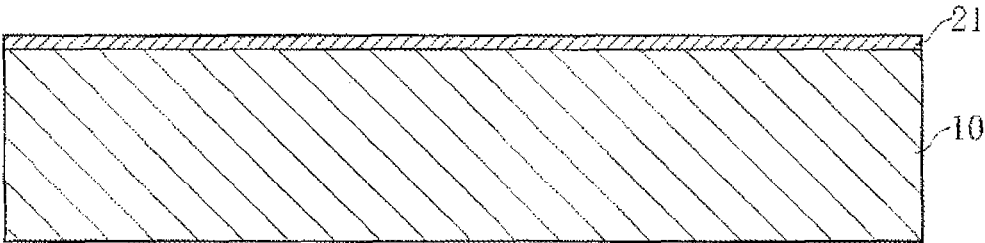


FIG.4

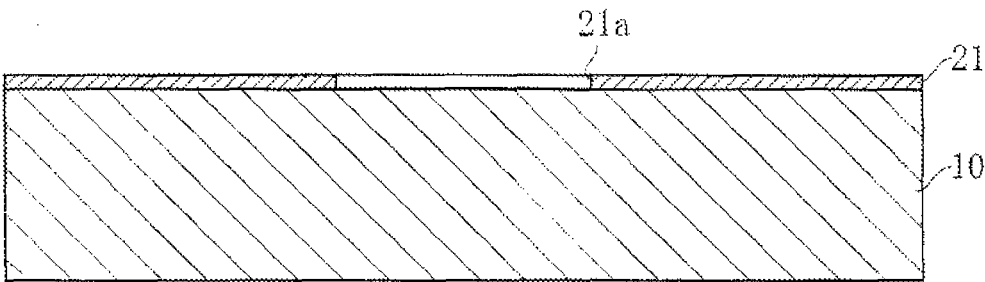


FIG.5

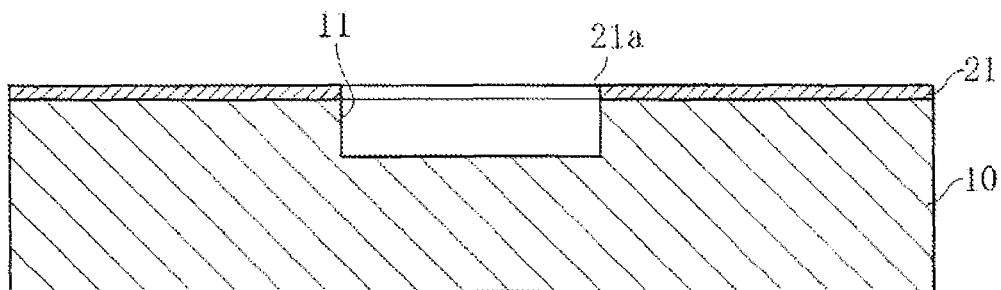


FIG.6

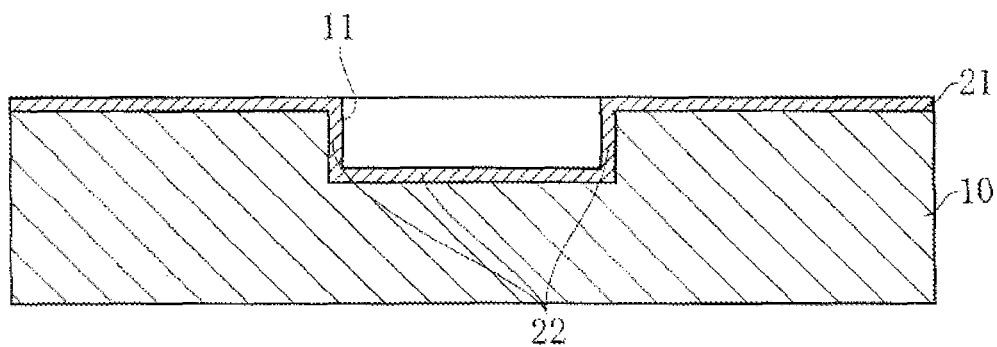


FIG.7

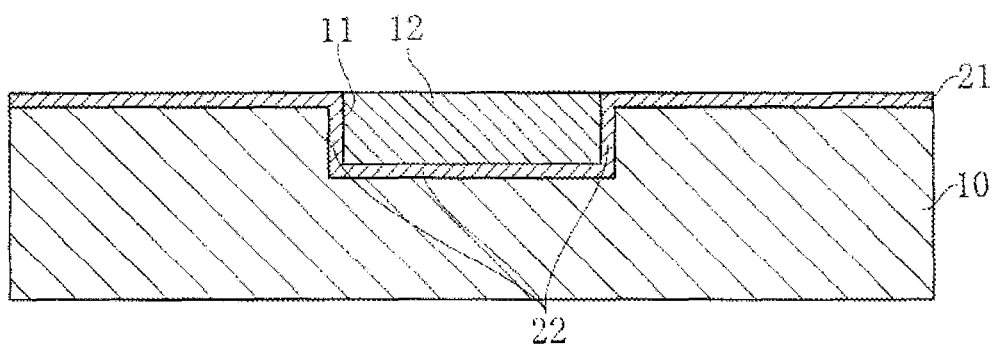


FIG.8

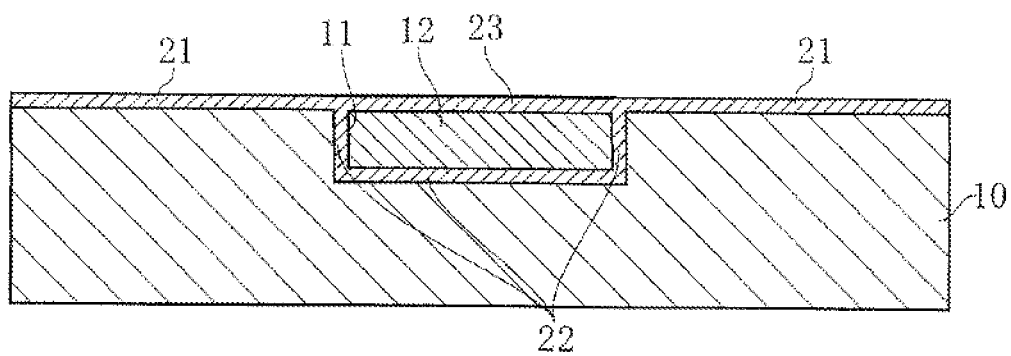


FIG.9

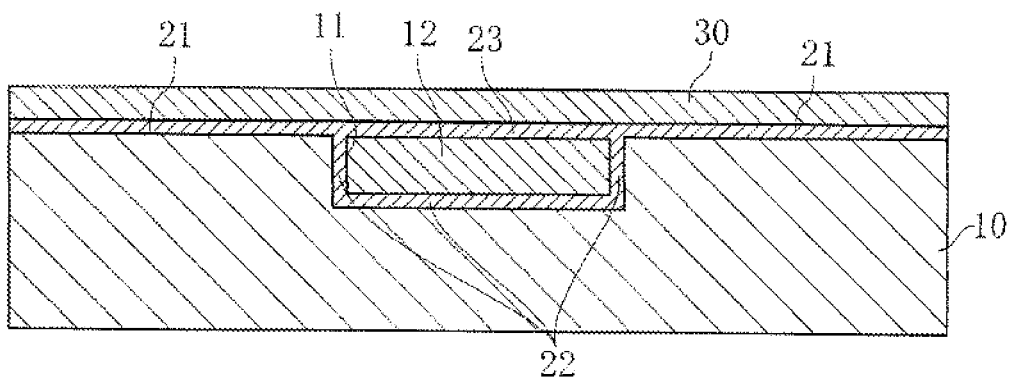
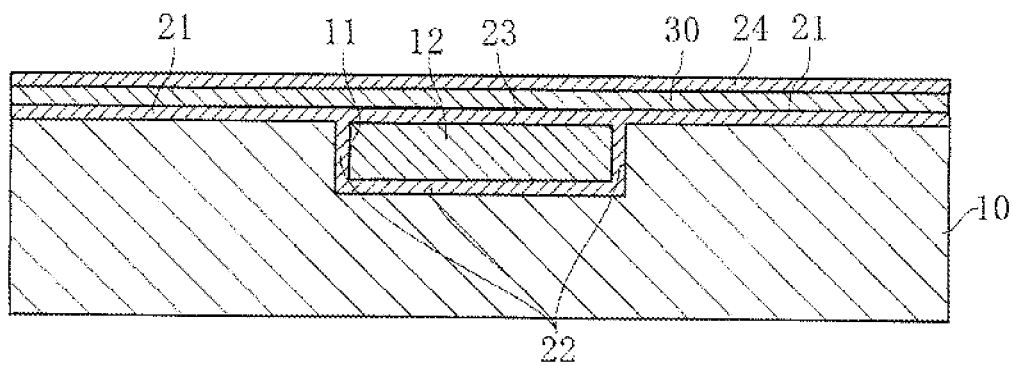
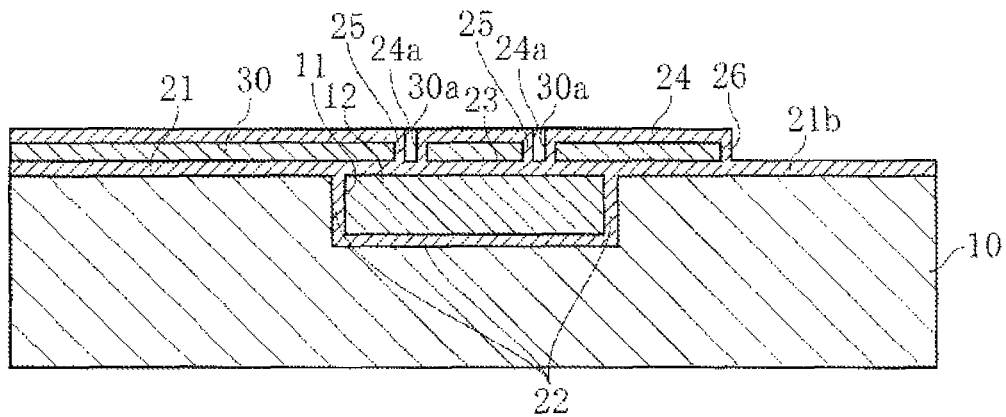


FIG.10





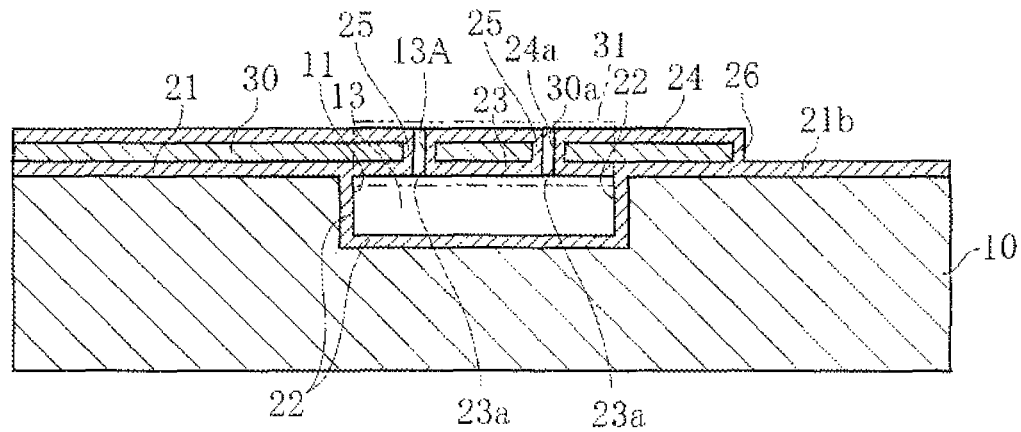




FIG.17

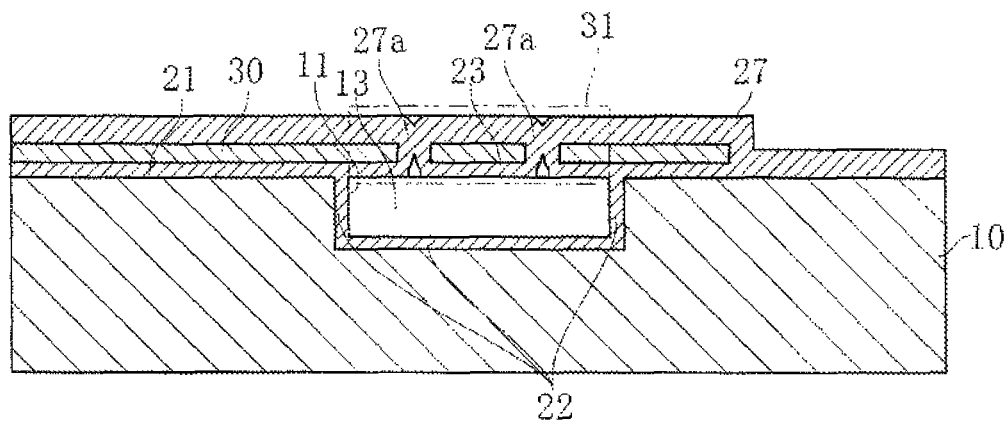
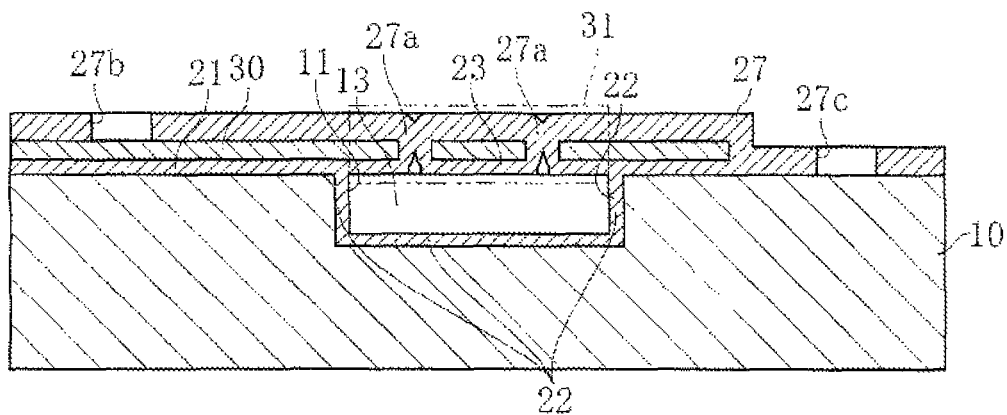


FIG.18



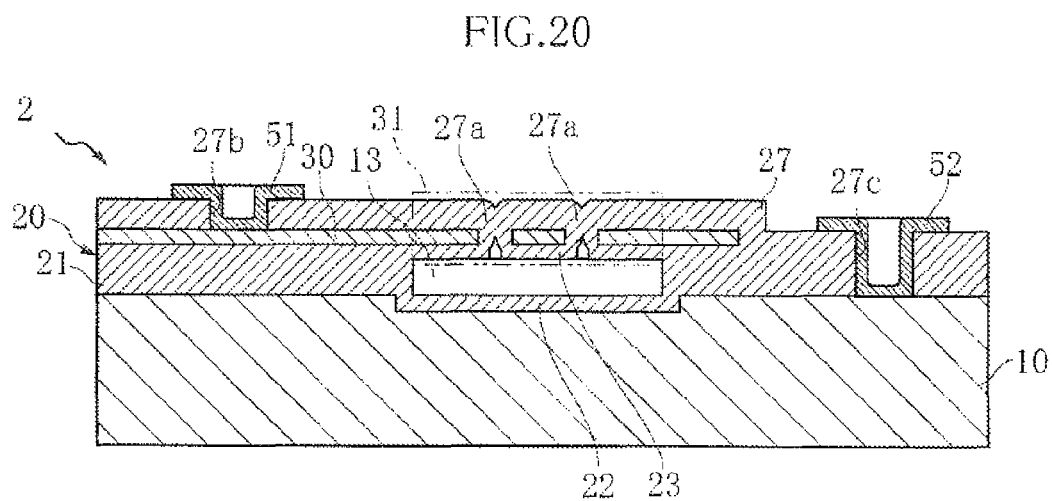
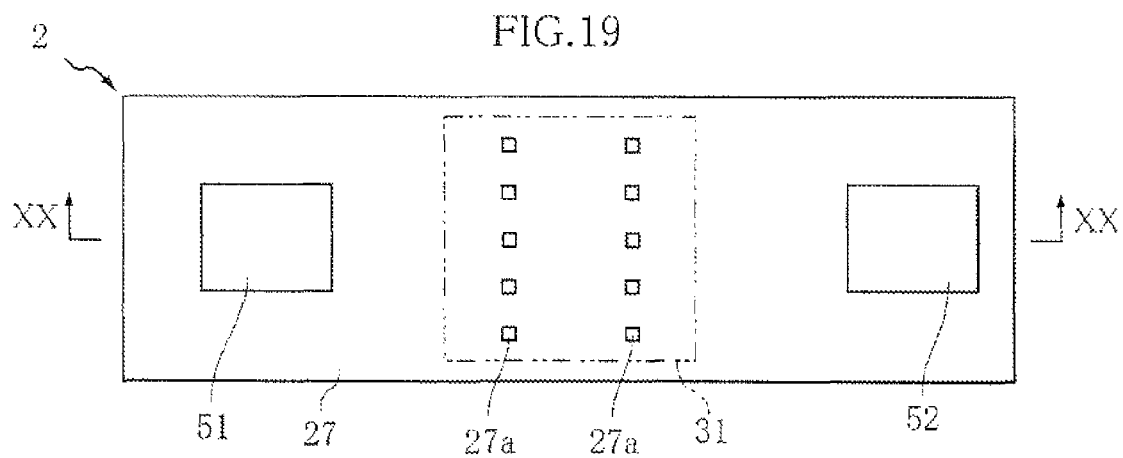


FIG.21

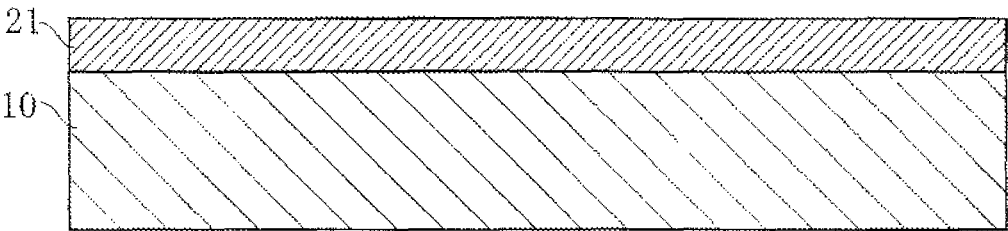


FIG.22

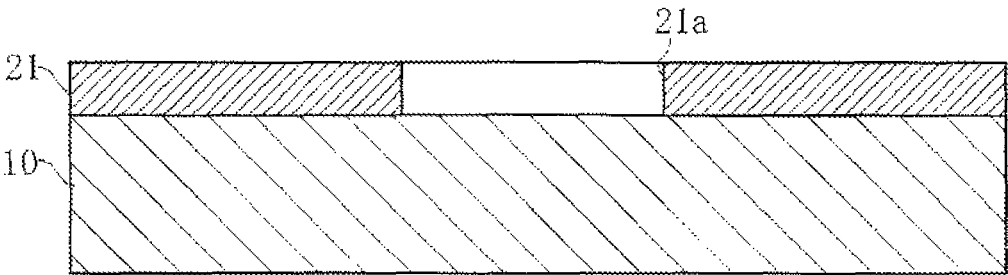


FIG.23

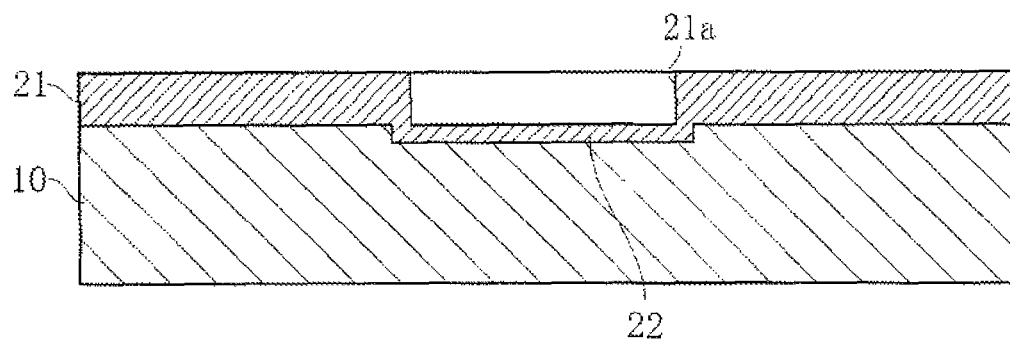


FIG.24

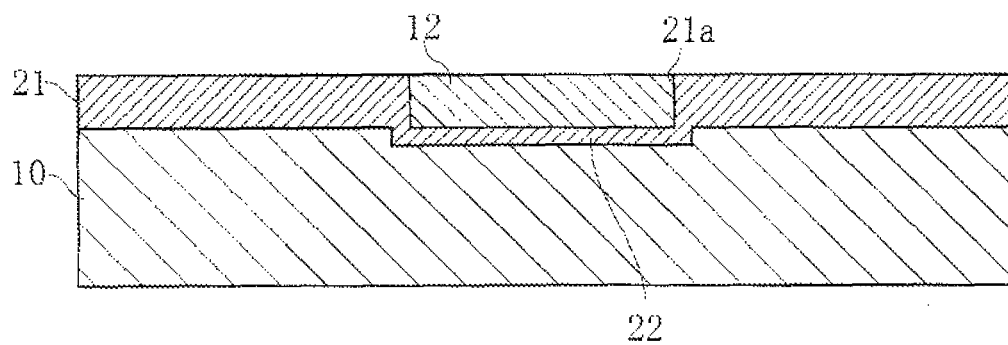


FIG.25

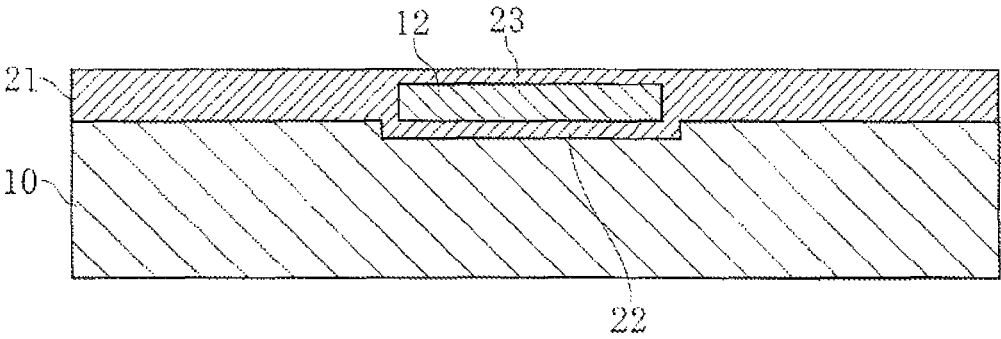


FIG.26

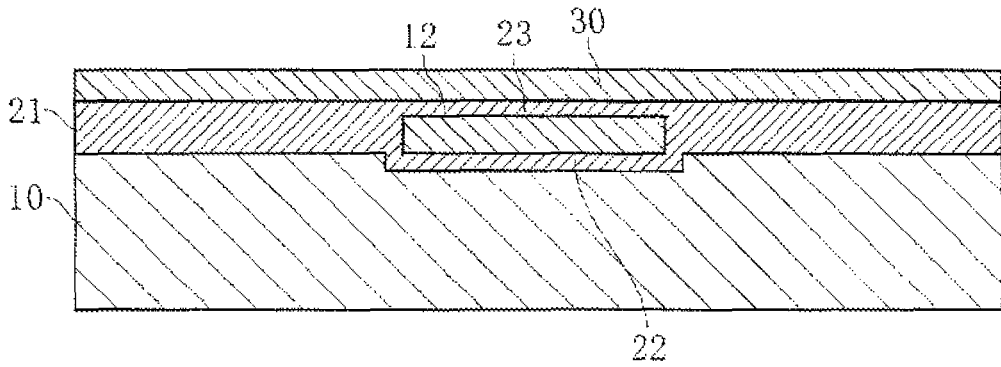


FIG.27

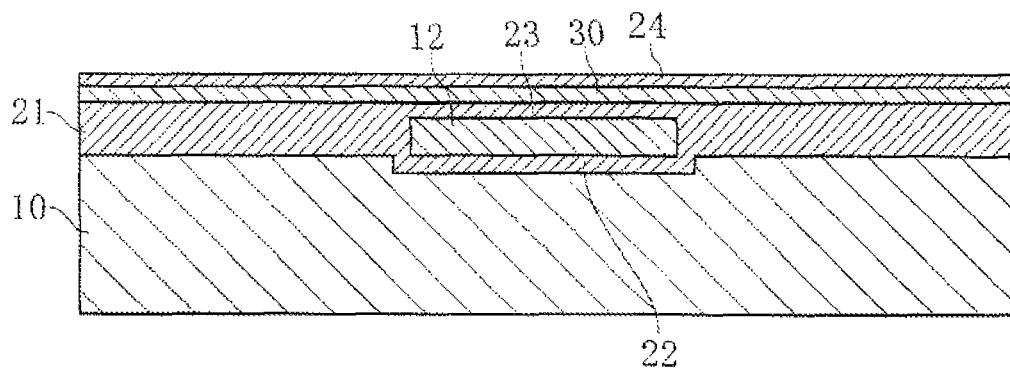


FIG.28

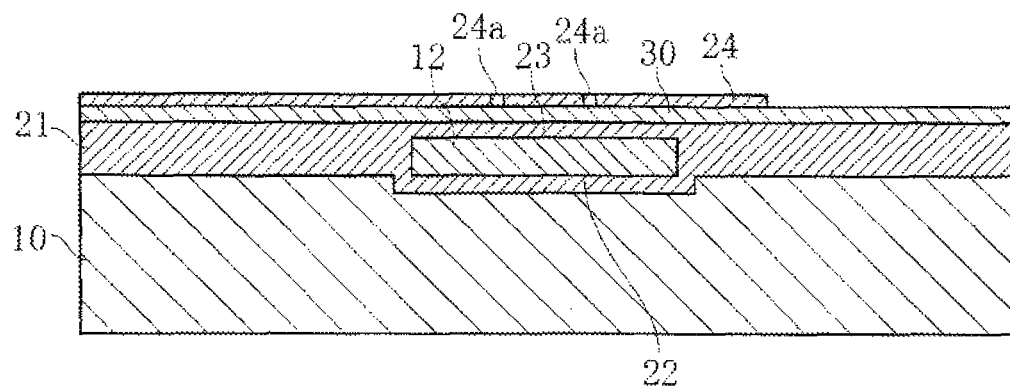


FIG.29

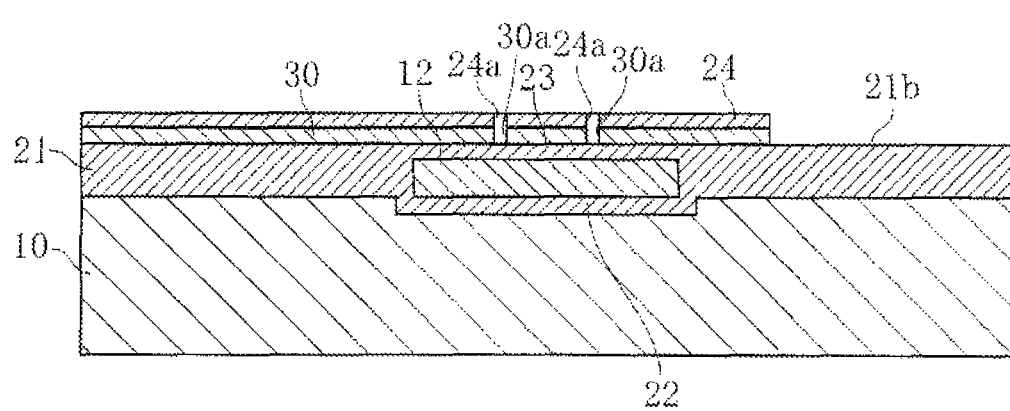


FIG.30

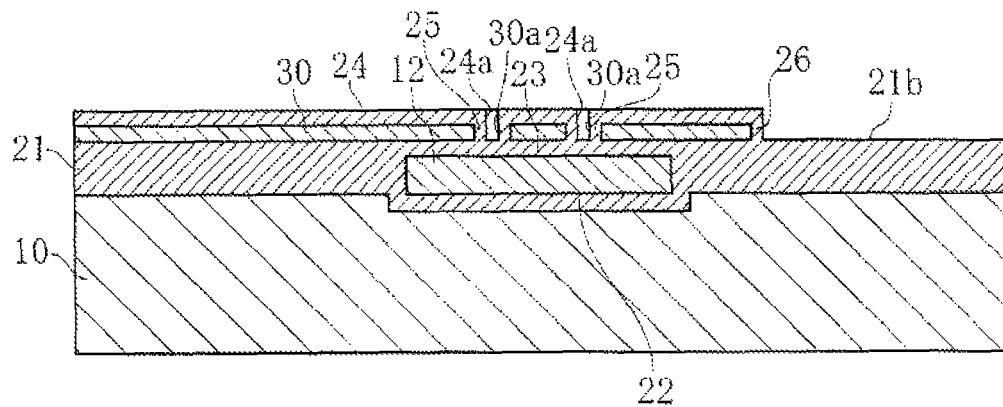


FIG.31

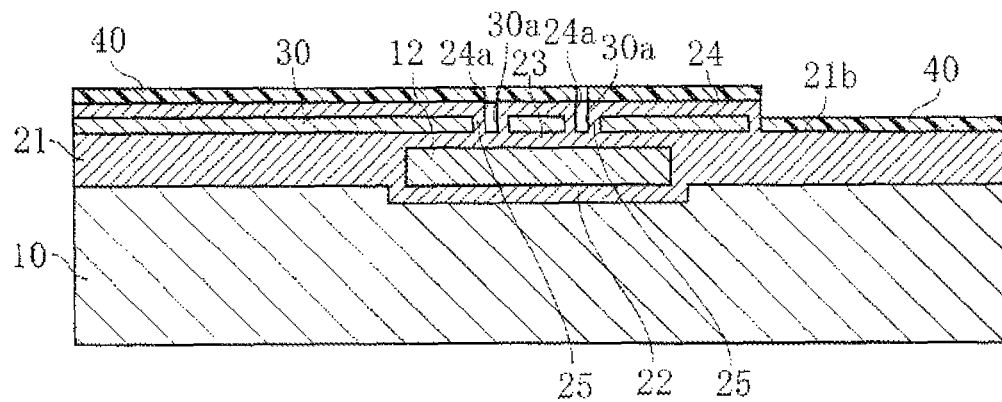
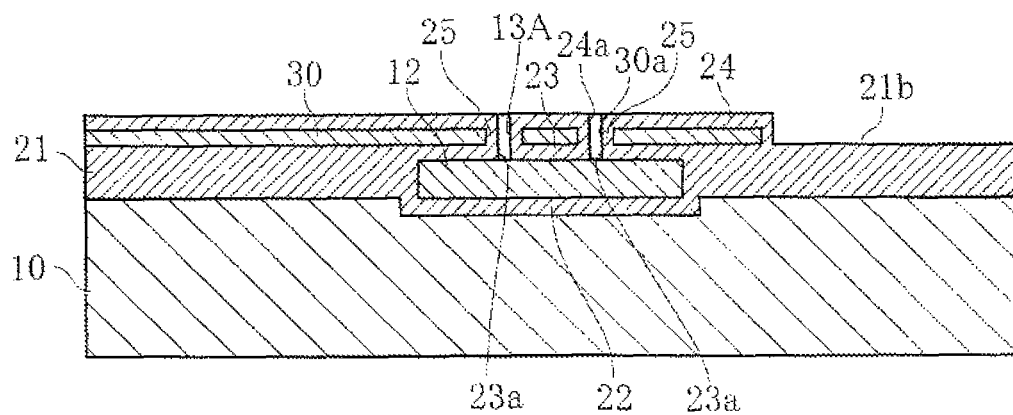


FIG.32



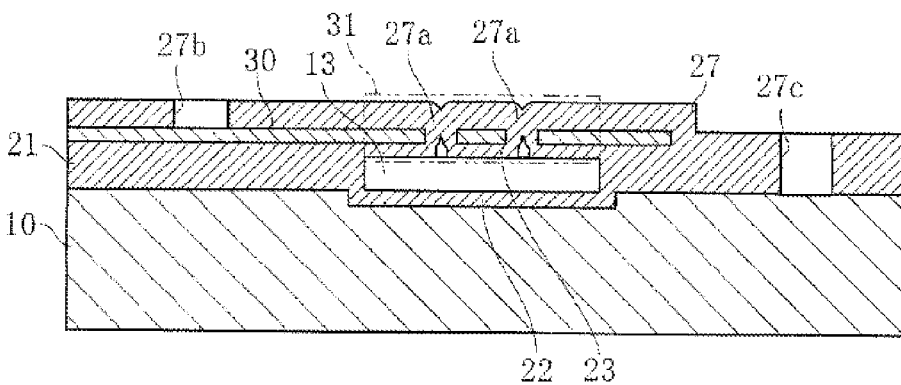




FIG.36

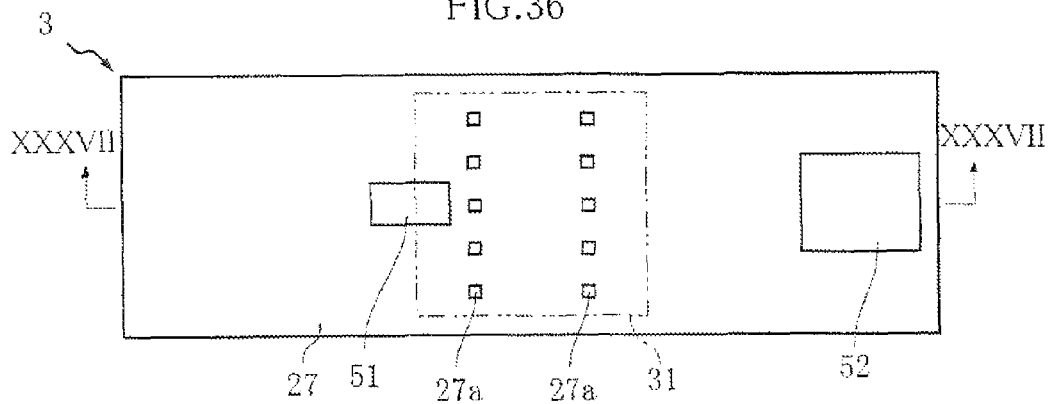


FIG.37

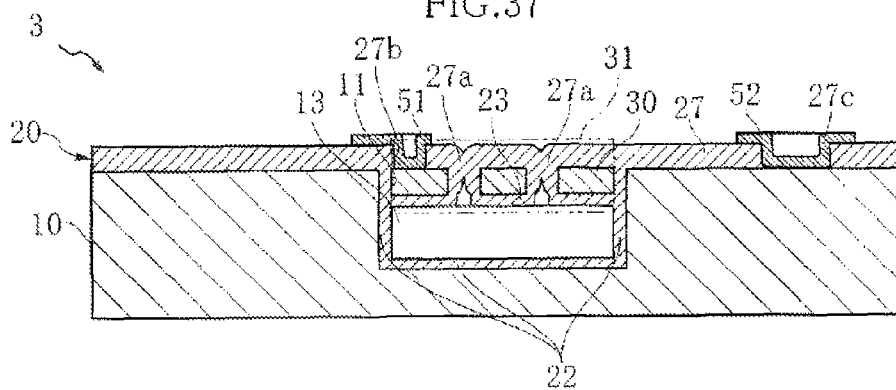


FIG.38

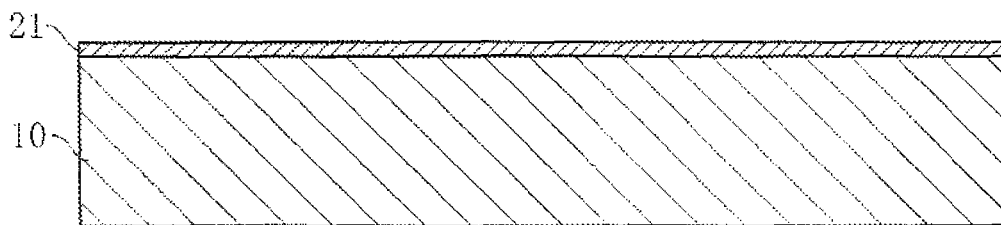


FIG.39

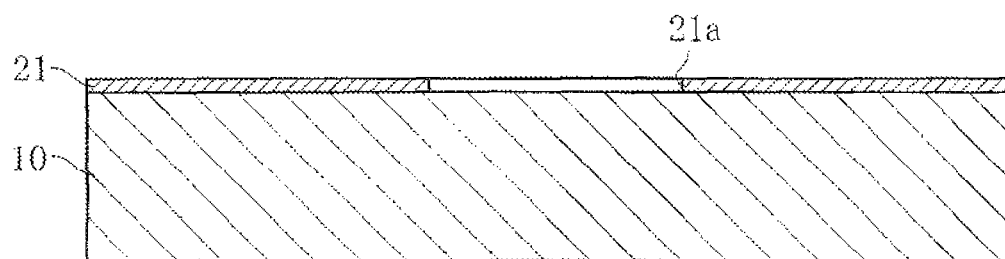


FIG.40

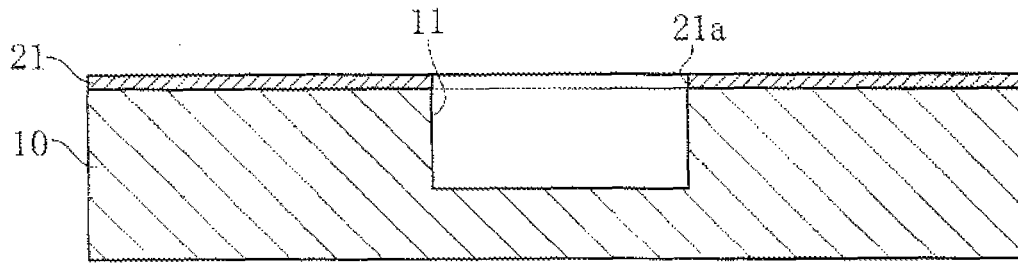


FIG.41

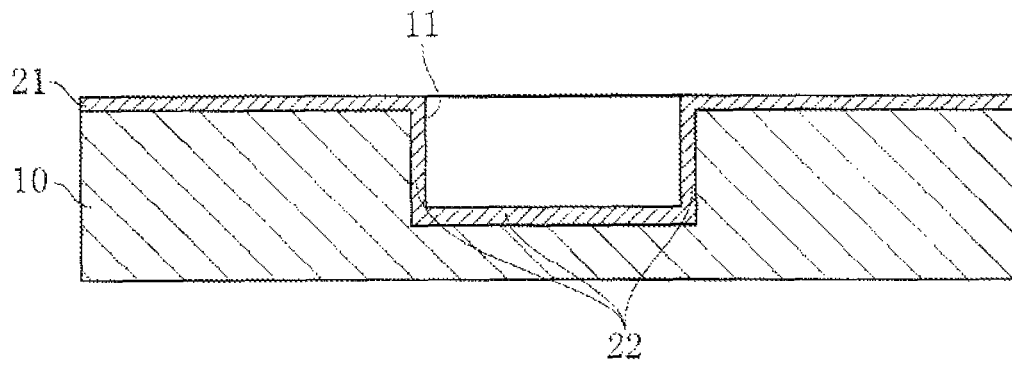


FIG.42

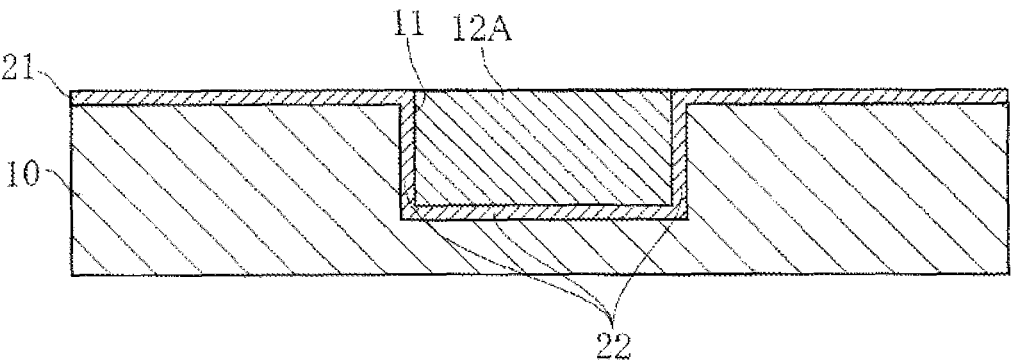
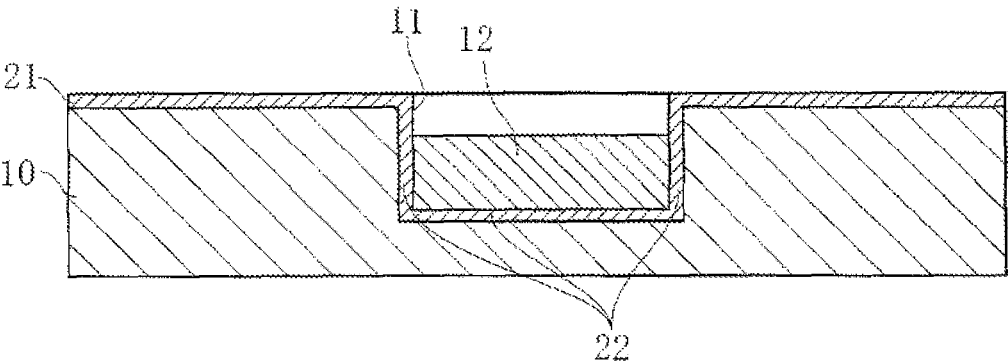


FIG.43



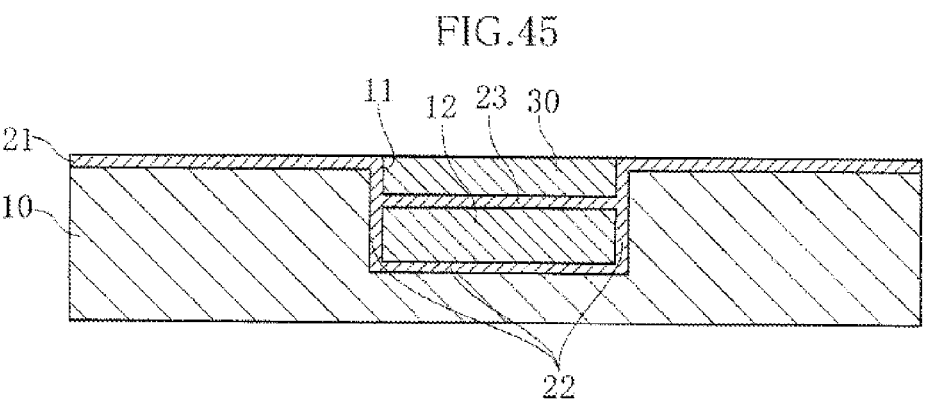
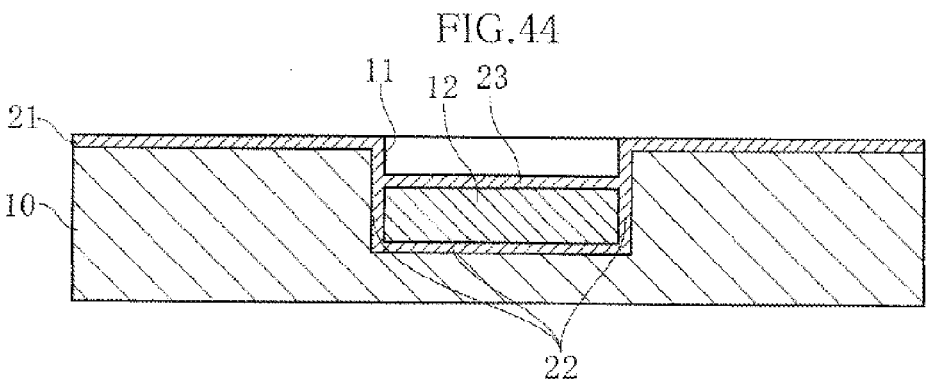


FIG. 46

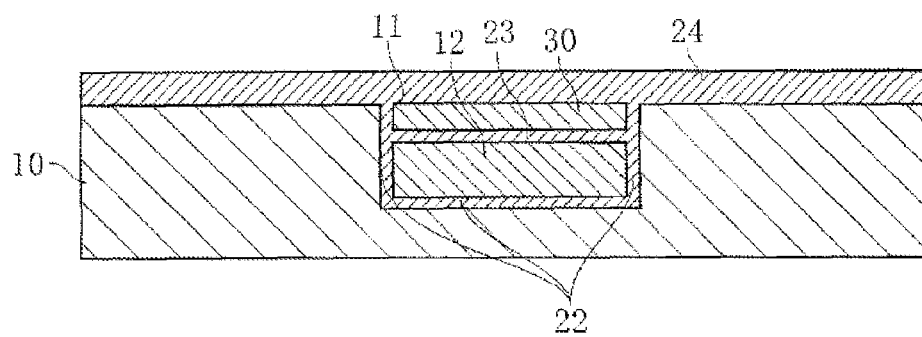


FIG. 47

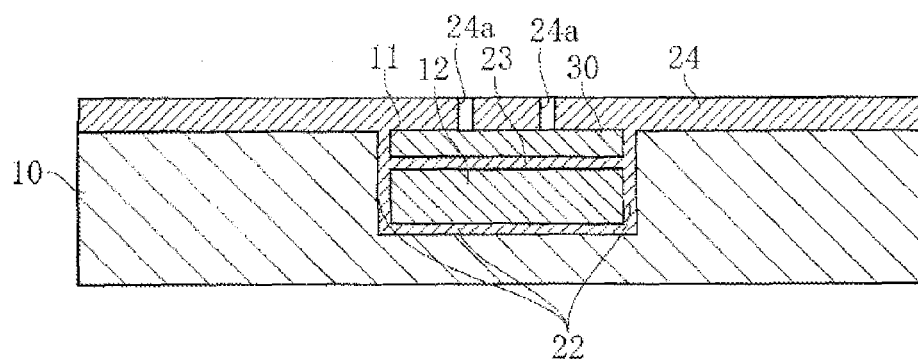


FIG. 48

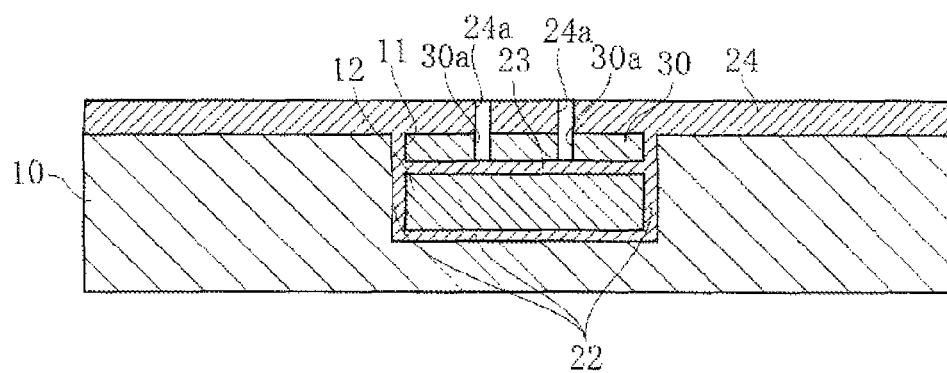


FIG. 49

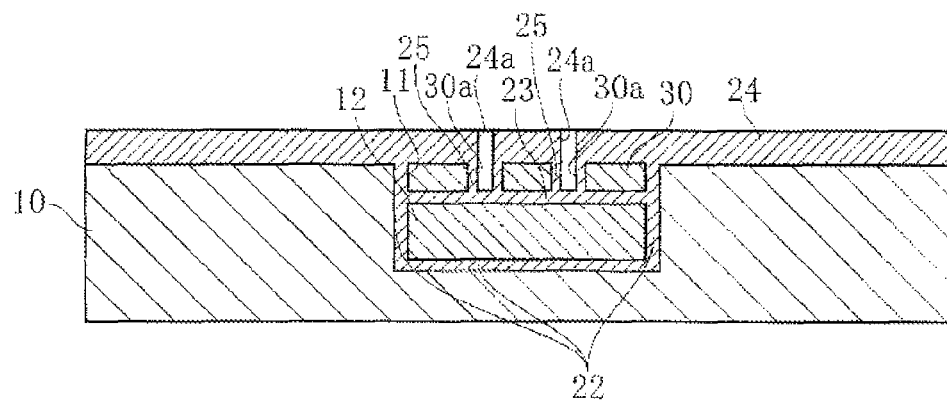


FIG.50

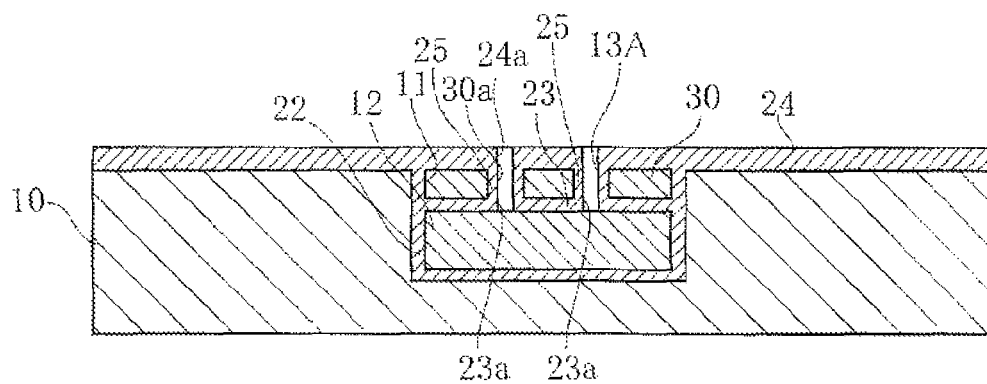


FIG.51

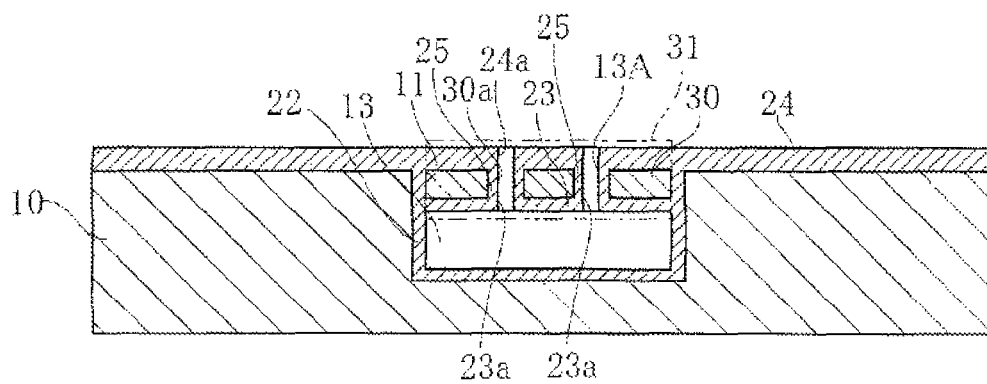




FIG.52

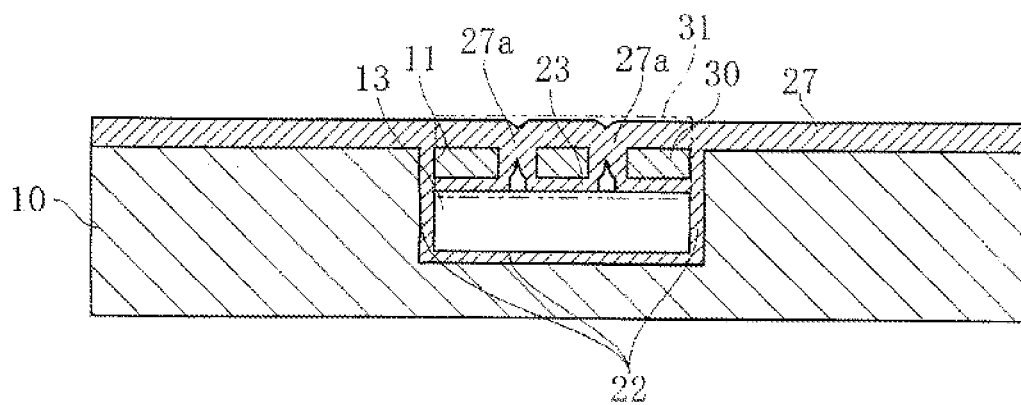


FIG.53

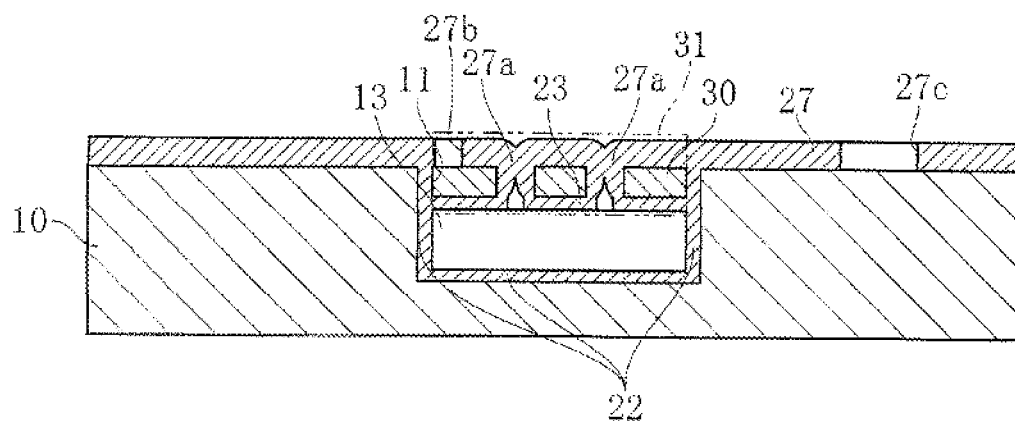


FIG.54

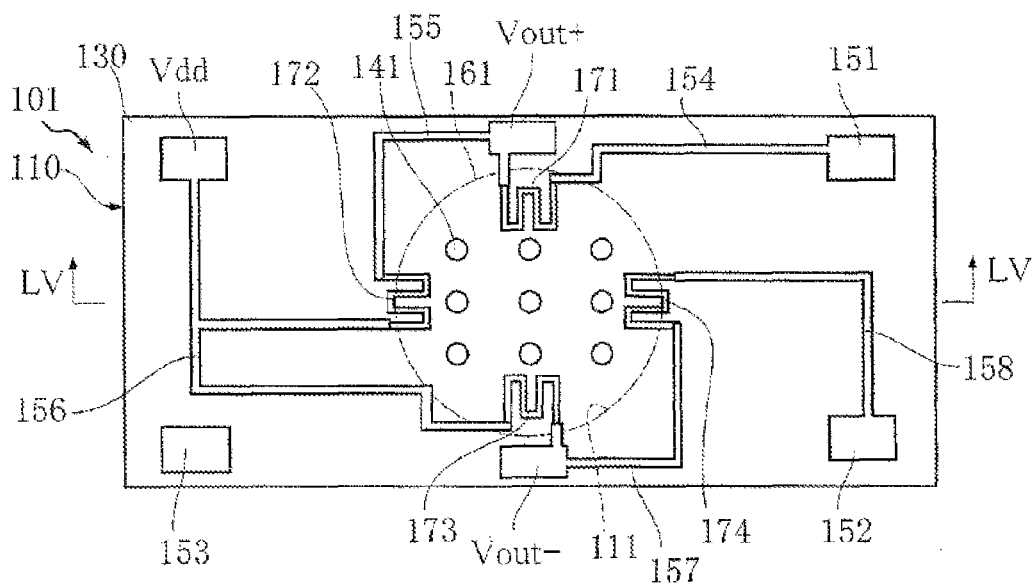


FIG.55

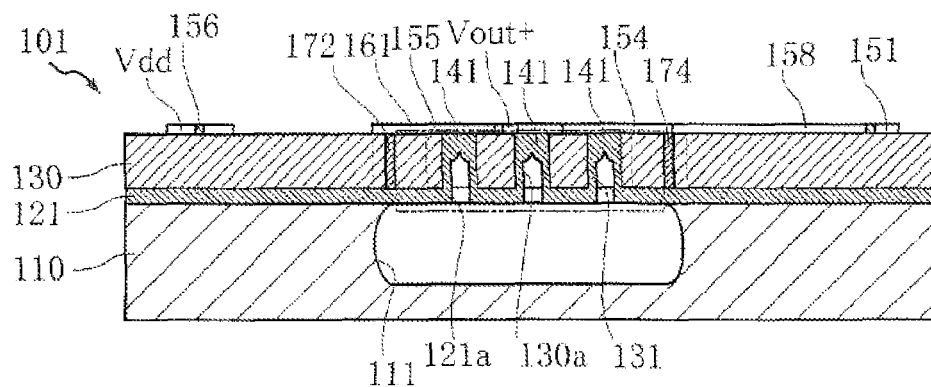


FIG.56

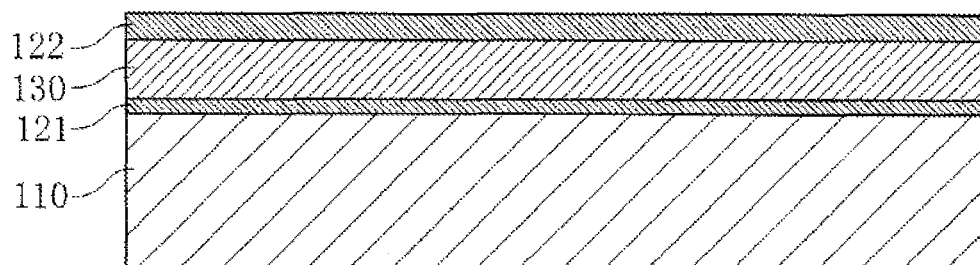


FIG.57

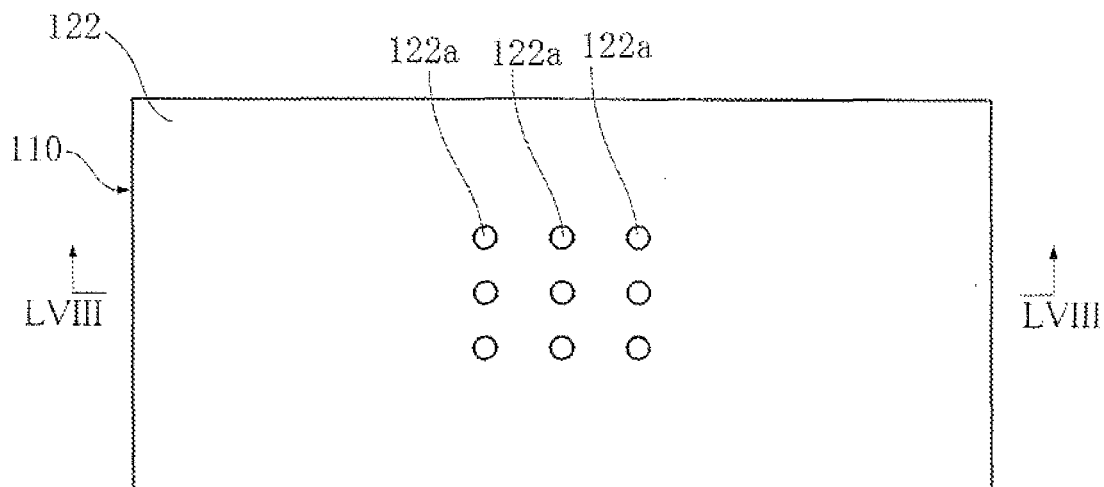


FIG.58

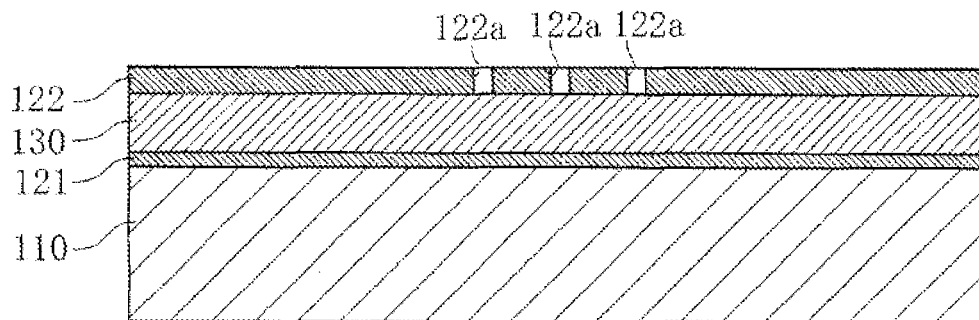


FIG.59

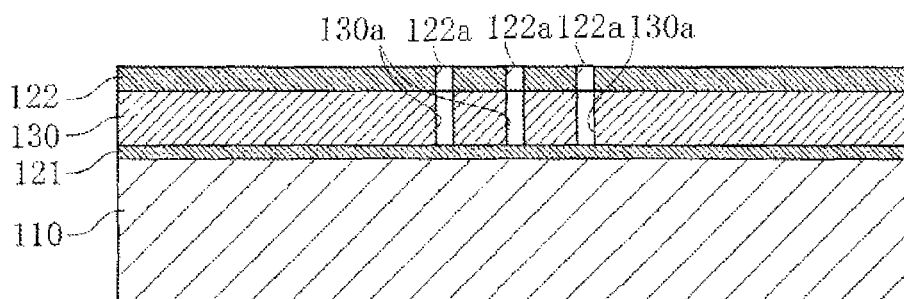


FIG.60

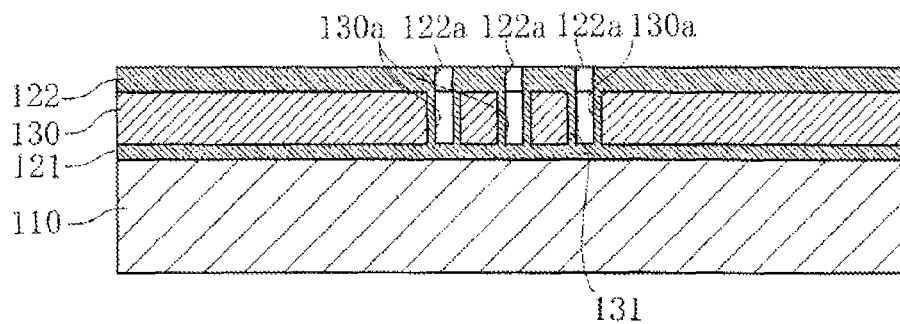


FIG.61

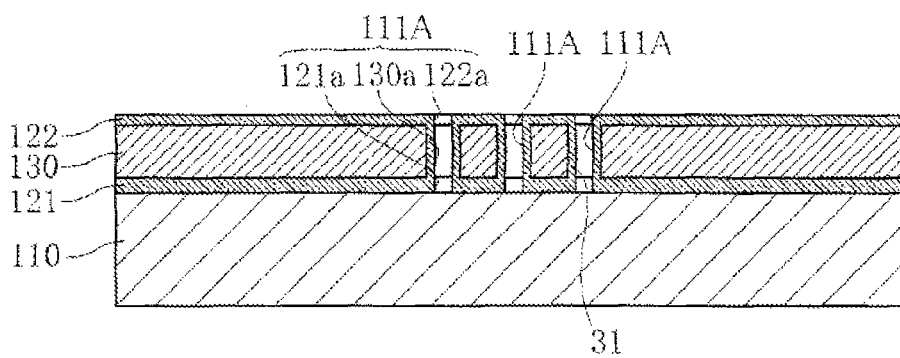


FIG.62

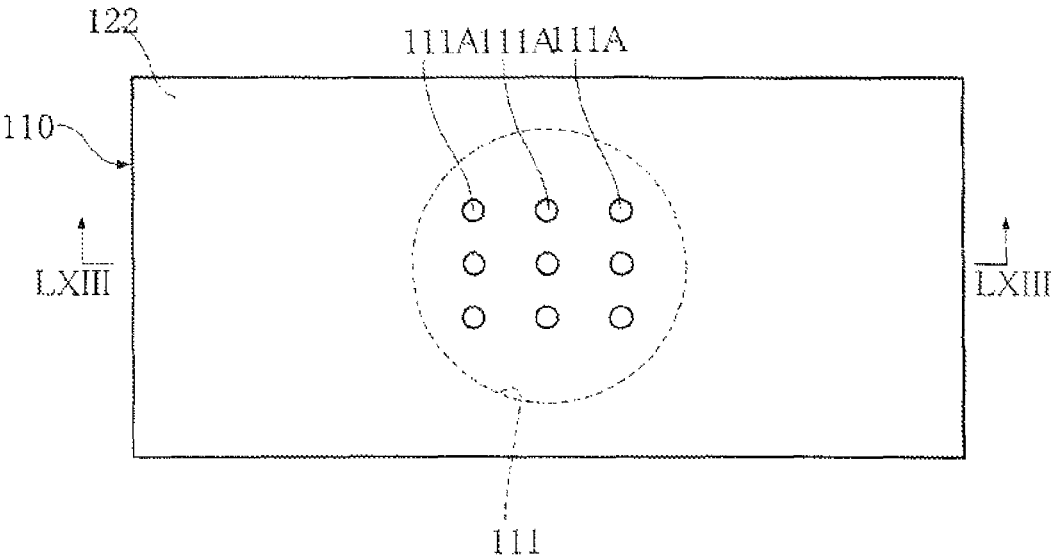


FIG. 63

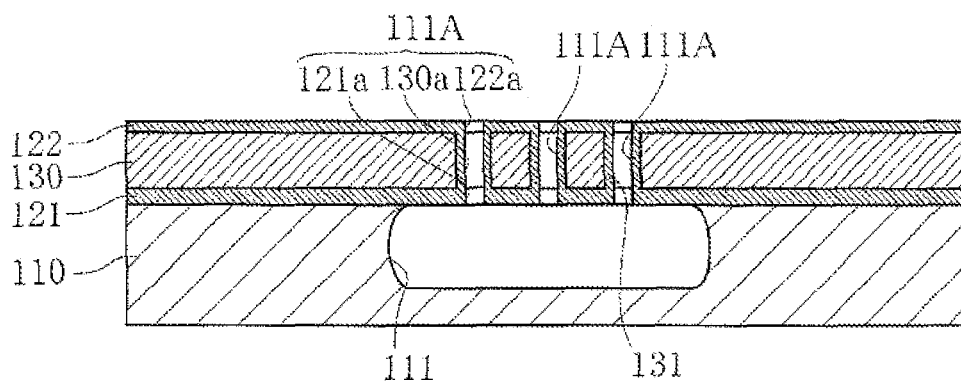


FIG. 64

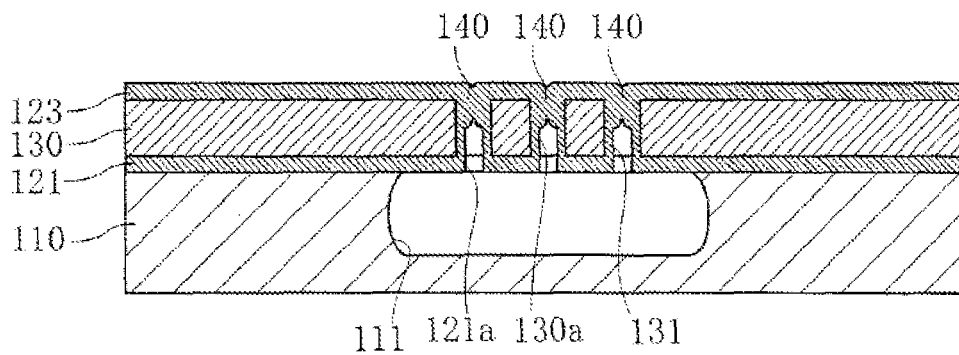


FIG.65

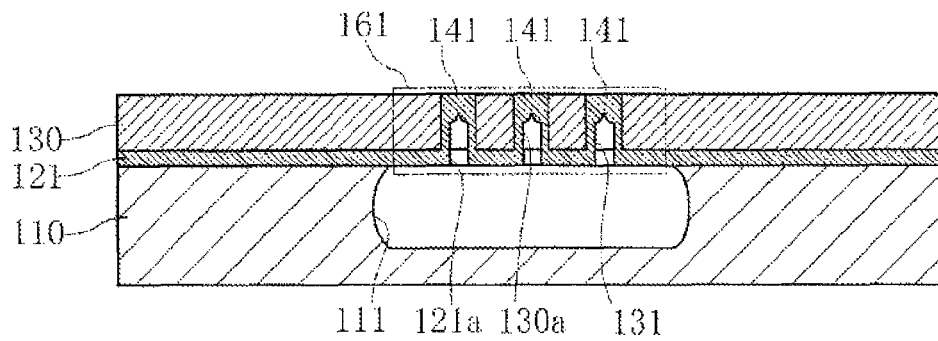


FIG.66

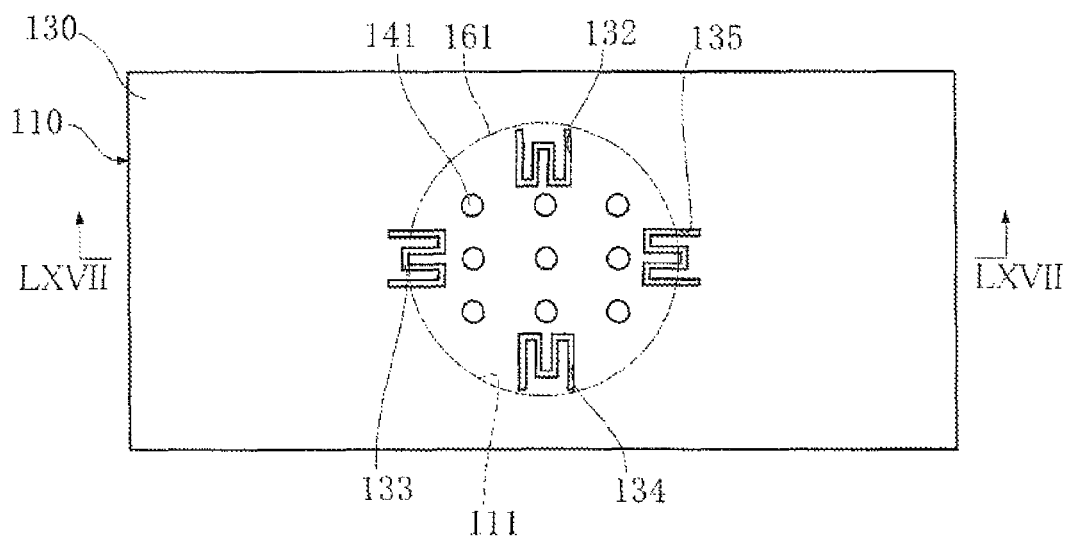


FIG.67

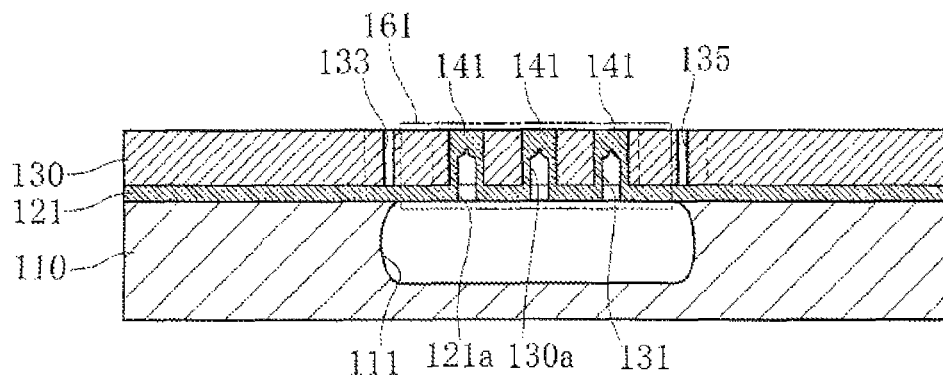


FIG.68

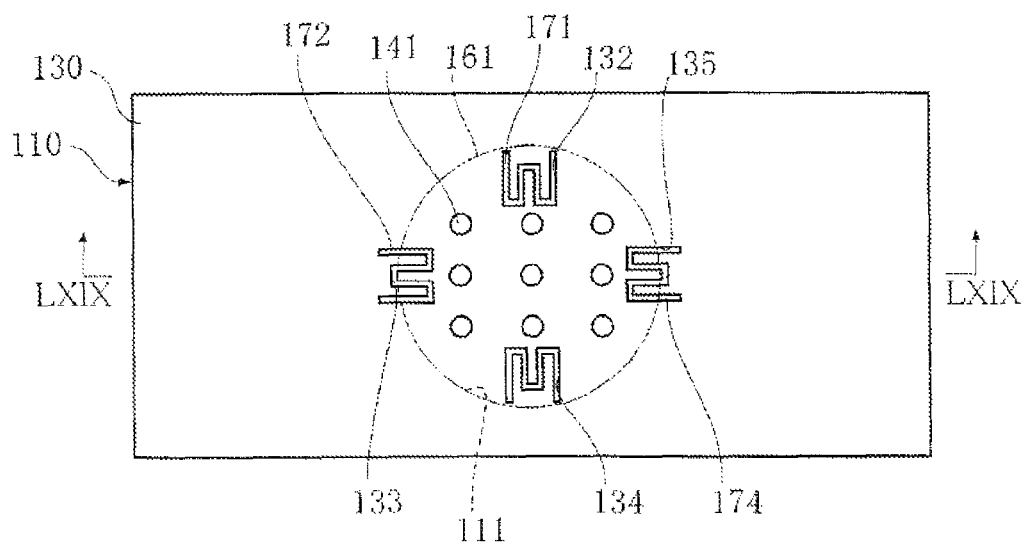


FIG.69

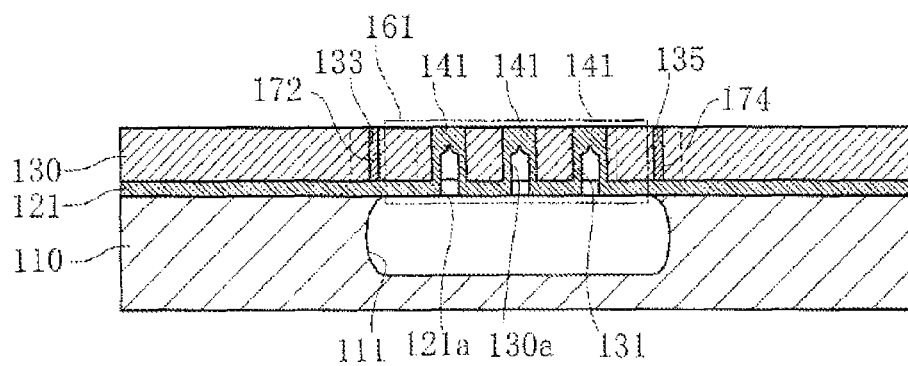




FIG. 70

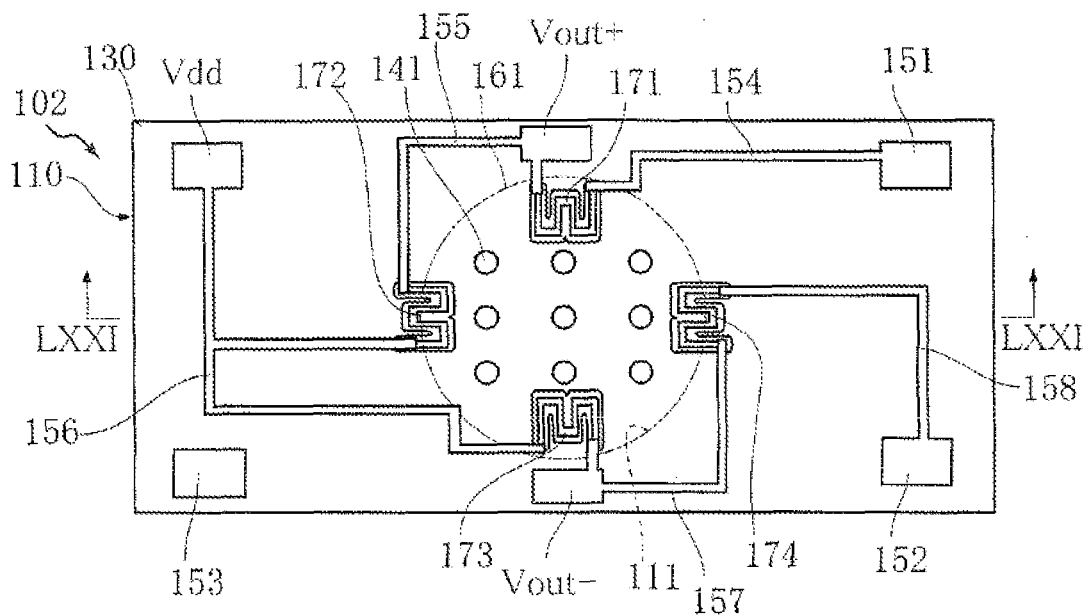


FIG. 71

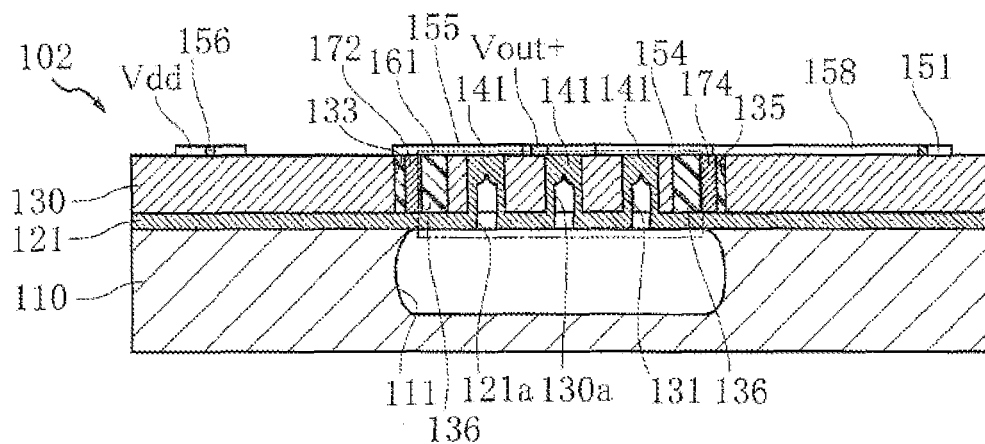


FIG. 72

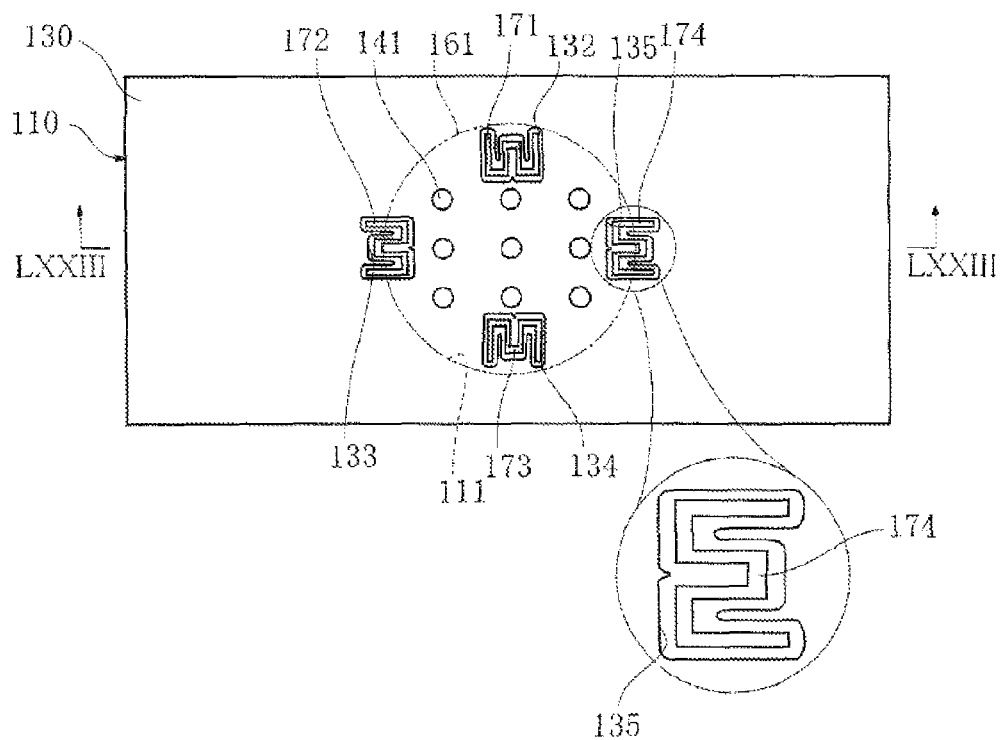


FIG. 73

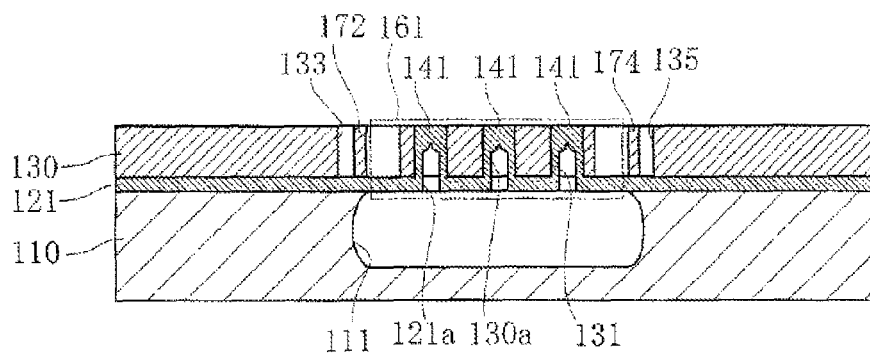


FIG.74

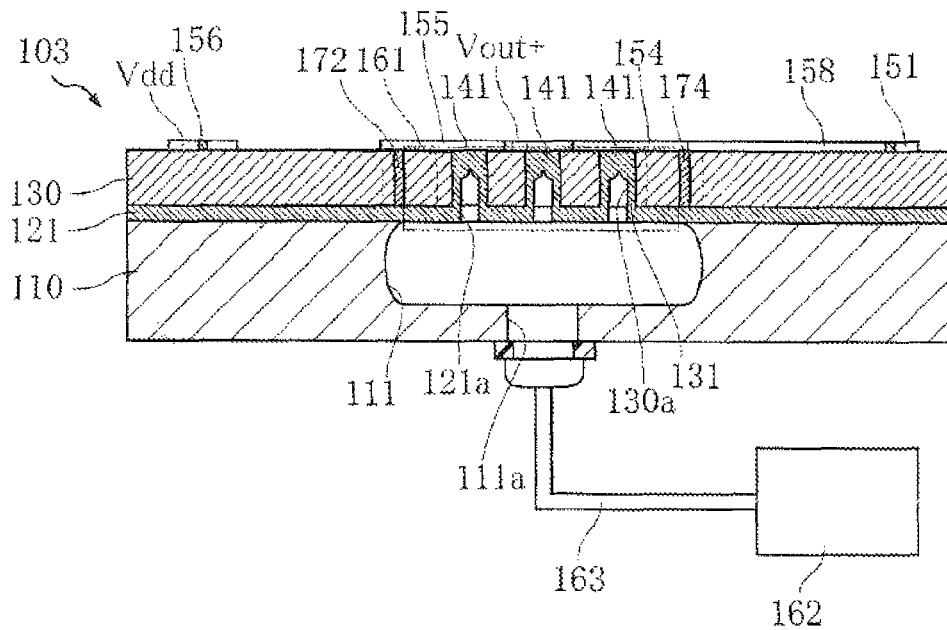


FIG.75

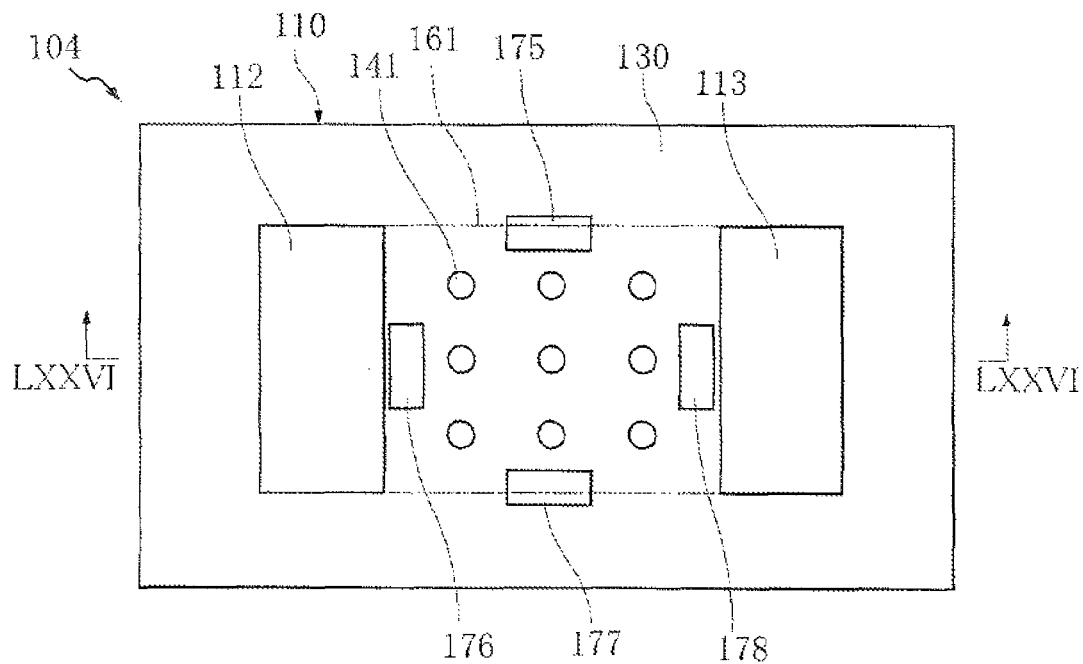


FIG.76

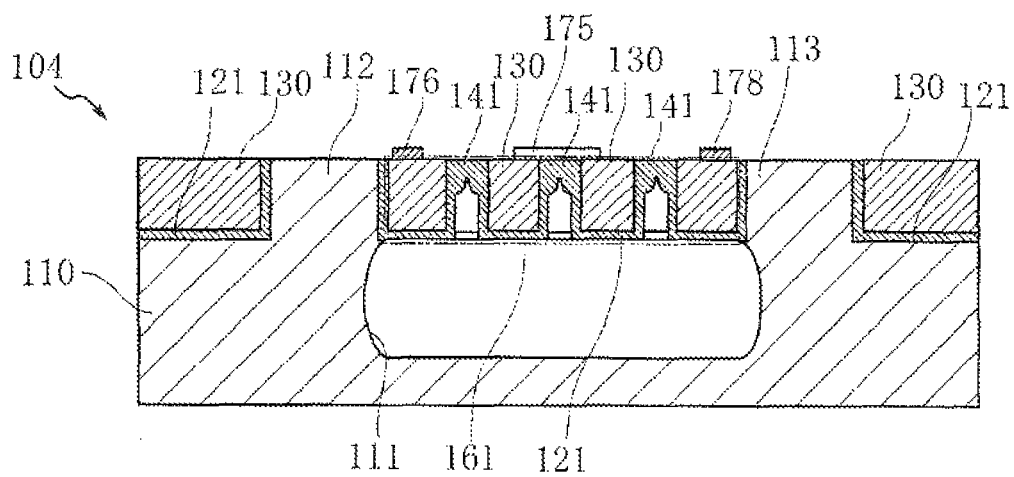


FIG.77

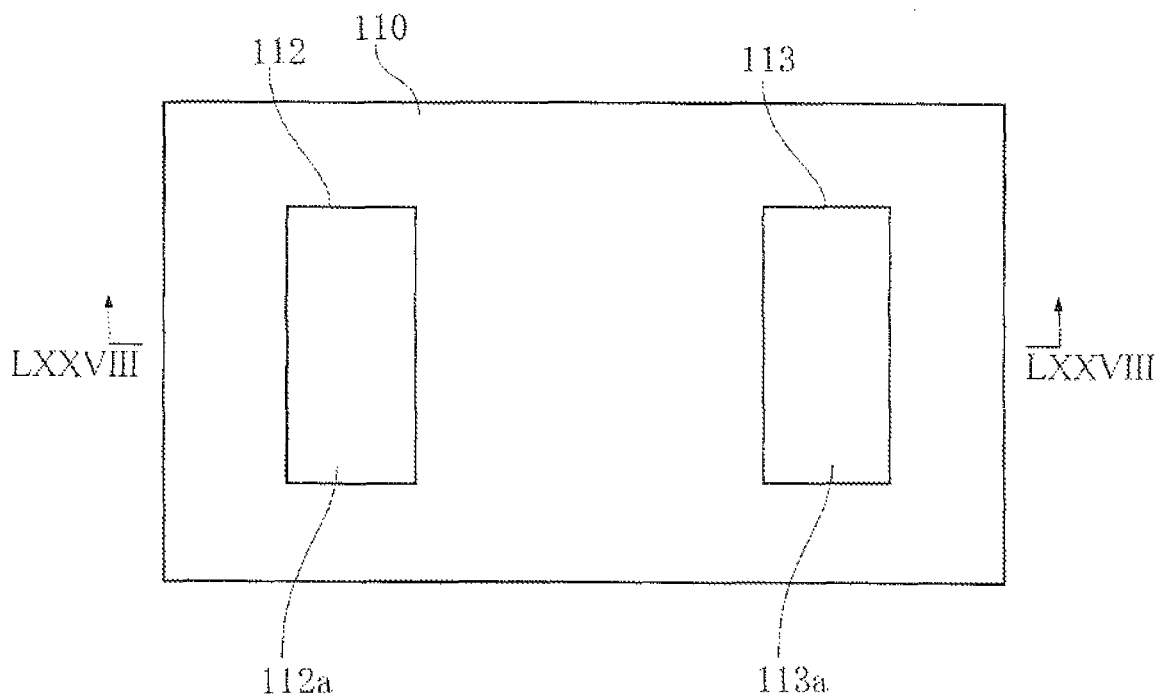


FIG.78

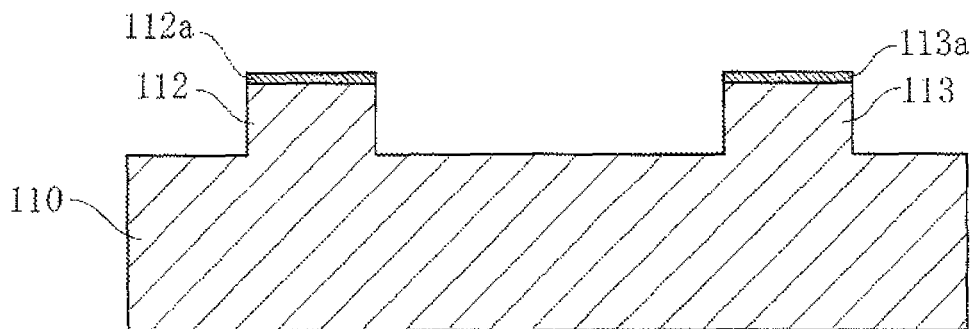


FIG.79

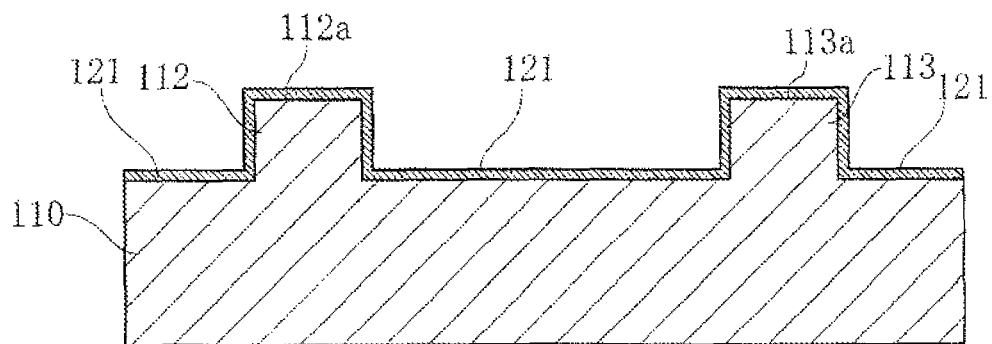


FIG.80

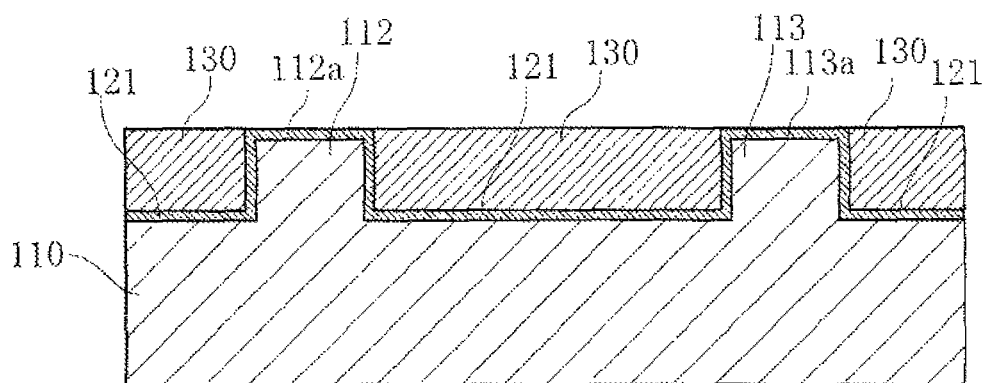


FIG. 81

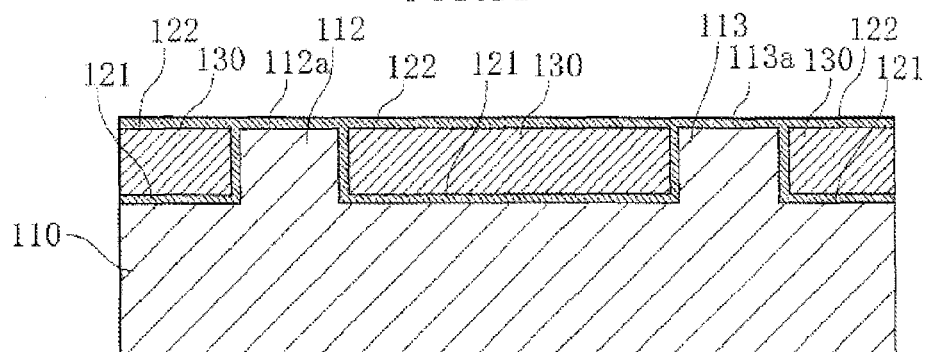


FIG.82

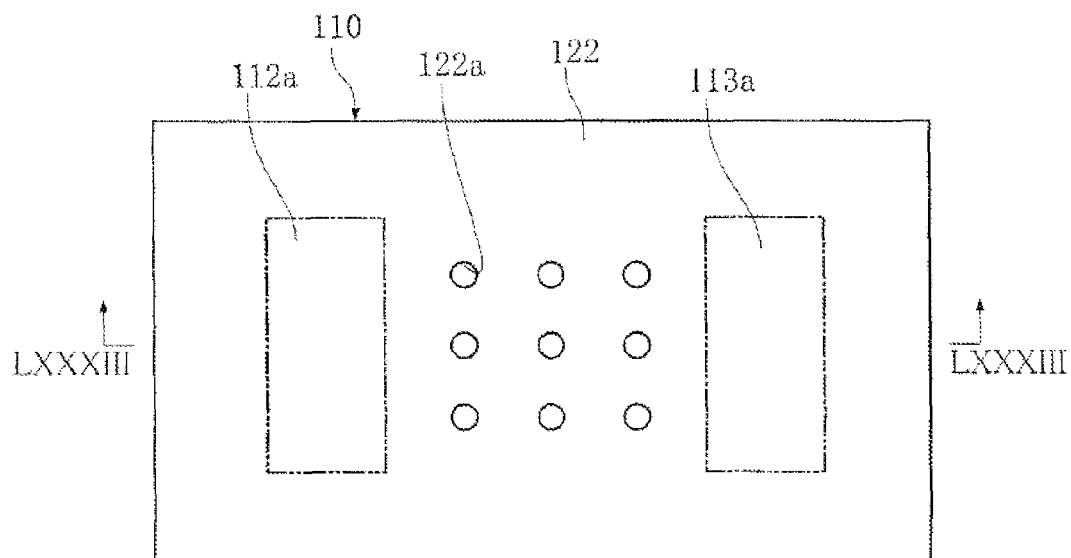


FIG. 83

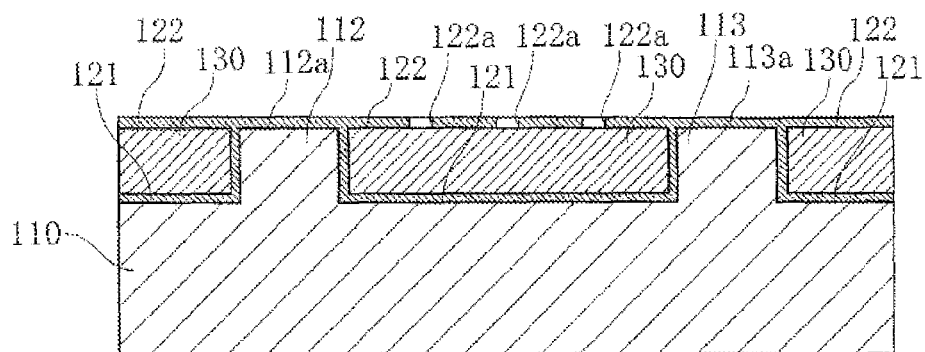


FIG.84

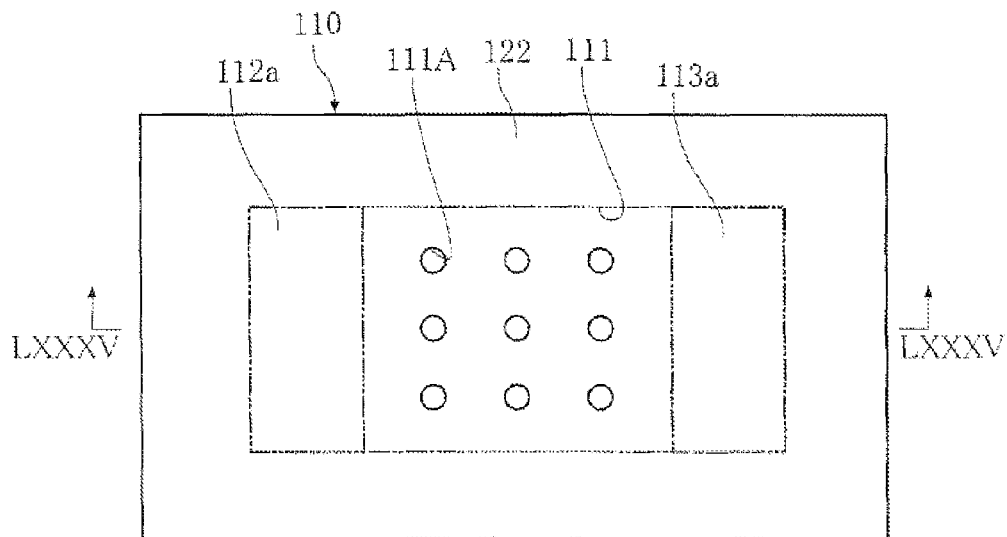
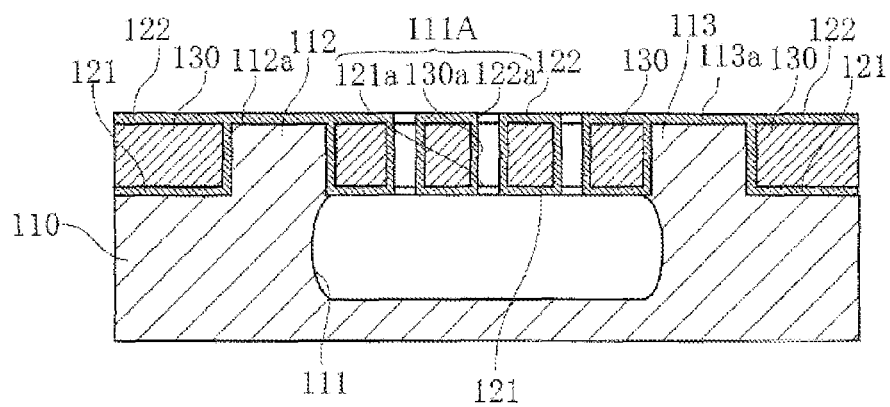


FIG.85



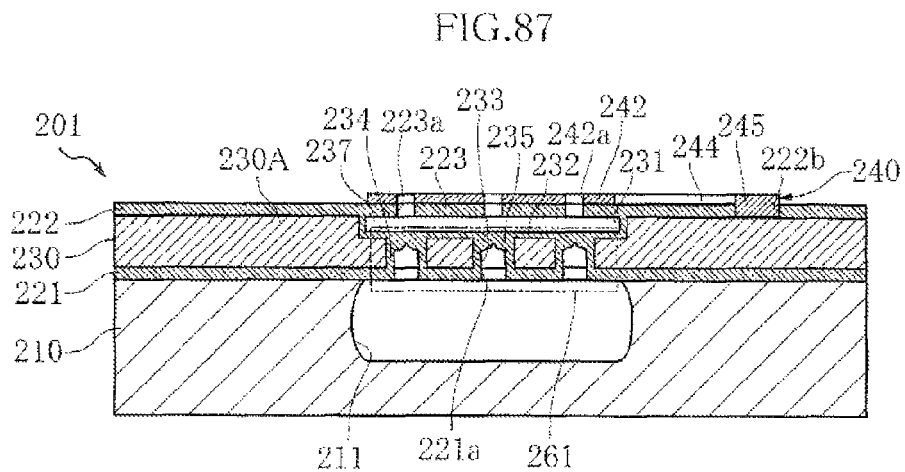
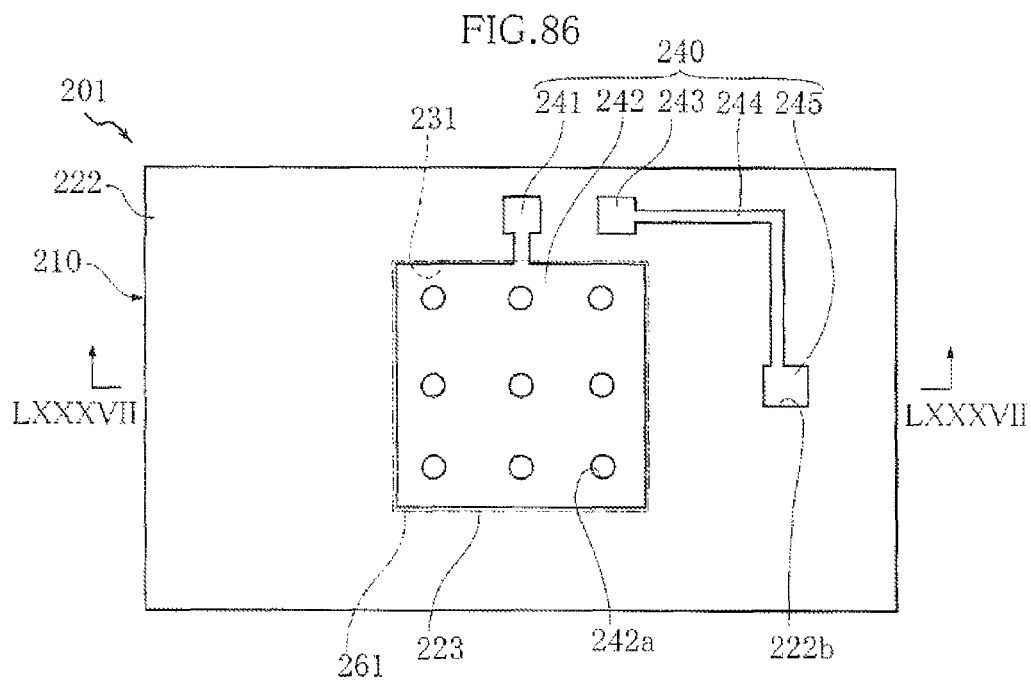




FIG.88

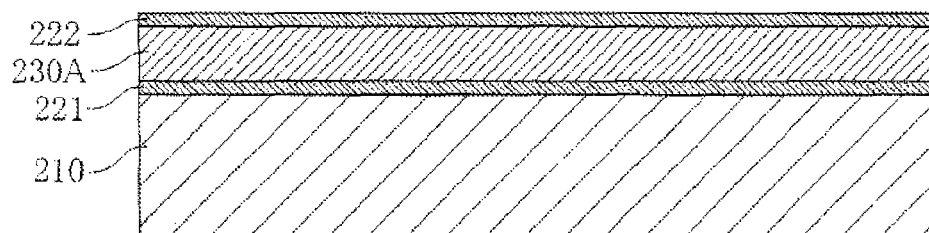


FIG.89

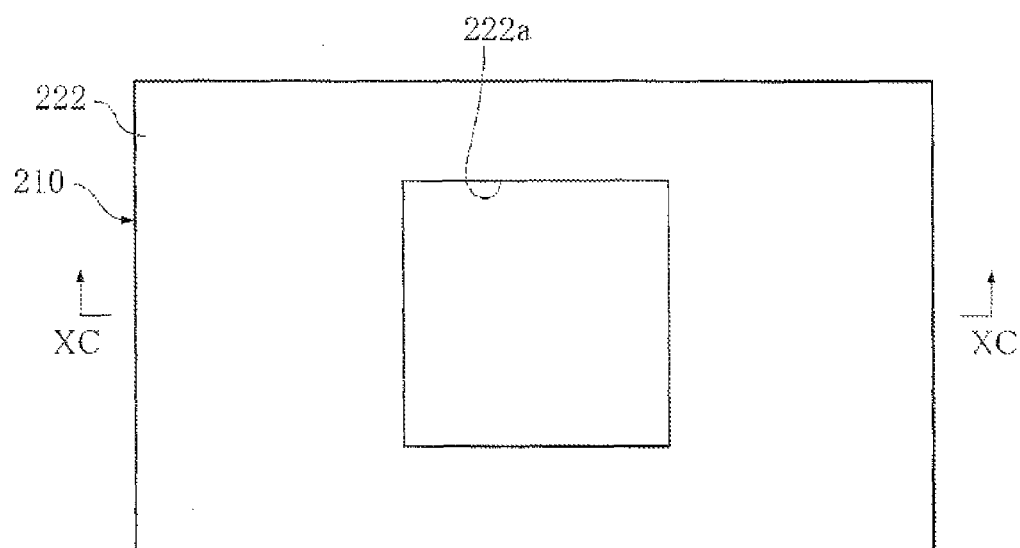


FIG.90

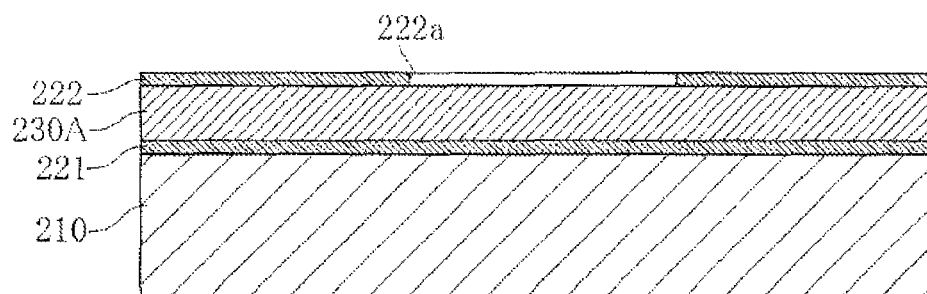


FIG.91

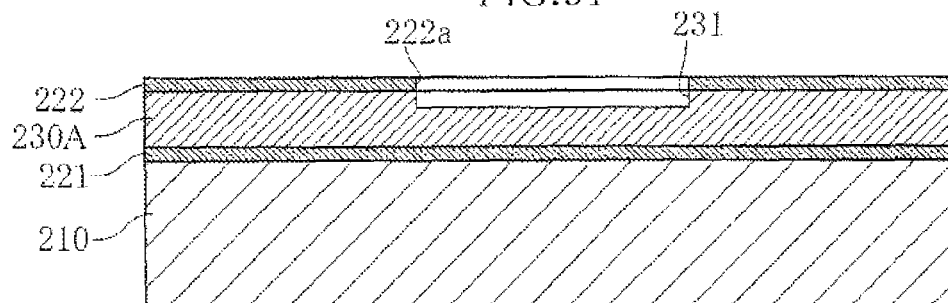


FIG.92

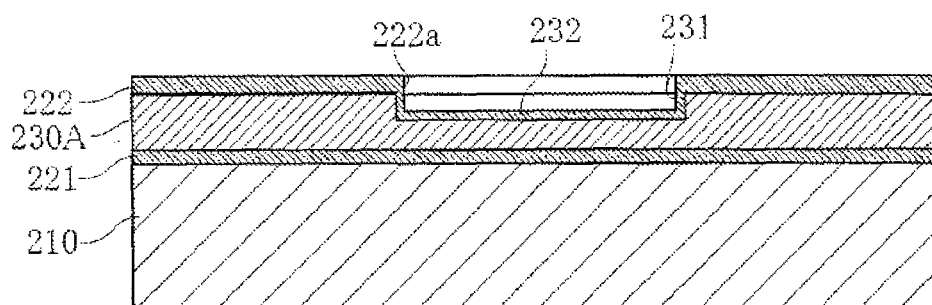


FIG.93

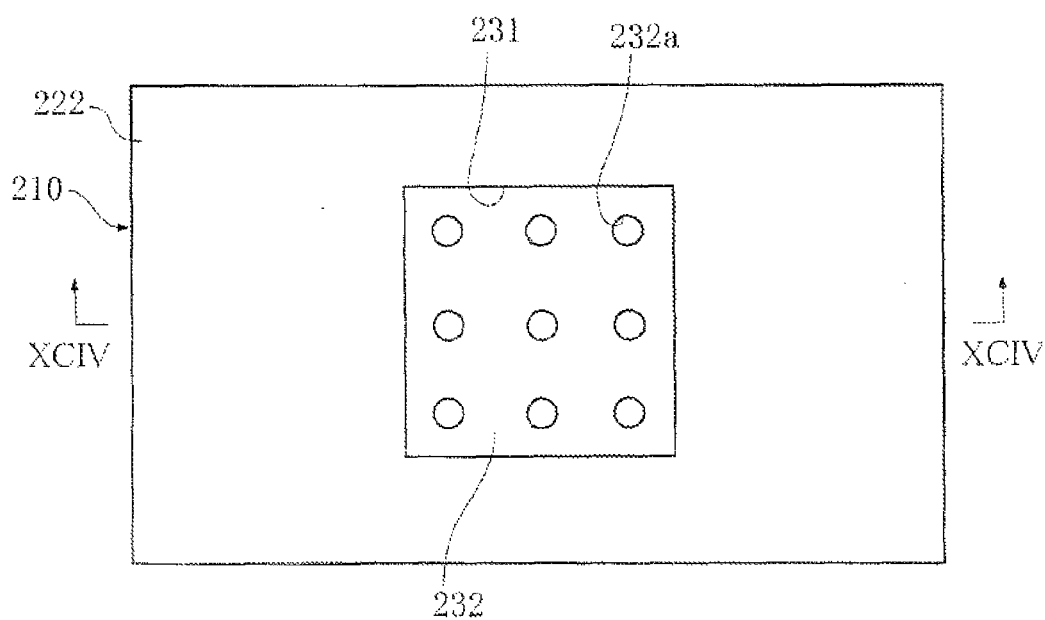


FIG.94

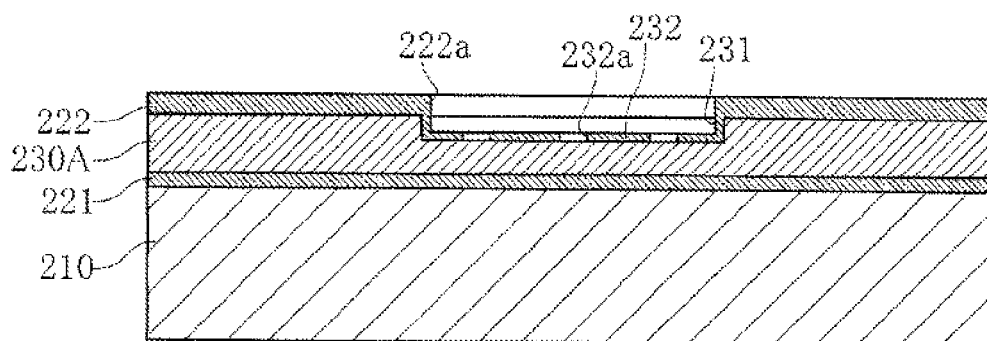


FIG.95

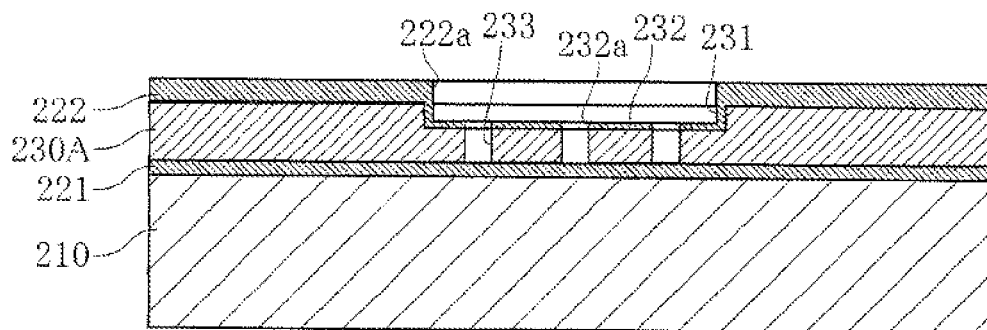


FIG.96

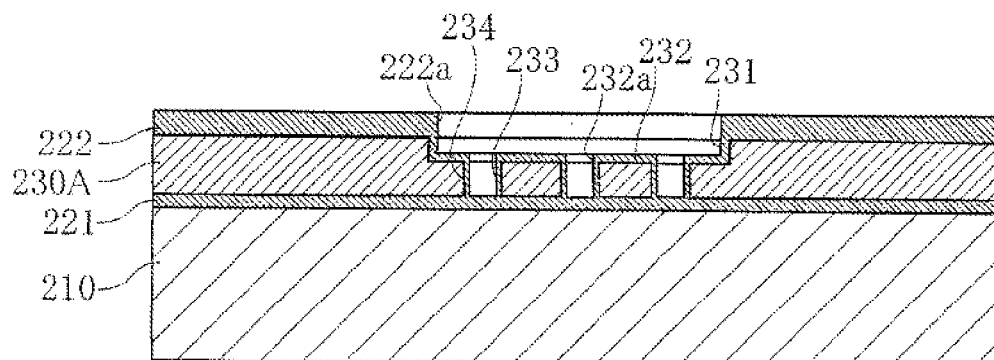


FIG.97

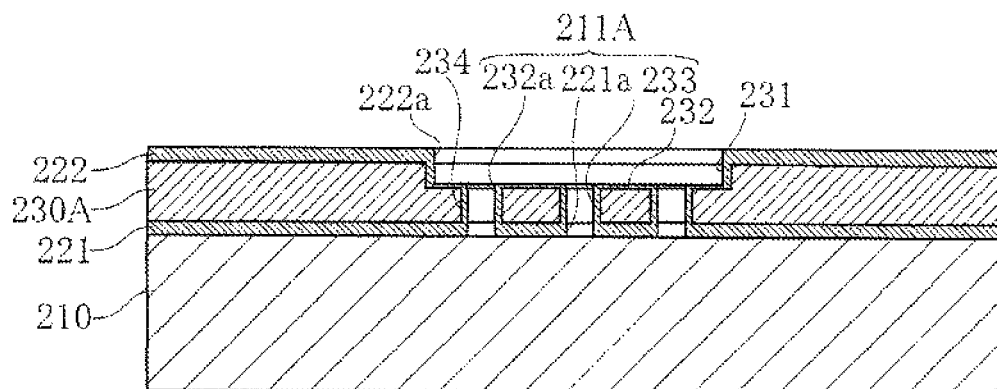
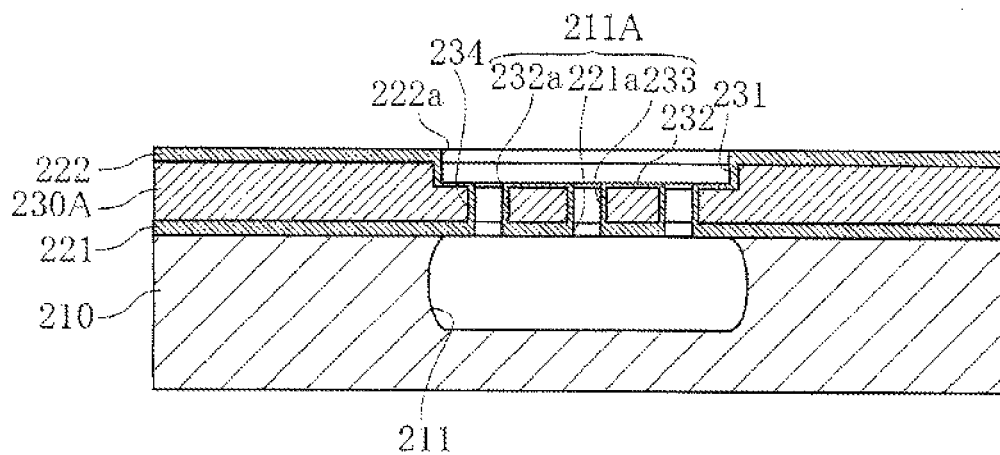
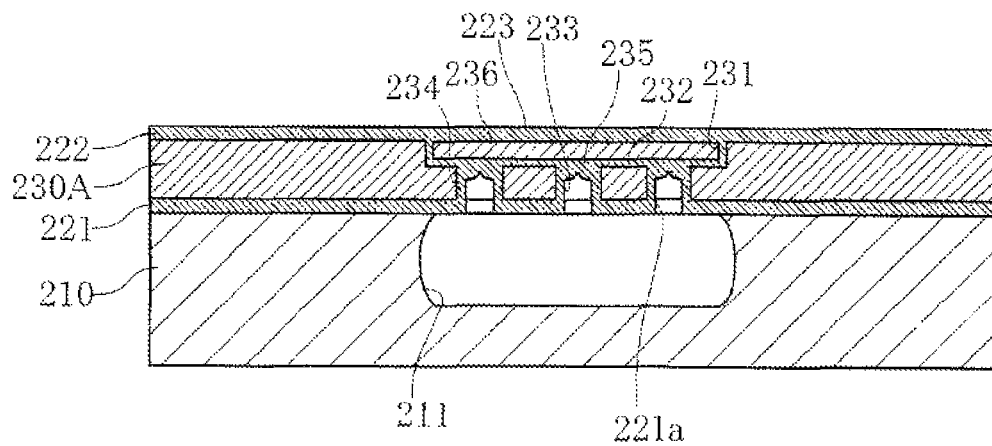


FIG.98





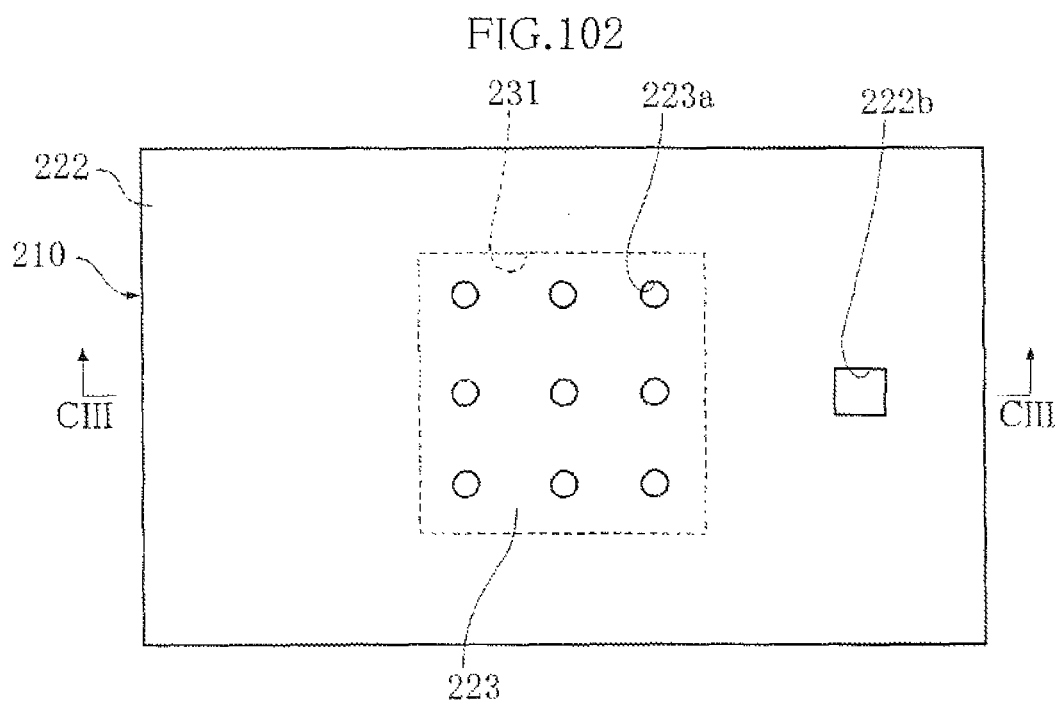


FIG. 103

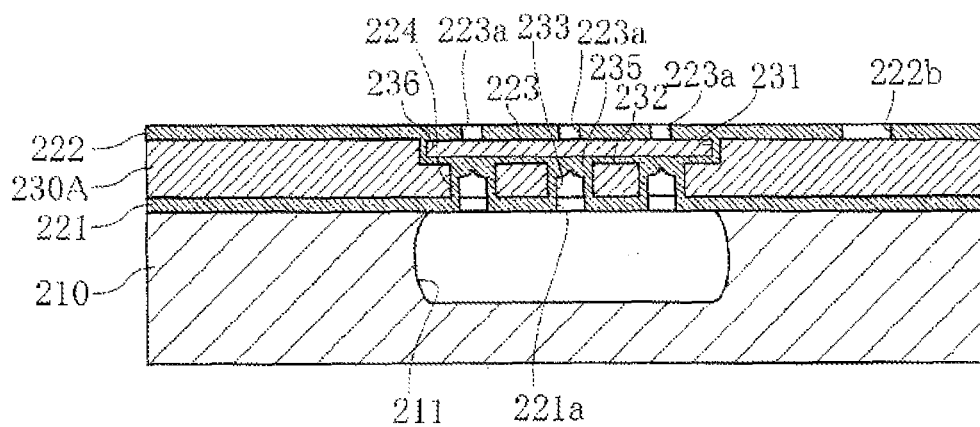


FIG. 104

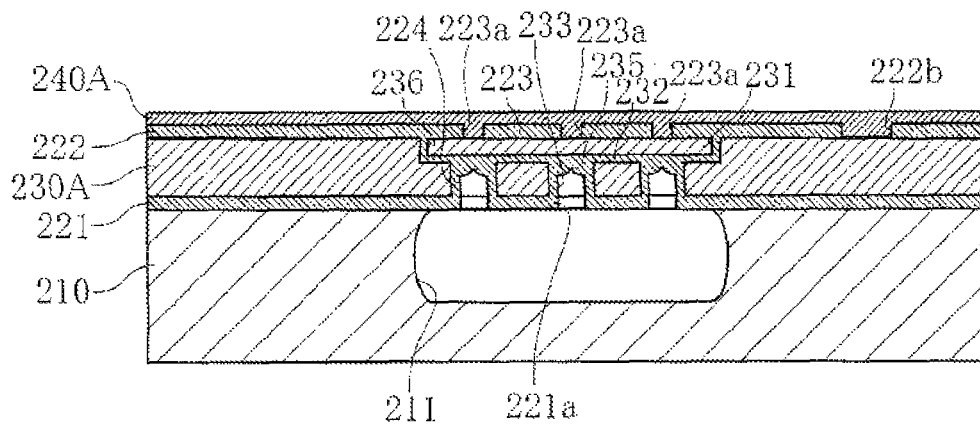


FIG.105

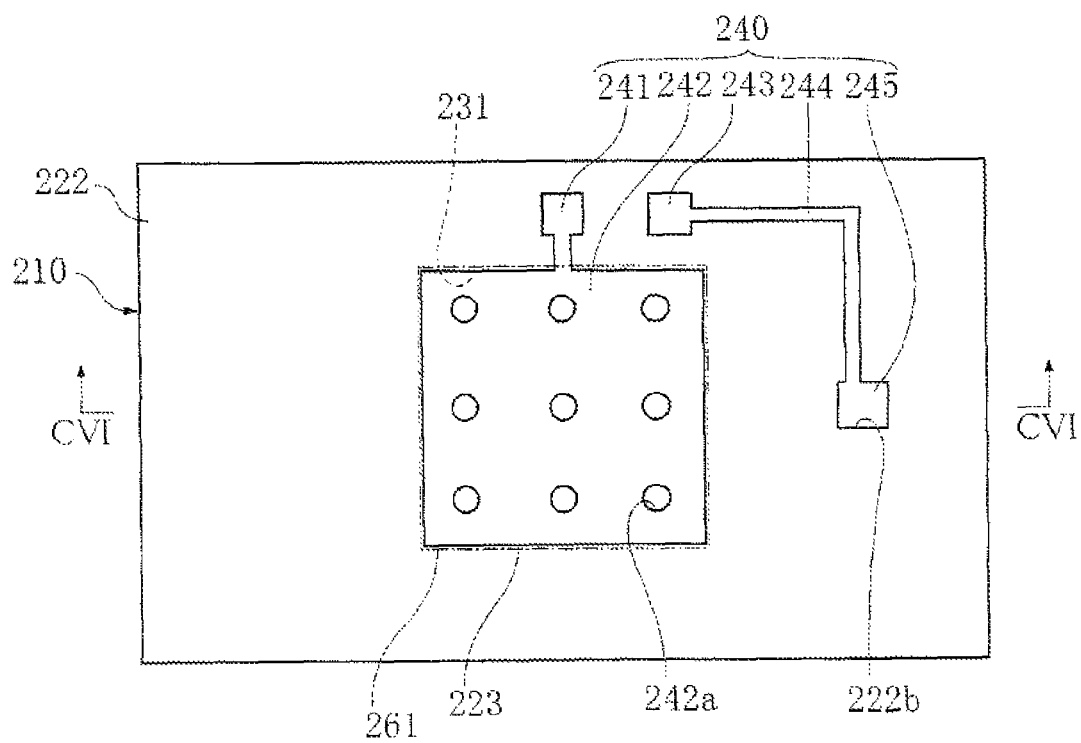


FIG.106

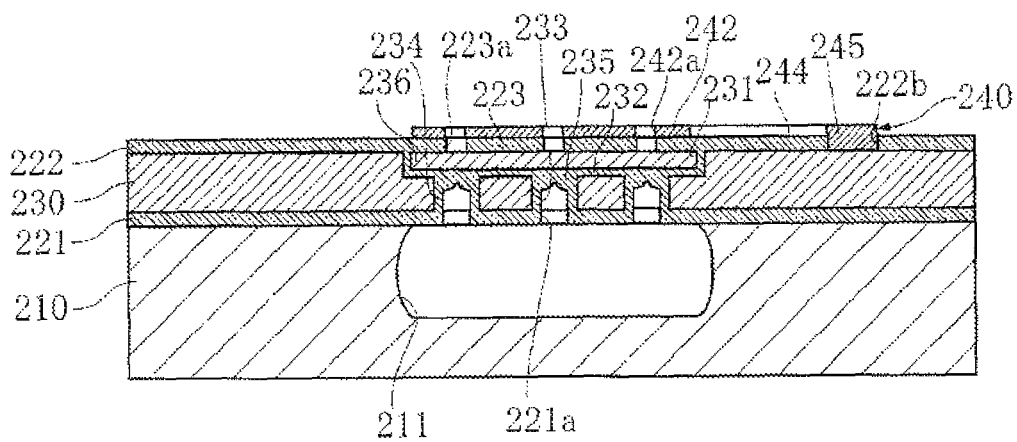




FIG. 107

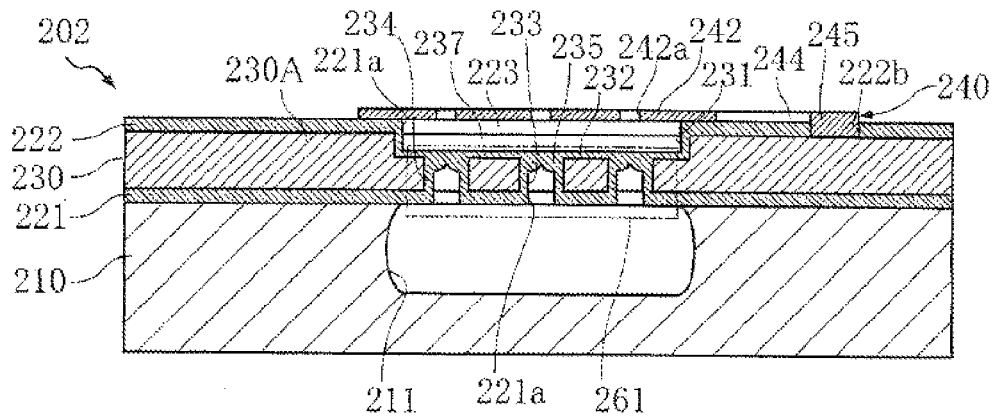


FIG. 108

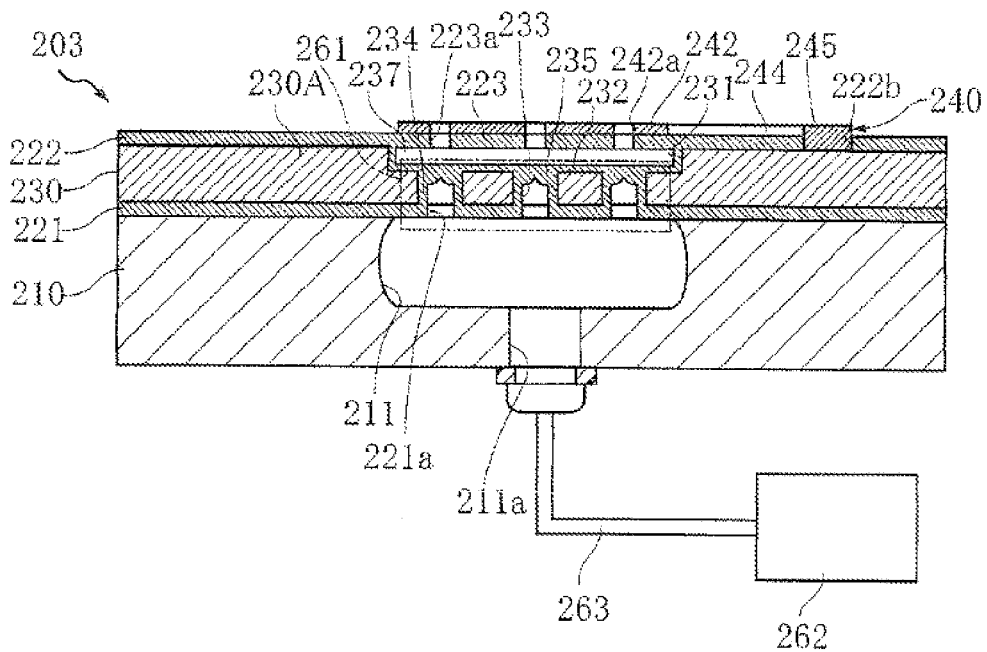


FIG.109

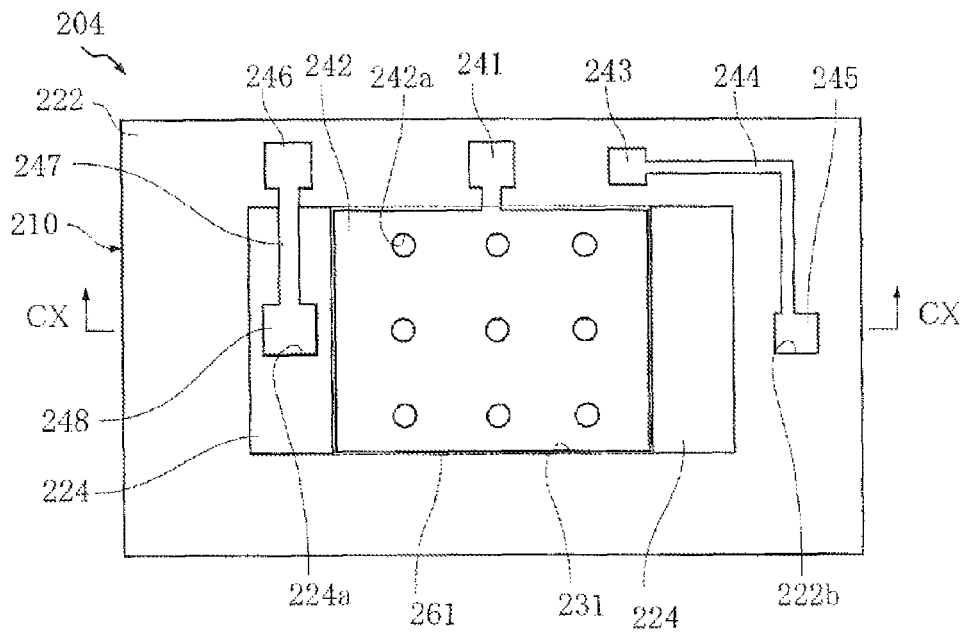


FIG.110

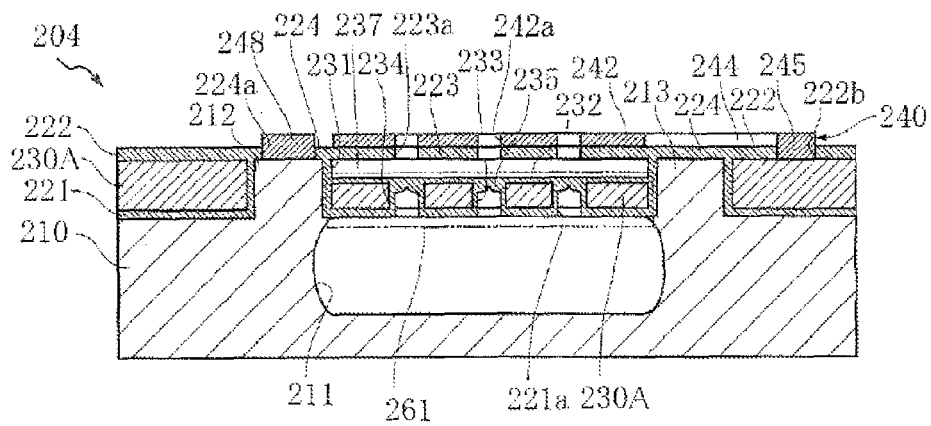


FIG.111

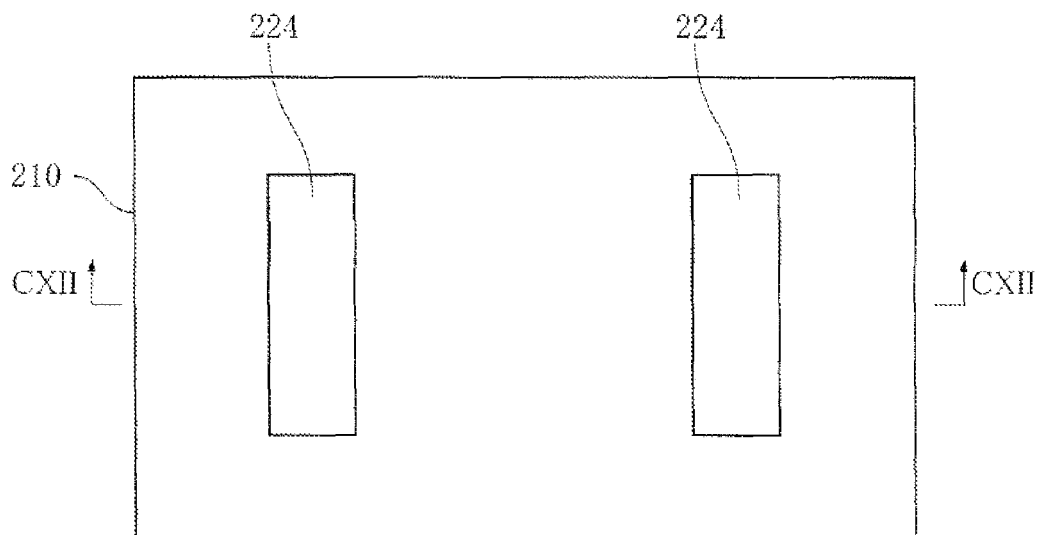


FIG.112

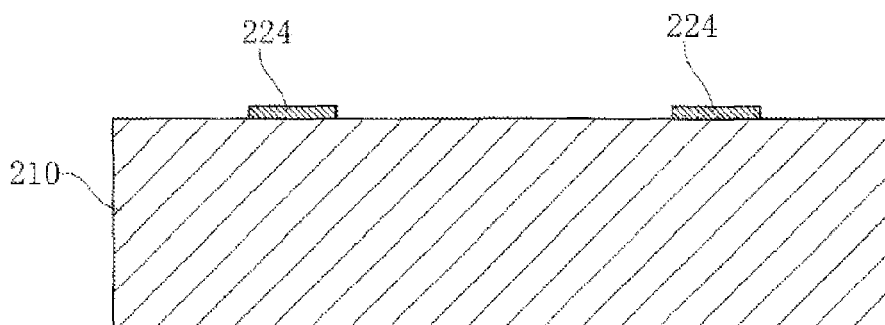


FIG.113

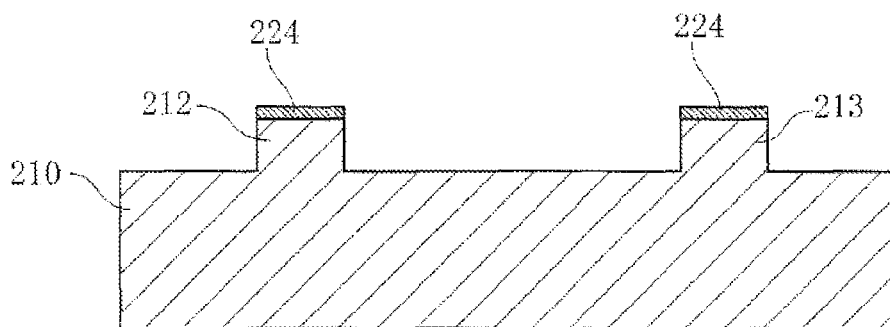


FIG.114

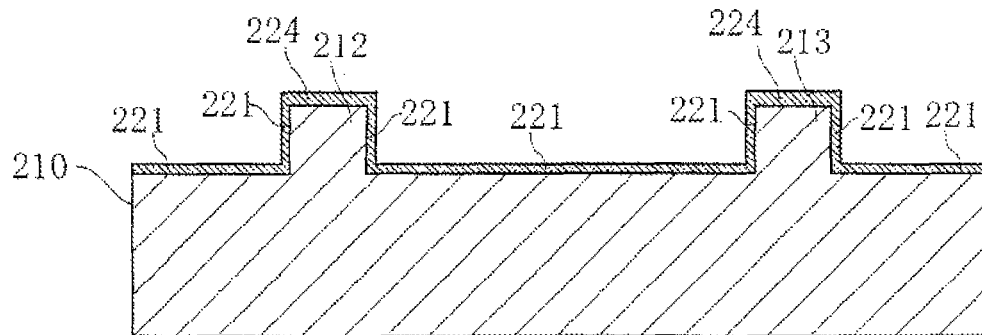


FIG.115

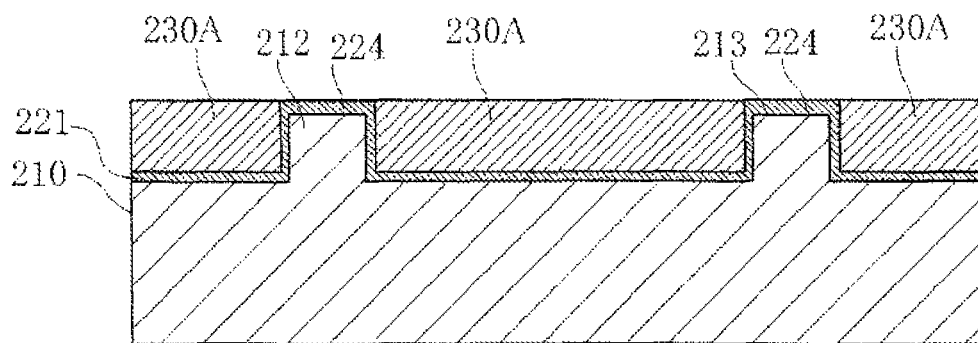


FIG.116

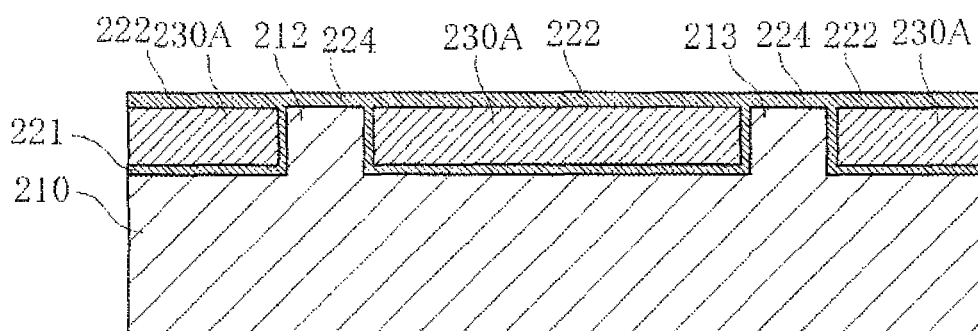


FIG.117

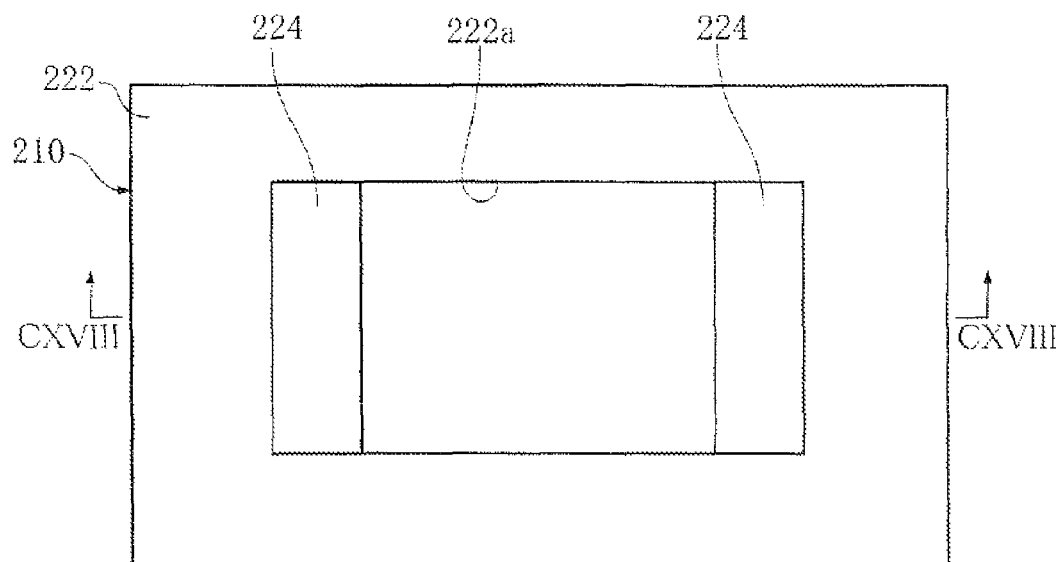


FIG.118

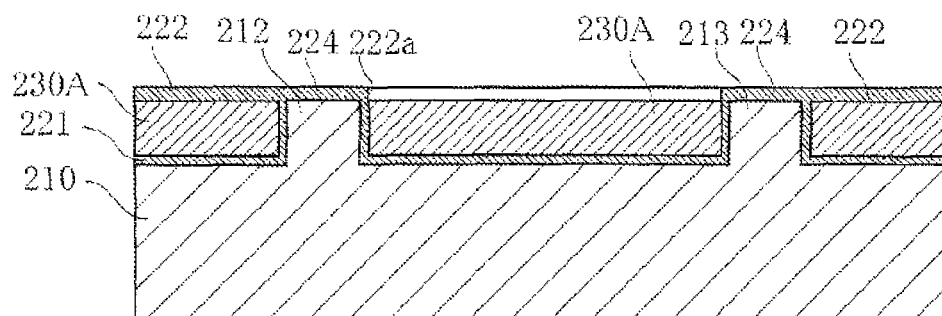




FIG.120

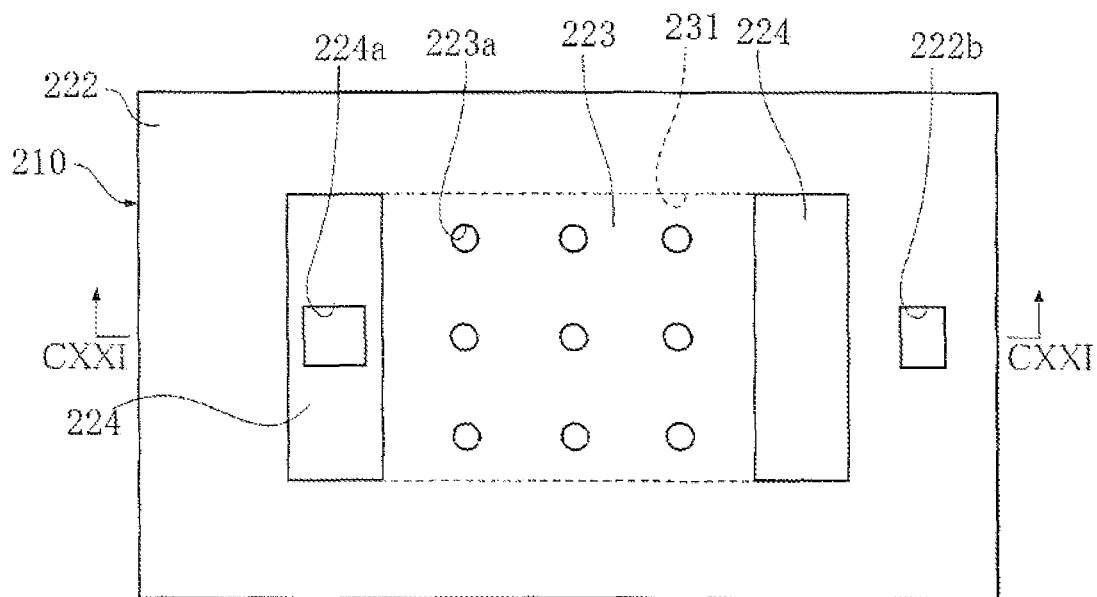


FIG.121

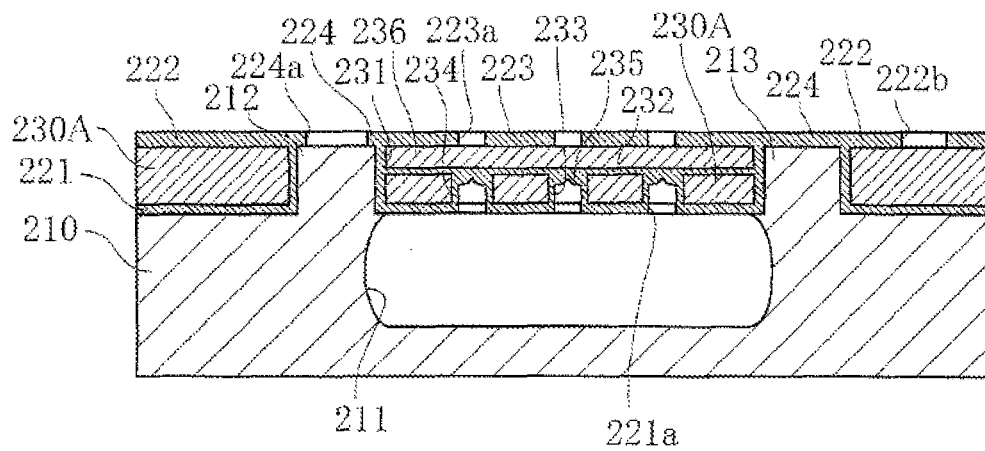
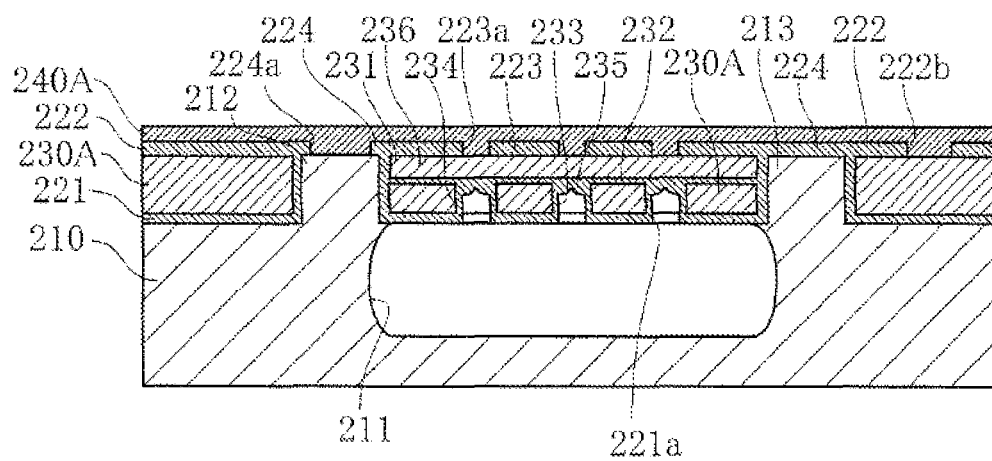


FIG.122





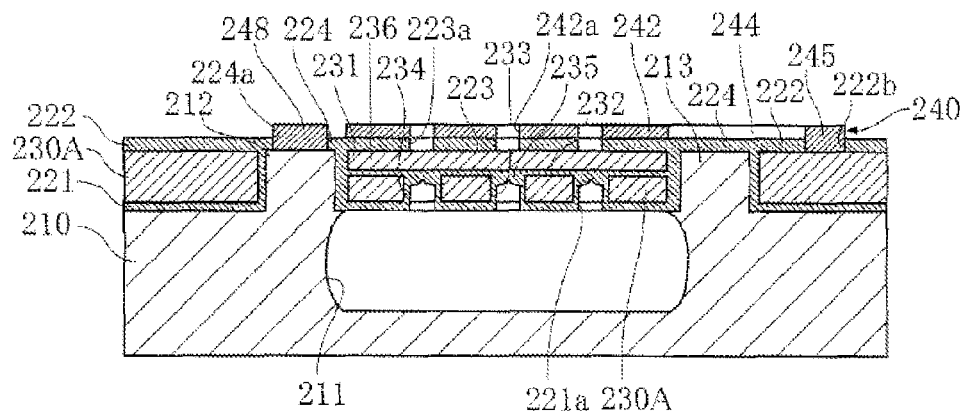


FIG. 125

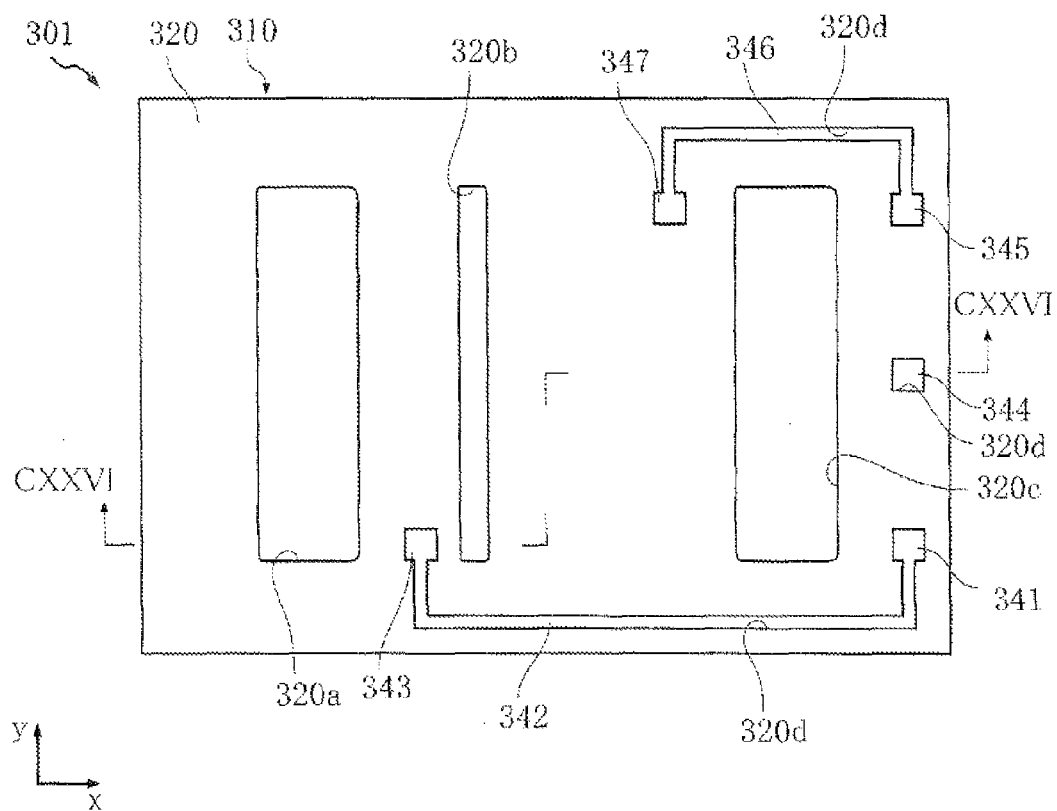


FIG.126

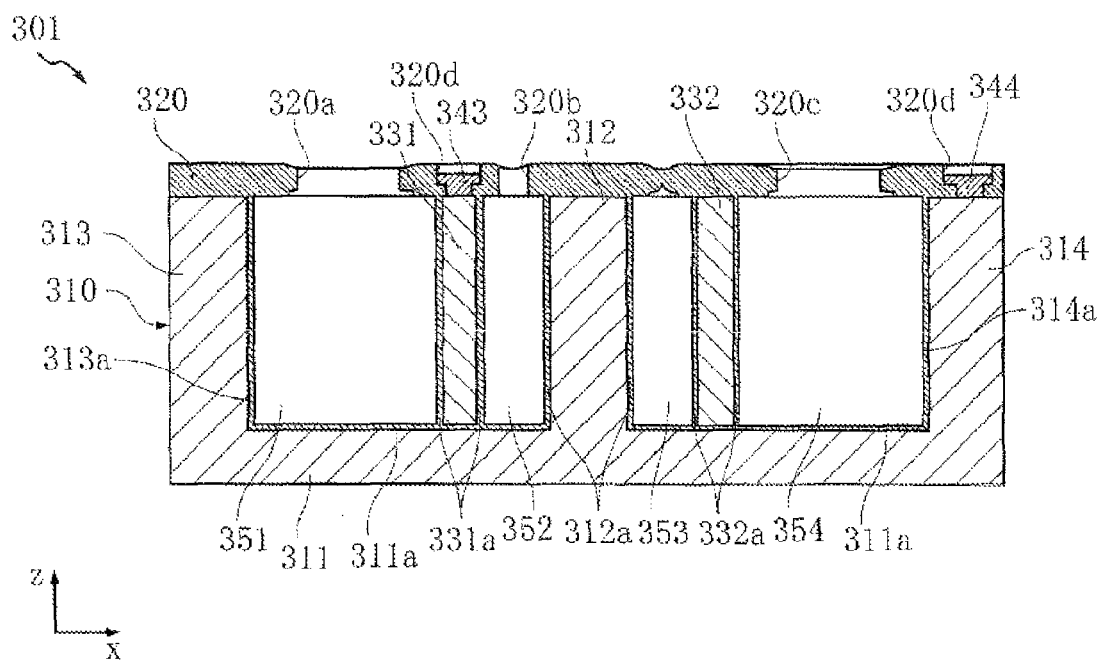


FIG.127

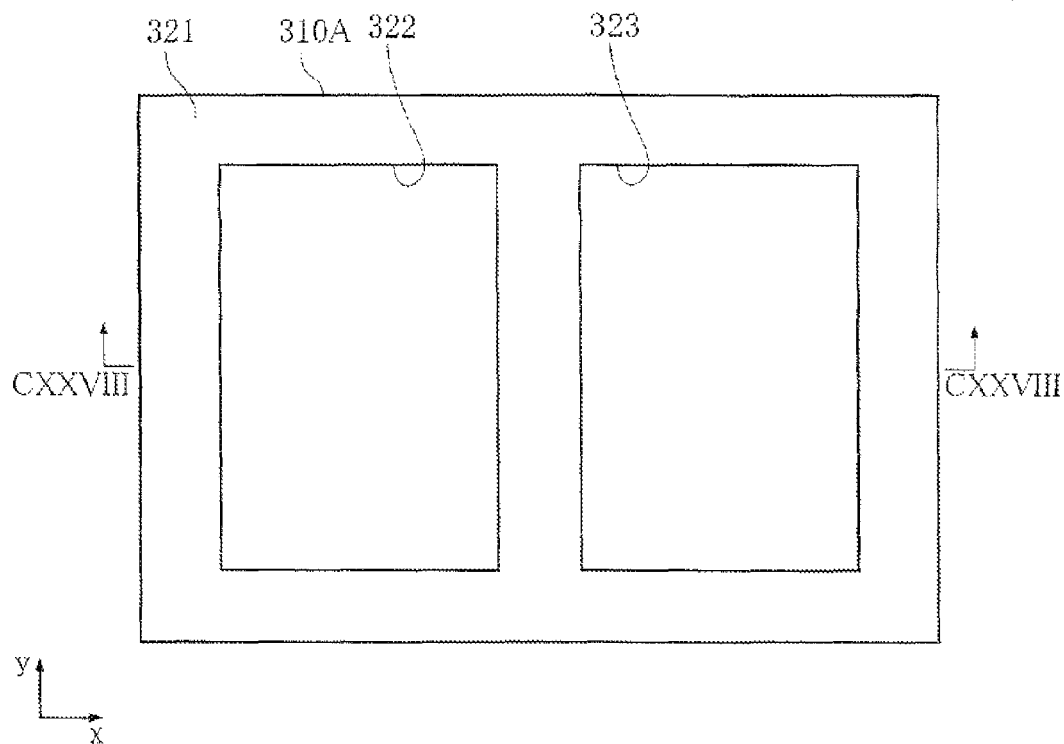


FIG.128

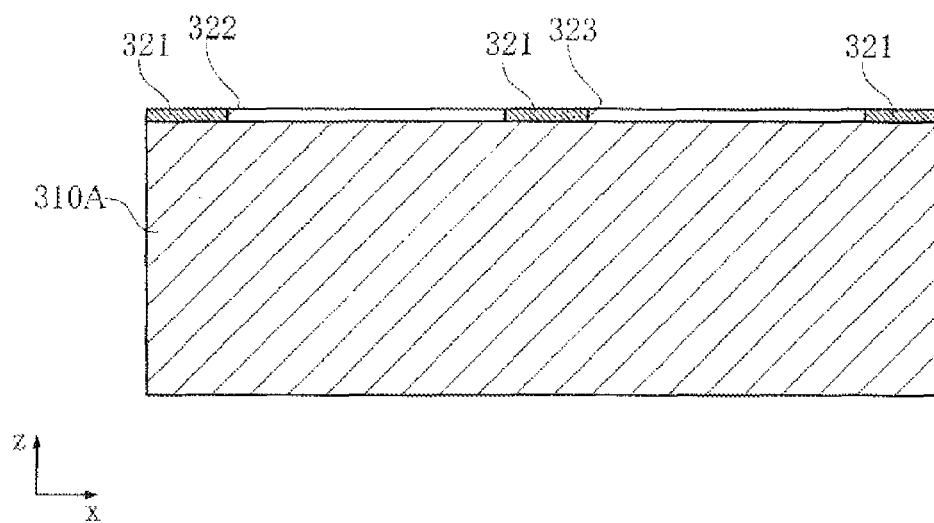


FIG.129

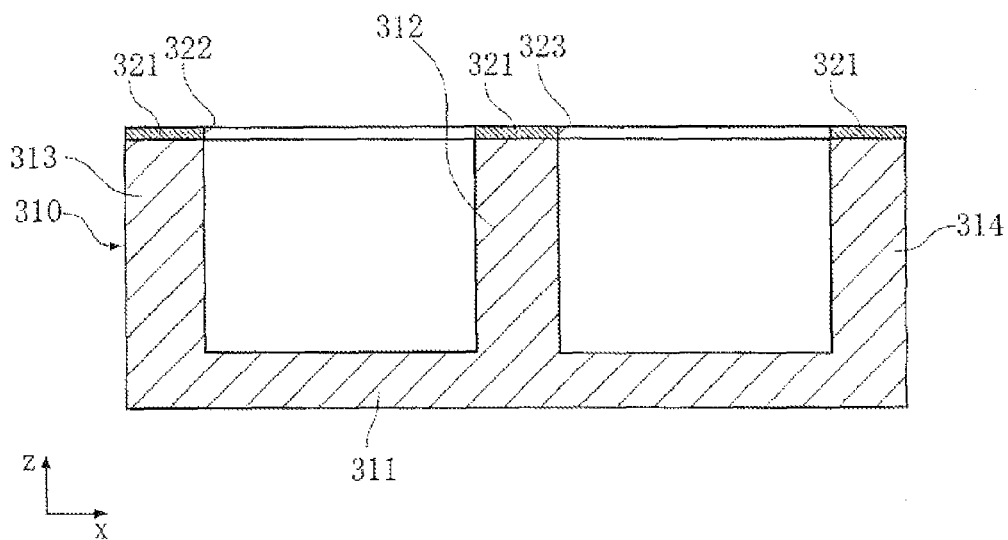


FIG.130

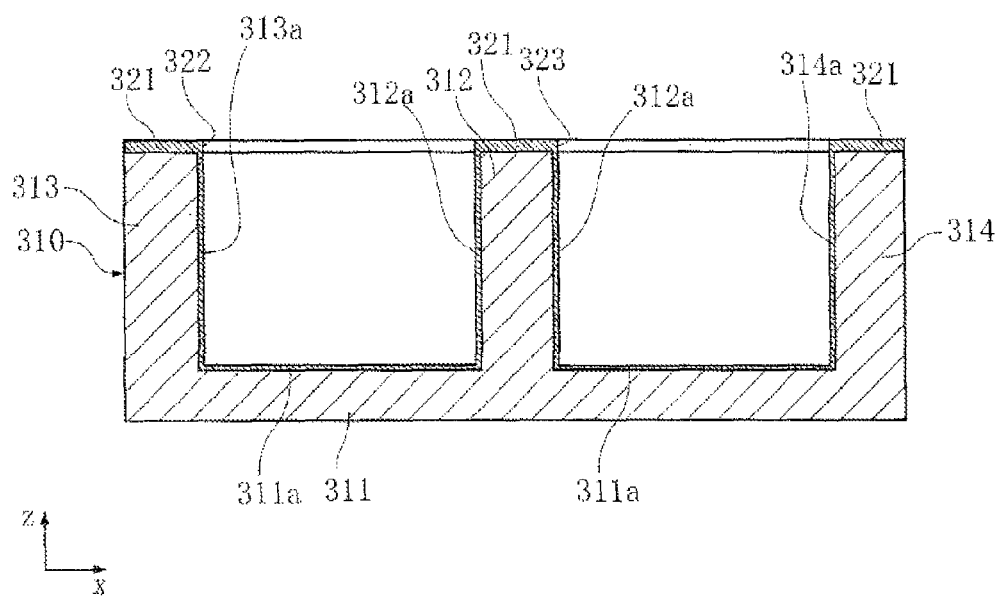


FIG. 131

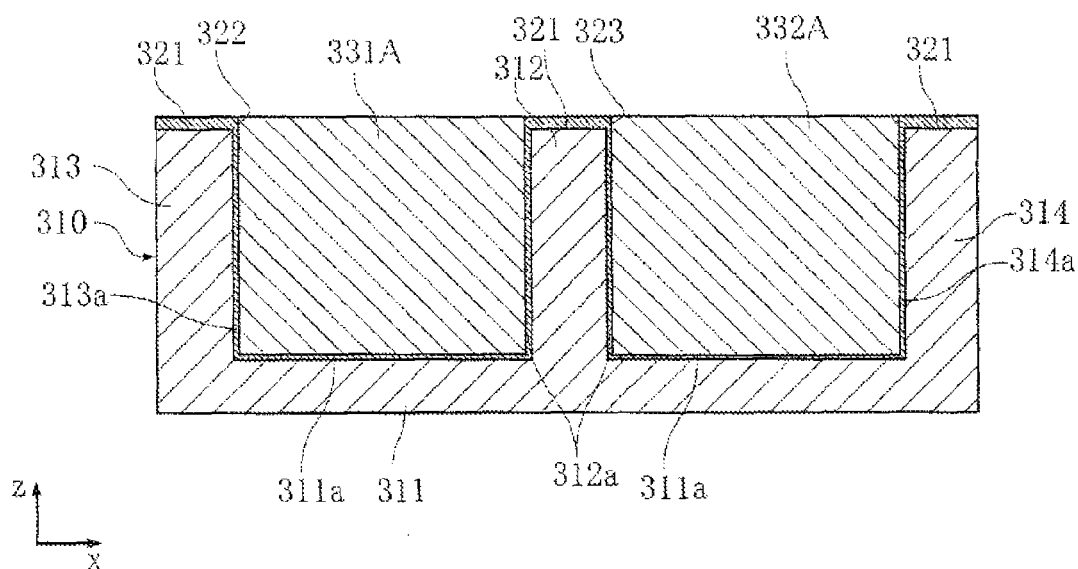


FIG. 132

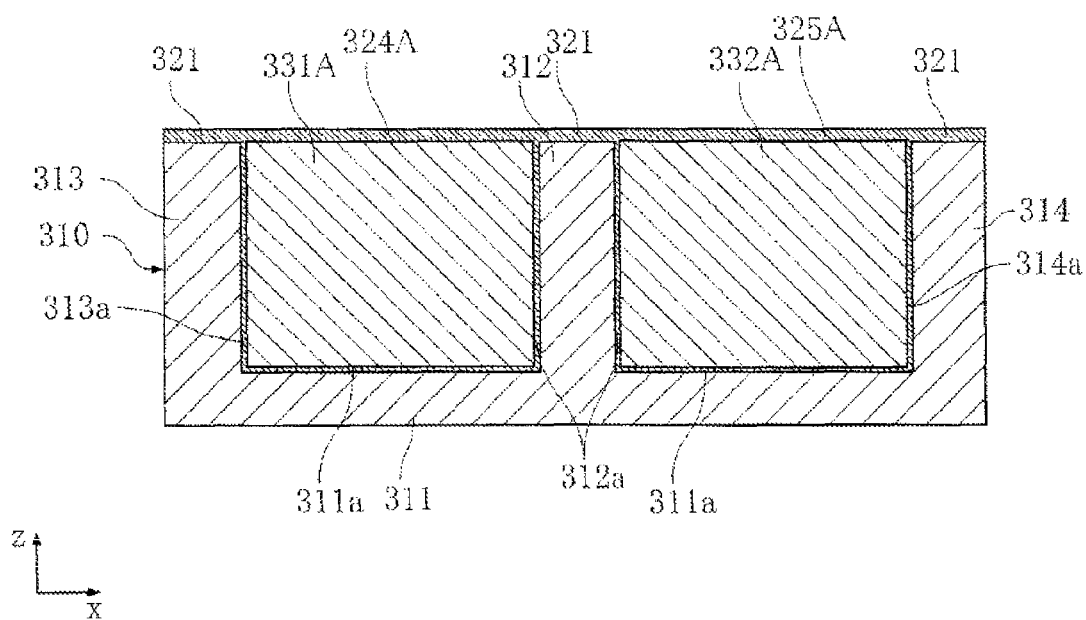


FIG.133

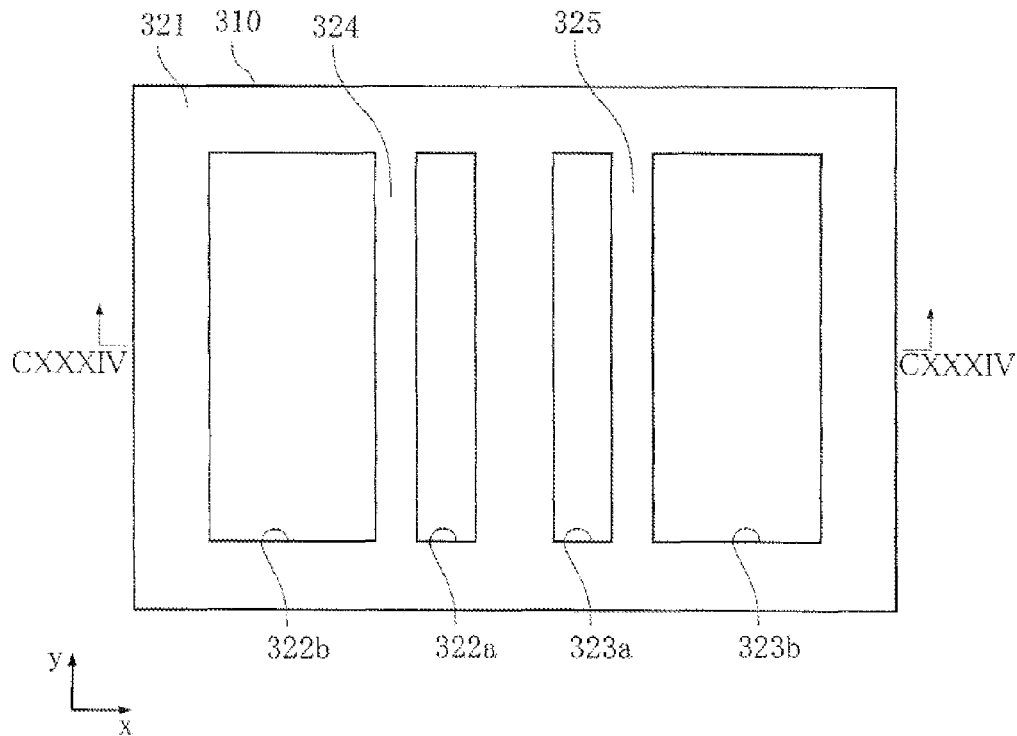


FIG.134

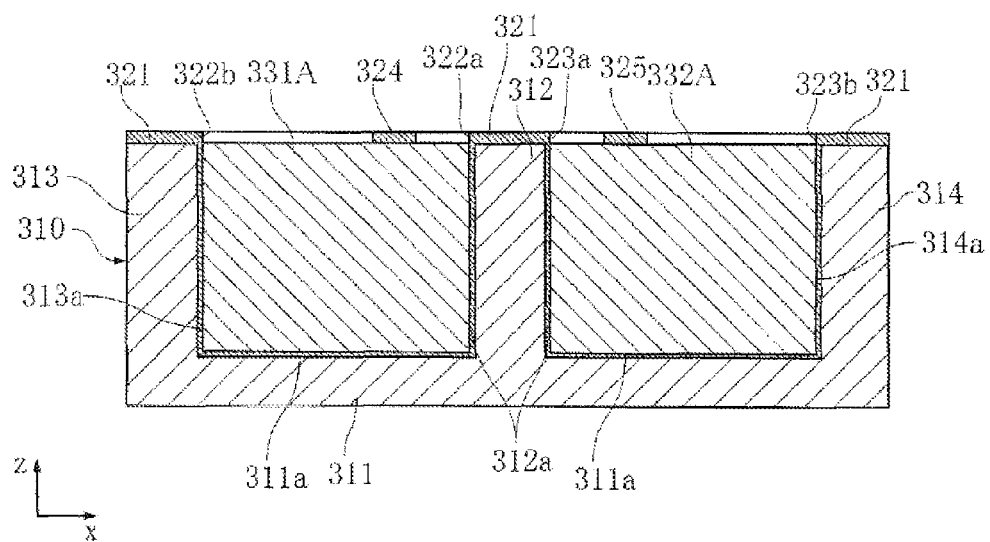


FIG.135

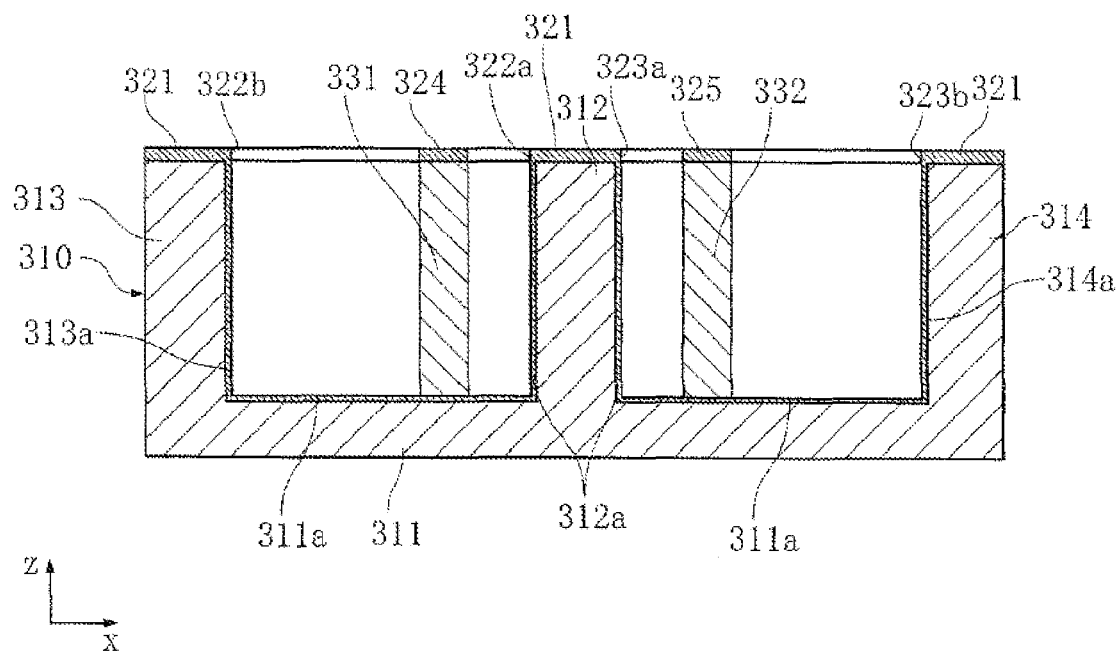


FIG.136

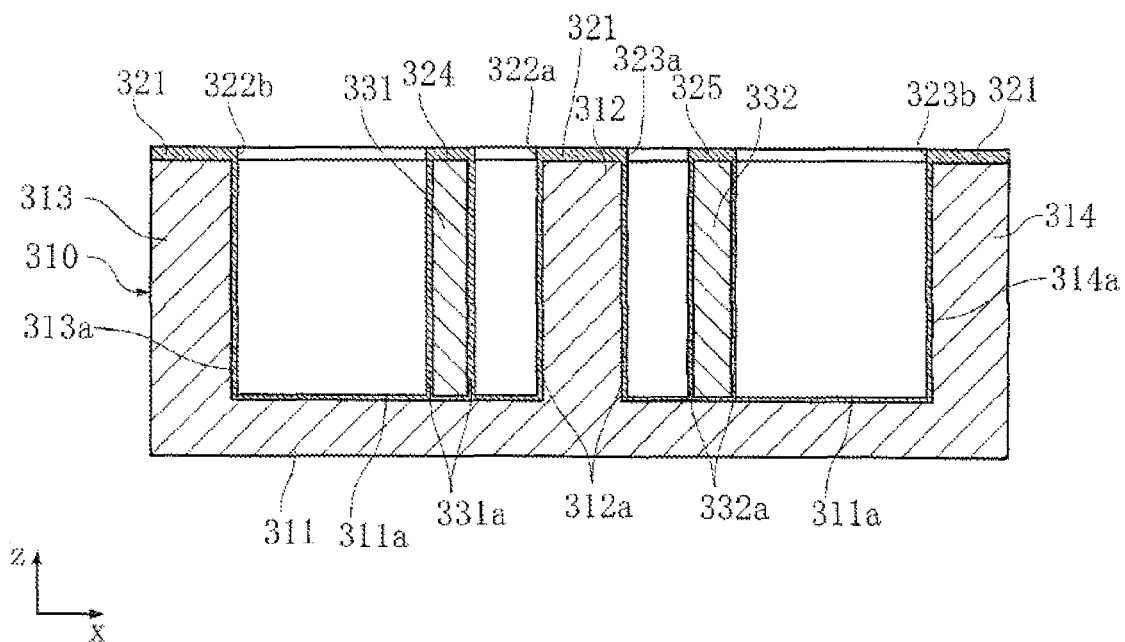




FIG.137

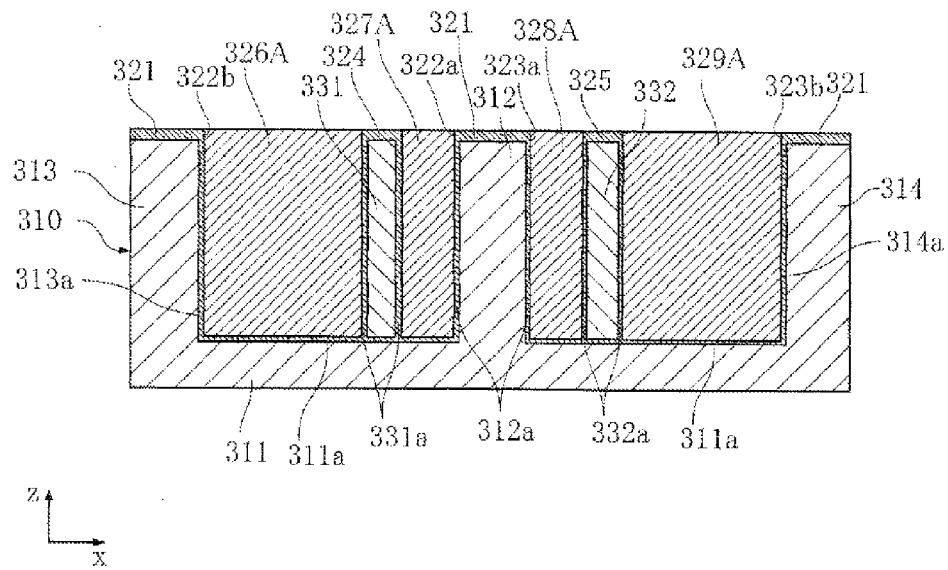


FIG.138

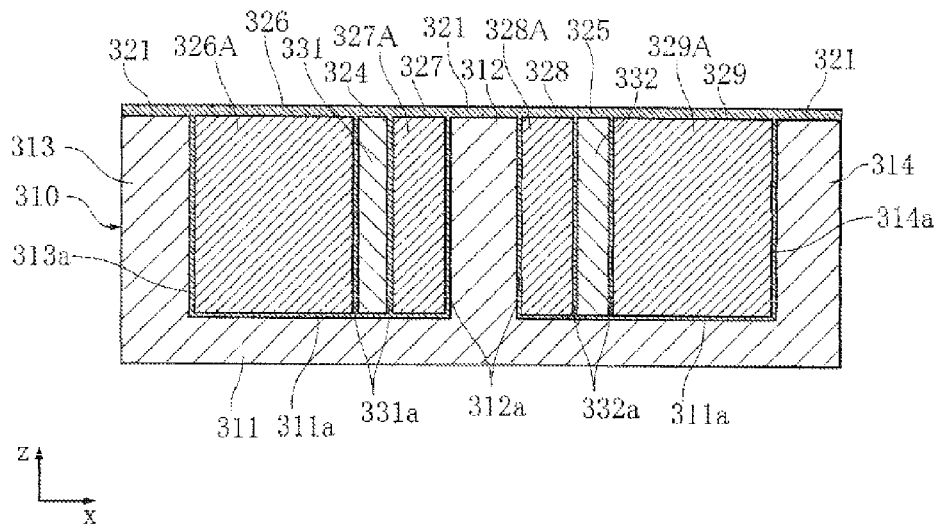


FIG. 139

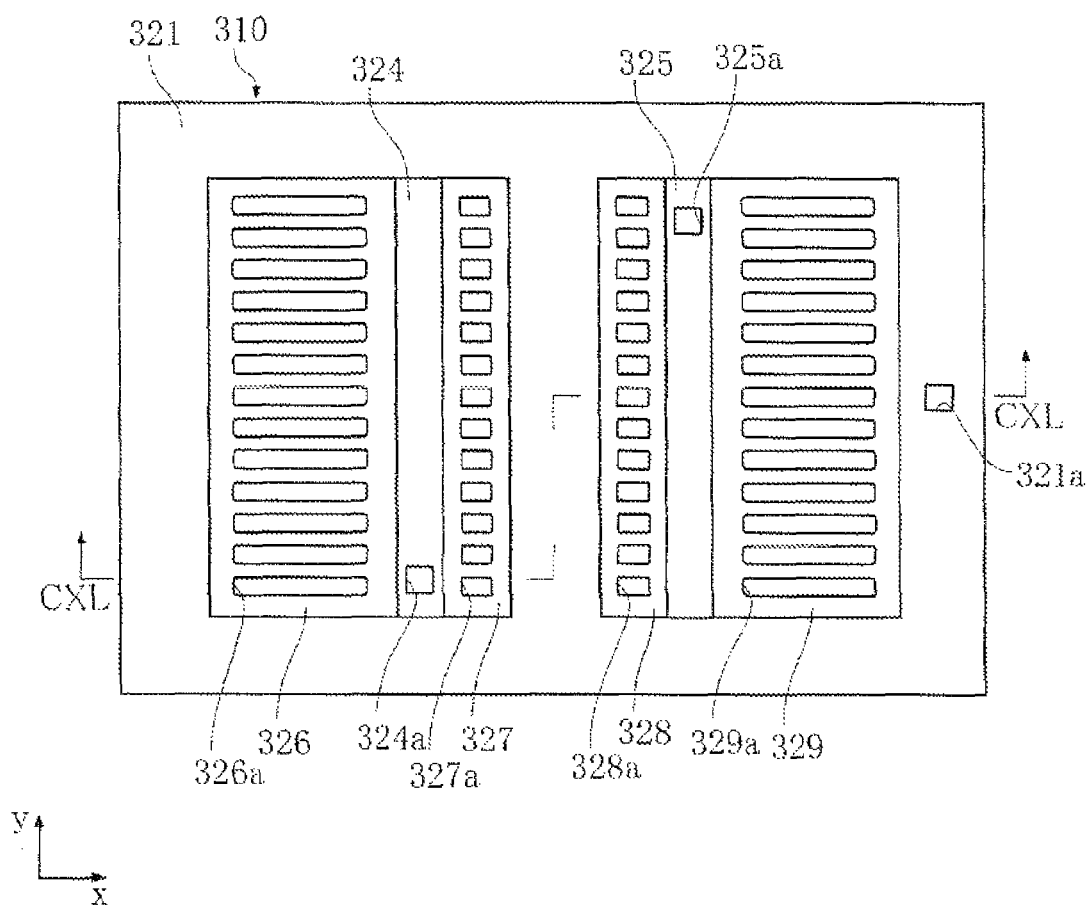


FIG.140

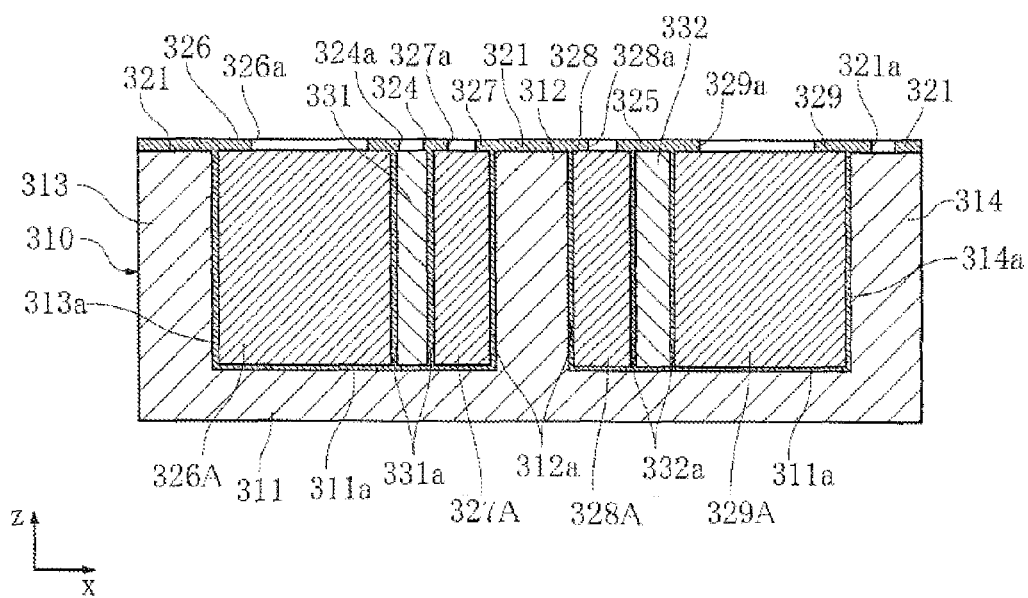


FIG. 141

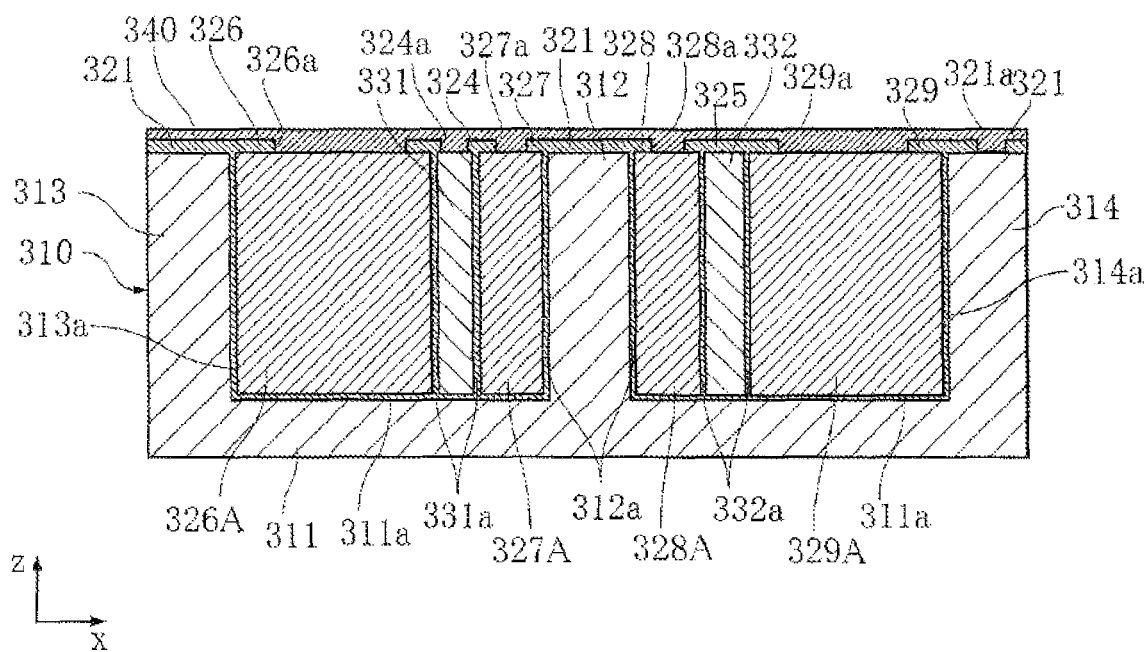


FIG. 142

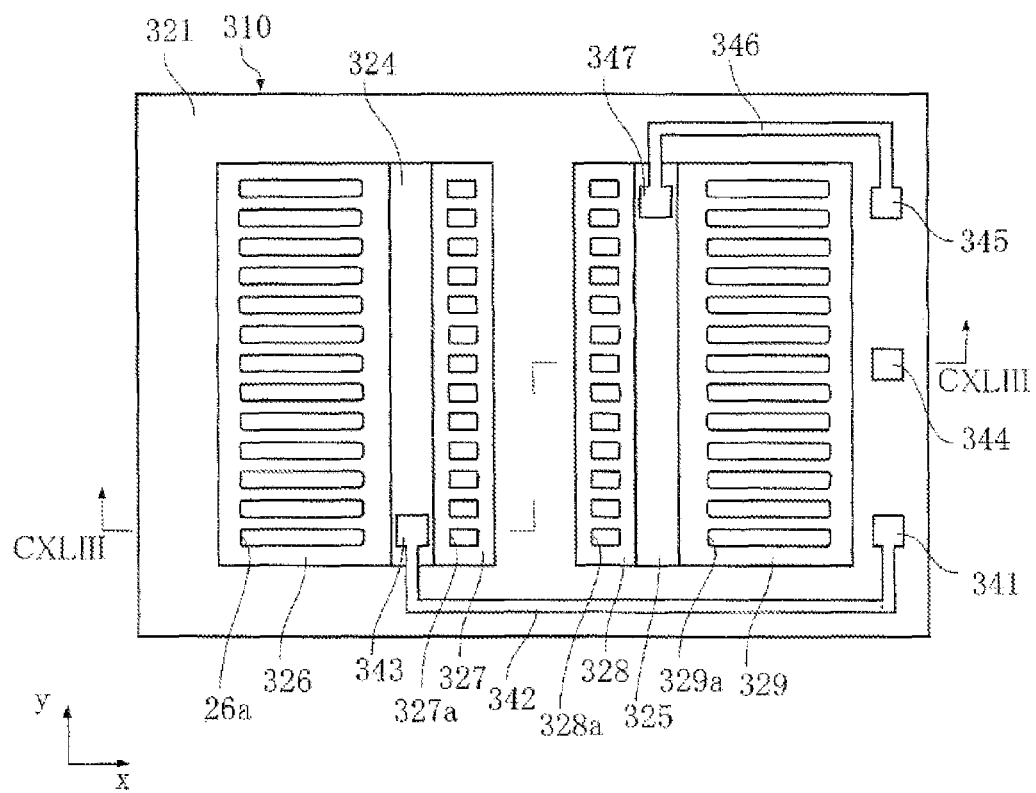


FIG. 143

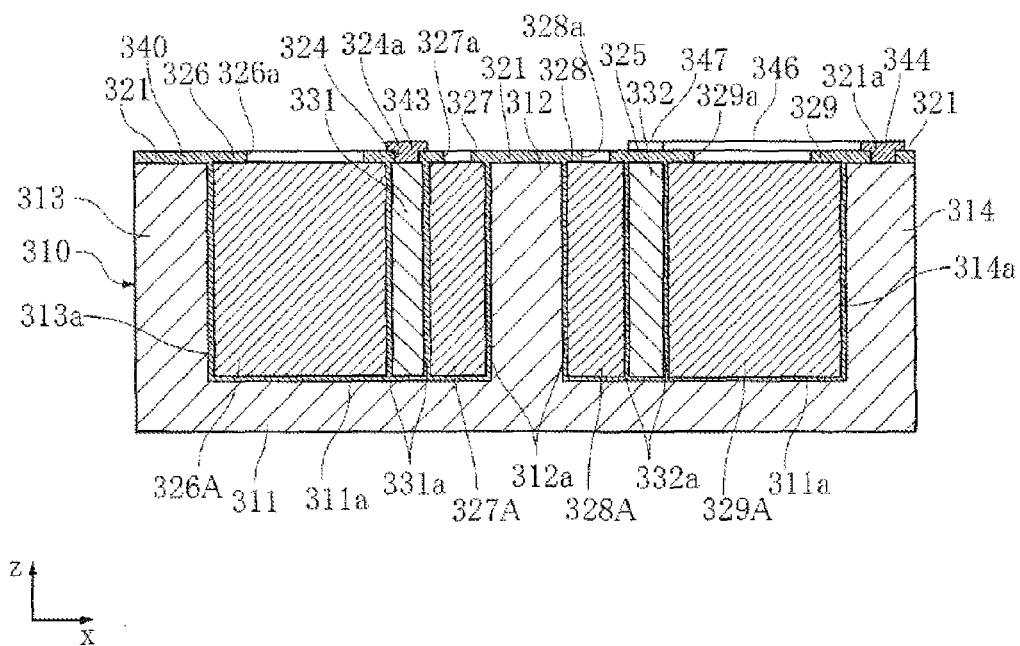


FIG. 144

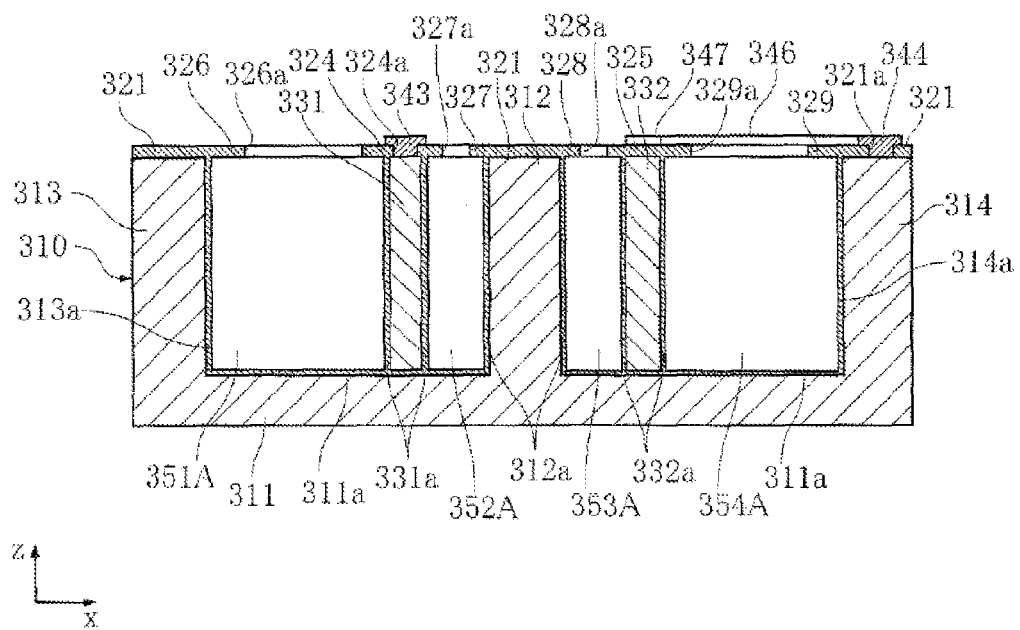




FIG. 146

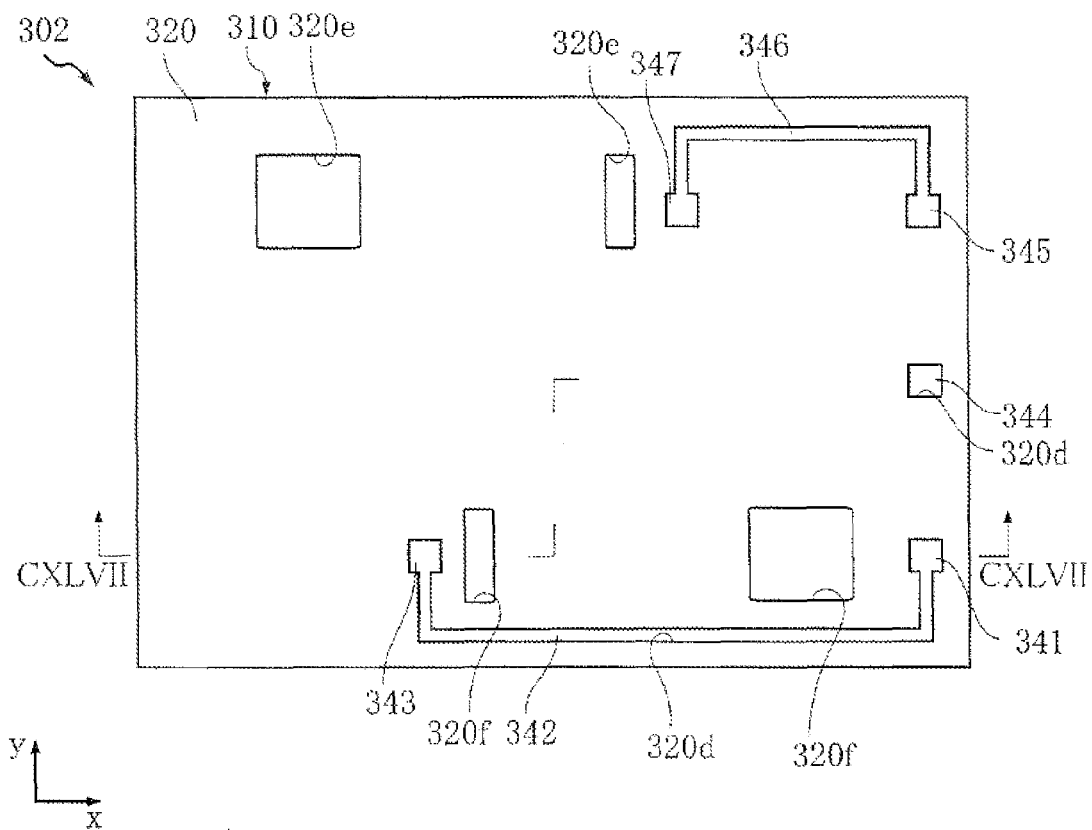




FIG.147

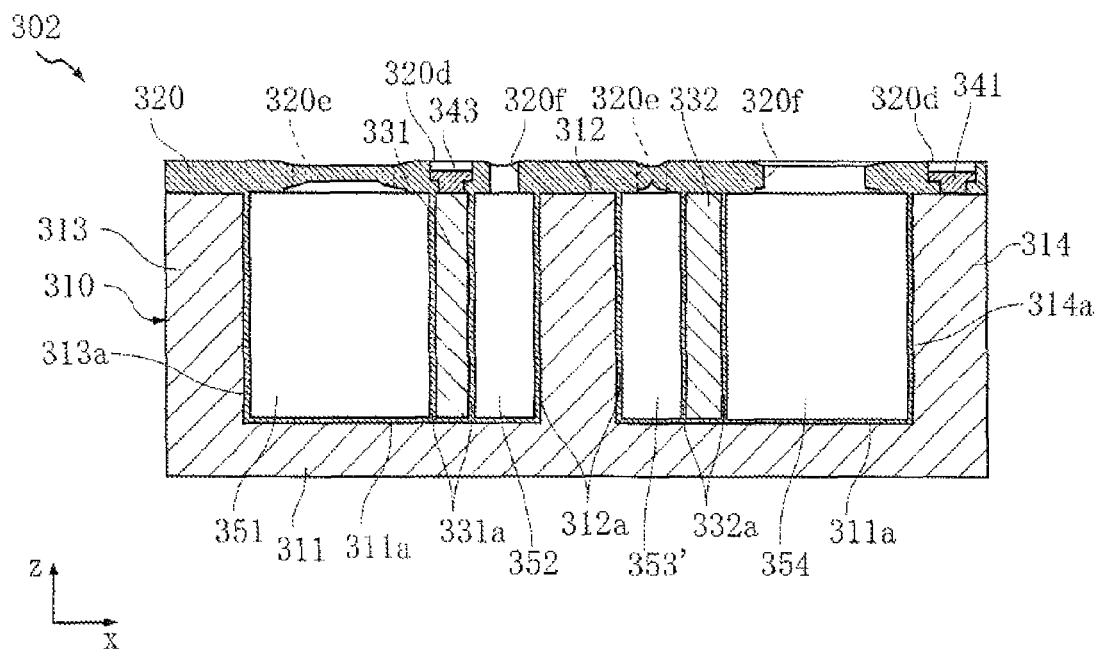


FIG. 148

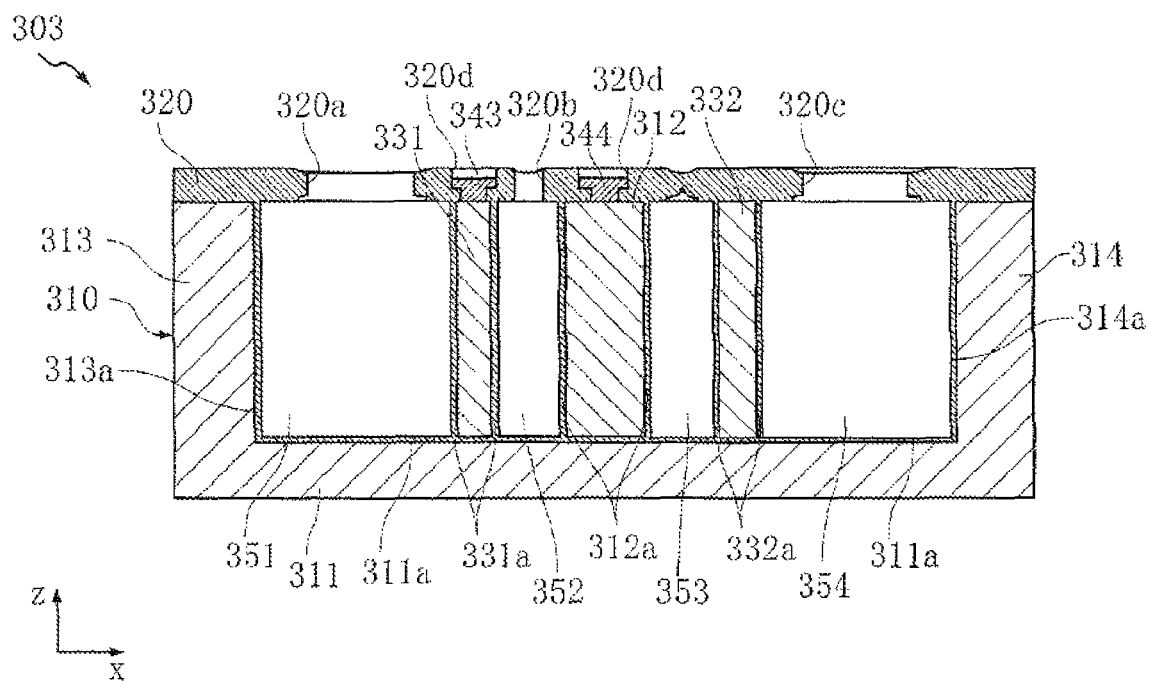


FIG. 149

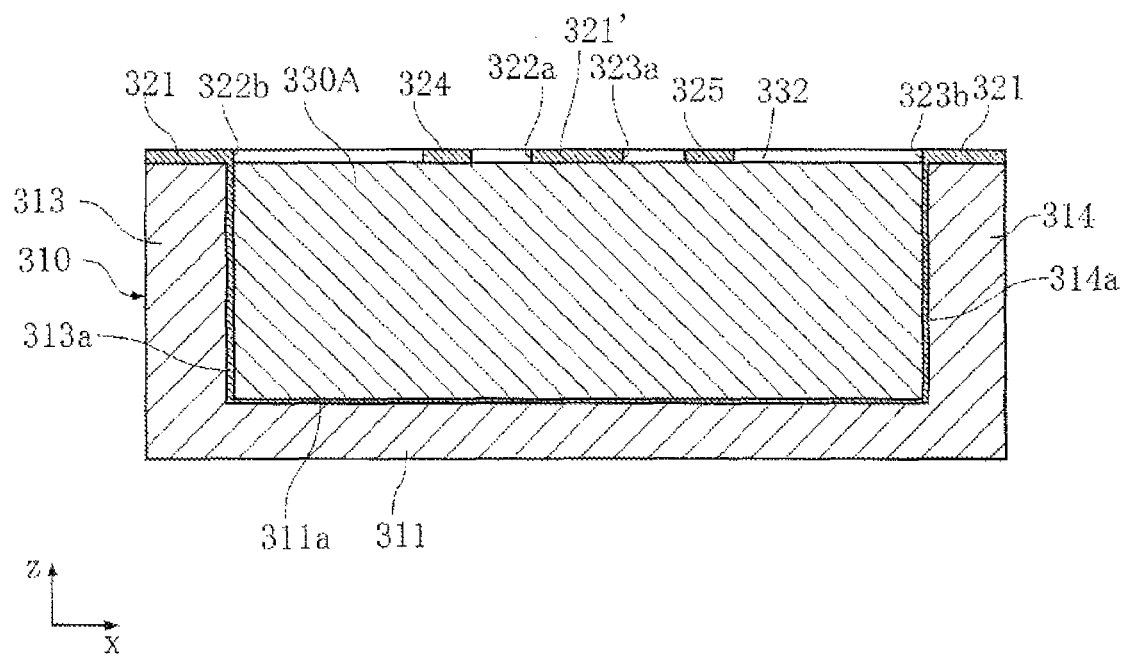


FIG.150

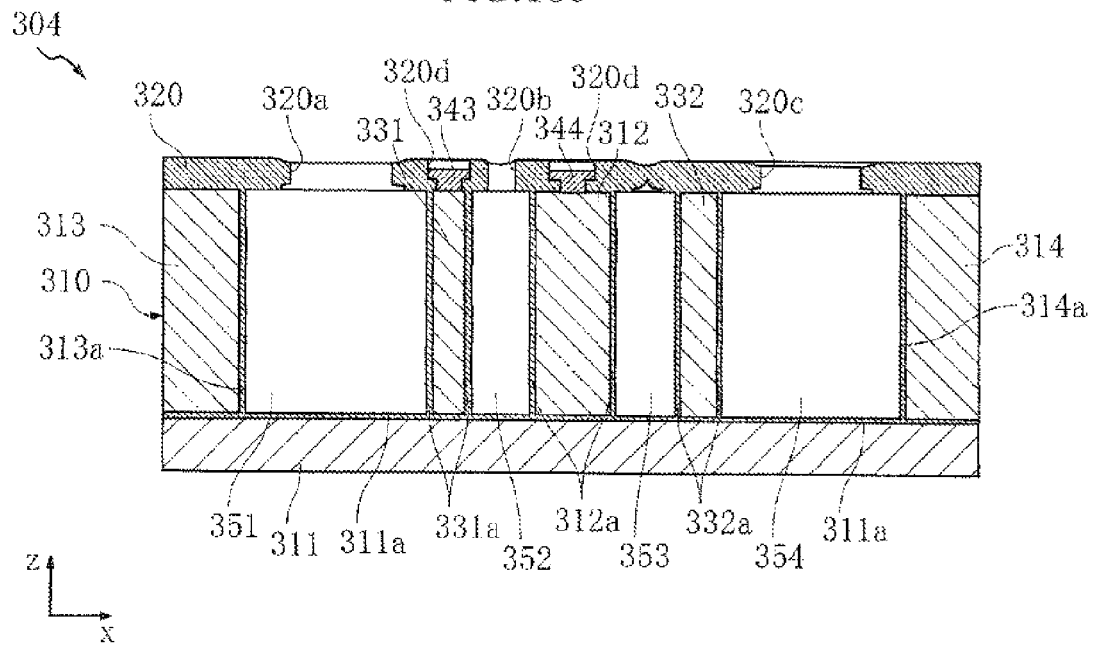


FIG.151

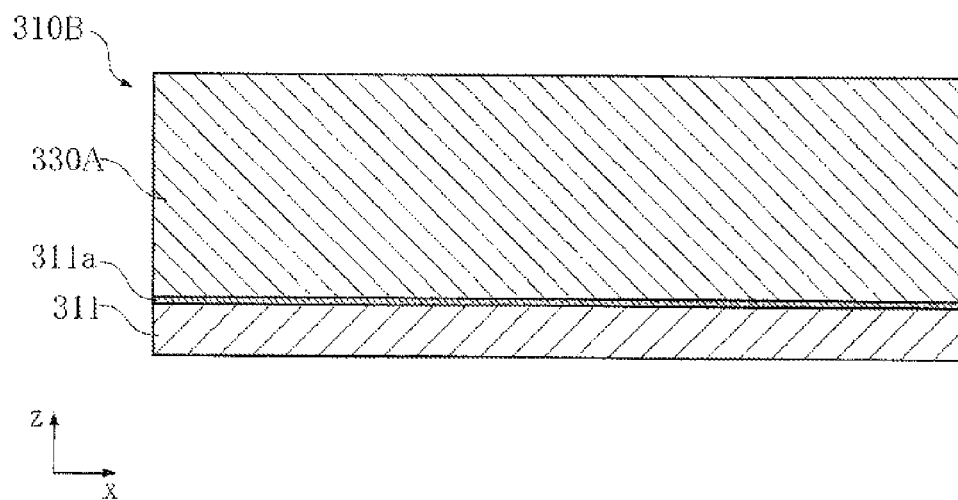


FIG.152

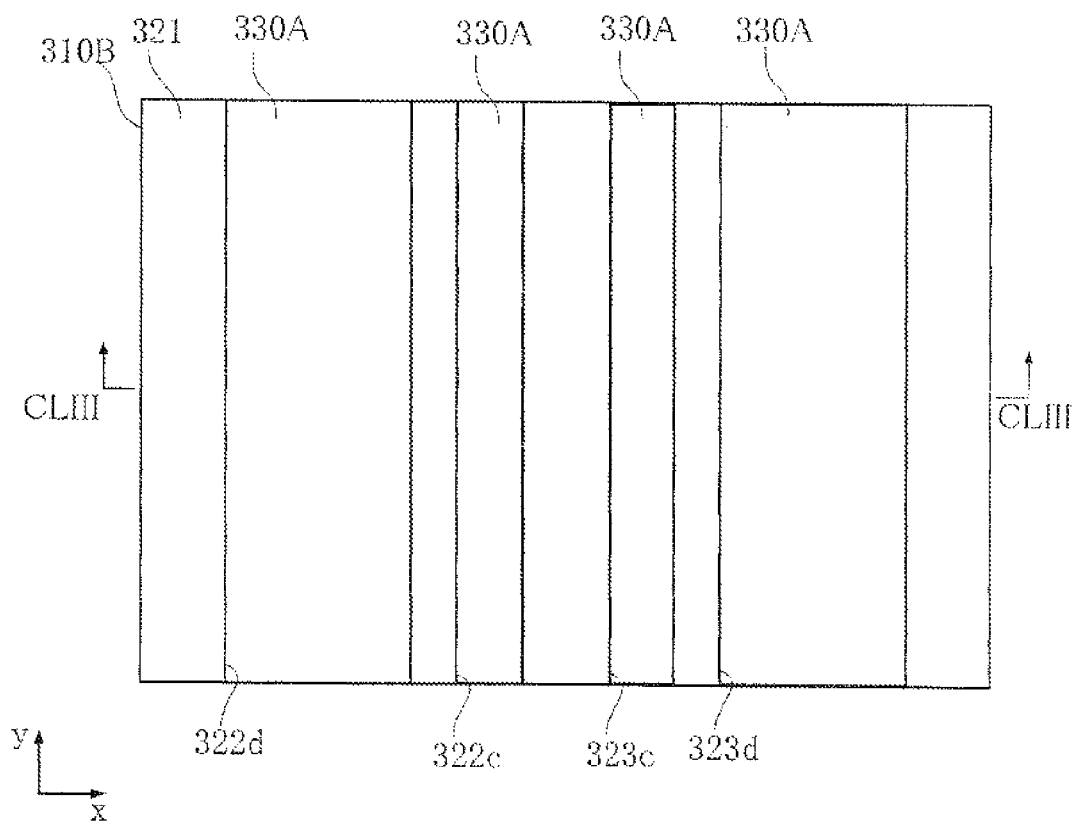


FIG.153

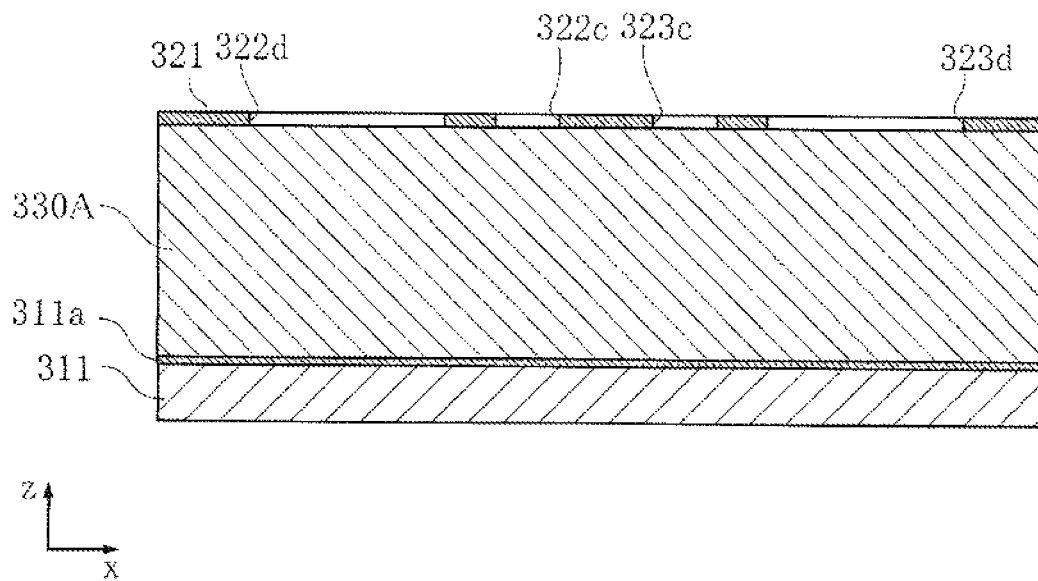


FIG.154  
PRIOR ART

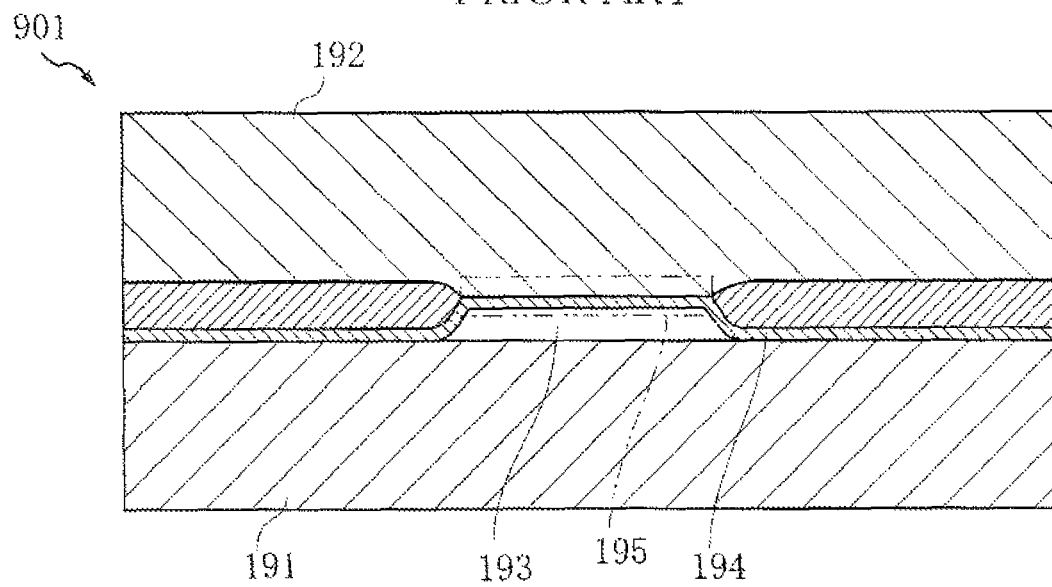
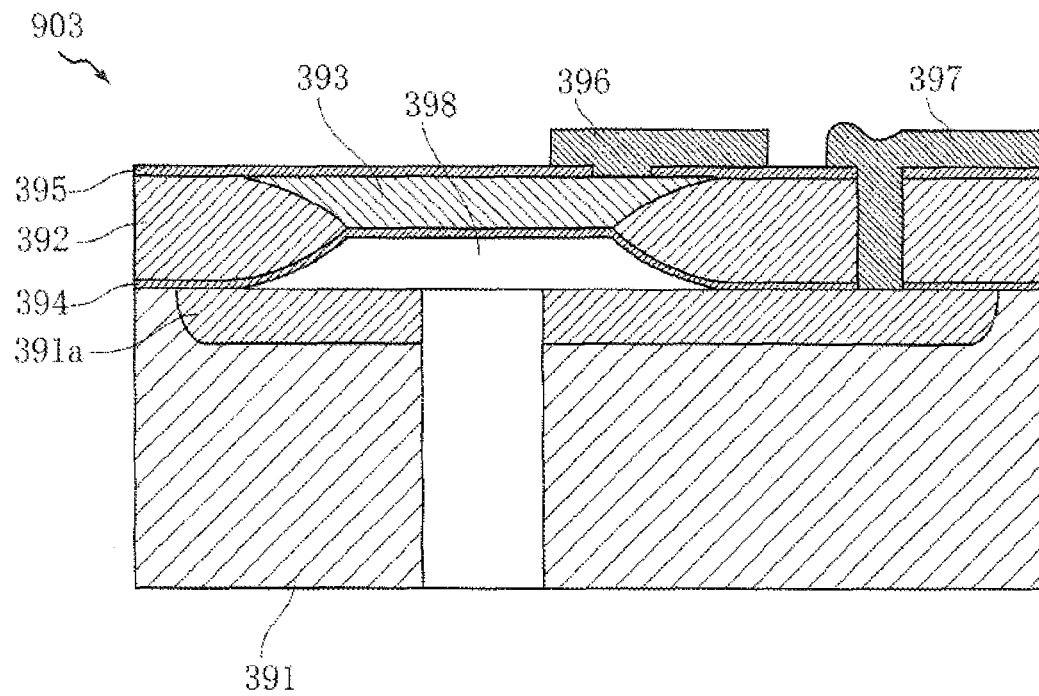


FIG.155  
PRIOR ART



1

# PRESSURE SENSOR AND METHOD FOR MANUFACTURING PRESSURE SENSOR

## TECHNICAL FIELD

The present invention relates to a pressure sensor manufactured by a semiconductor manufacturing technique, and to a method for manufacturing such a pressure sensor.

## BACKGROUND ART

FIG. 154 shows a process step of a method for manufacturing a conventional pressure sensor 901, which is disclosed in Patent Document 1. As shown in FIG. 154, to manufacture the pressure sensor 901, two semiconductor substrates 191 and 192 are bonded together, with a cavity portion 193 and an insulating layer 194 intervening between the substrates. By subsequently abrading the semiconductor substrate 192, a silicon diaphragm is provided on a portion 195 overlapping the cavity portion 193 in the vertical direction. The pressure sensor 901 detects changes in pressure by detecting changes in capacitance between the silicon diaphragm and the semiconductor substrate 191.

However, as described above, to manufacture the pressure sensor 901, two semiconductor substrates 191 and 192 need to be prepared and bonded together. Besides, processing to form a wiring and an electrode needs to be performed with respect to each of the semiconductor substrates 191 and 192. Thus, the manufacturing process is complicated, resulting in a high manufacturing cost of the pressure sensor 901.

FIG. 155 shows a conventional capacitive pressure sensor 903, which is disclosed in Patent Document 1. As shown in FIG. 155, the pressure sensor 903 includes a base substrate 391 in the form of a flat plate, an oxide film 392, a movable electrode 393, insulating layers 394, 395, metal wirings 396, 397, and a cavity portion 398. The base substrate 391 is made of silicon and has a fixed electrode 391a on the surface, in which boron ions are implanted and dispersed. The movable electrode 393 is formed by implanting and dispersing boron ions into part of a material substrate of made of silicon, and then removing remaining portions. The movable electrode is supported by the oxide film 392. The movable electrode 393 is formed to be parallel to the fixed electrode 391a by arranging the material substrate in parallel to the base substrate 391. The insulating layer 394 provides insulation between the base substrate 391 and the oxide film 392. The insulating layer 395 is formed to cover the surfaces of the oxide film 392 and movable electrode 393. The cavity portion 398 is formed to separate the fixed electrode 391a and the movable electrode 393 in the direction normal to the surface of the base substrate 391 (lamination direction). The metal wiring 396 is electrically connected to the movable electrode 393, and the metal wiring 397 is electrically connected to the fixed electrode 391a. This pressure sensor 903 detects changes in pressure by detecting changes in capacitance between the fixed electrode 391a and the movable electrode 393 facing each other in the lamination direction.

In recent years, size reduction of pressure sensors is increasingly demanded with size reduction of electronic devices. On the other hand, to detect changes in capacitance more precisely, it is desirable to increase the capacitance between the fixed electrode 391a and the movable electrode 393, and for that purpose, the facing area of the fixed electrode 391a and the movable electrode 393 as viewed in the lamination direction of the base substrate 391 needs to be increased. Thus, it is difficult to reduce the area of the mov-

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able electrode 393 as viewed in the lamination direction, which hinders size reduction of the pressure sensor 903. Patent Document 1: Japanese Patent No. 2850558

## DISCLOSURE OF THE INVENTION

### Problems to be Solved by the Invention

The present invention has been proposed under the circumstances described above. It is therefore an object of the present invention to provide a more precise pressure sensor that can be manufactured easily. Another object of the present invention is to provide a method for manufacturing a pressure sensor that realizes size reduction.

### Means for Solving the Problems

A pressure sensor provided according to a first aspect of the present invention comprises a semiconductor substrate, an insulating layer formed on the semiconductor substrate, a semiconductor layer formed on the semiconductor substrate, with the insulating layer intervening therebetween, and a cavity portion provided between the semiconductor substrate and the semiconductor layer. The portion of the semiconductor layer which overlaps the cavity portion as viewed in a lamination direction serves as a movable portion. The cavity portion is surrounded by the insulating layer.

In a preferred embodiment, the semiconductor substrate includes a recess extending inward in the lamination direction, and the cavity portion is provided in the recess.

In a preferred embodiment, the semiconductor layer is provided outside the recess.

In a preferred embodiment, the semiconductor layer is provided in the recess.

In a preferred embodiment, the pressure sensor further comprises a first electrode electrically connected to the semiconductor layer and a second electrode electrically connected to the semiconductor substrate.

In a preferred embodiment, the semiconductor substrate is made of single-crystal silicon, the semiconductor layer is made of polycrystalline silicon, and the insulating layer is made of silicon dioxide.

A method for manufacturing a pressure sensor according to a second aspect of the present invention comprises the steps of forming a recess in a semiconductor substrate, covering an entire surface of the recess with a first insulating layer, filling the recess with a sacrificial layer after covering the recess with the first insulating layer, covering with a second insulating layer a portion of the sacrificial layer which is exposed from the first insulating layer, forming a semiconductor layer to overlap the sacrificial layer with the second insulating layer intervening therebetween, and forming a cavity portion by removing the sacrificial layer. The portion of the semiconductor layer which overlaps the cavity portion serves as a movable portion.

A method for manufacturing a pressure sensor according to a third aspect of the present invention comprises the steps of forming a recess in a semiconductor substrate, covering an entire surface of the recess with a first insulating layer, forming a sacrificial layer to fill a portion of the recess which is close to a bottom after covering the recess with the first insulating layer, covering with a second insulating layer a portion of the sacrificial layer which is exposed from the first insulating layer, forming a semiconductor layer in the recess to overlap the sacrificial layer with the second insulating layer



intervening therebetween, and forming a cavity portion by removing the sacrificial layer. The semiconductor layer serves as a movable portion.

A method for manufacturing a pressure sensor according to a fourth aspect of the present invention comprises the steps of forming a first insulating layer on a surface of a semiconductor substrate, forming a recess in the first insulating layer, forming a second insulating layer on a bottom of the recess, forming a sacrificial layer in the recess, covering with a third insulating layer a portion of the sacrificial layer which is exposed from the first insulating layer, forming a semiconductor layer to overlap the sacrificial layer with the third insulating layer intervening therebetween, and forming a cavity portion by removing the sacrificial layer. The portion of the semiconductor layer which overlaps the cavity portion serves as a movable portion.

In a preferred embodiment, the step of forming a cavity portion comprises forming a vent hole penetrating the semiconductor layer and reaching the sacrificial layer, etching the sacrificial layer through the vent hole, and sealing the vent hole with an insulating material after the sacrificial layer is removed.

A pressure sensor provided according to a fifth aspect of the present invention comprises a movable portion and a piezoresistor provided at the movable portion. The pressure sensor further comprises a semiconductor substrate including a cavity portion which is open at an obverse surface, a semiconductor layer formed on the obverse surface of the semiconductor substrate and including a through-hole penetrating in a lamination direction, and a sealing member which seals the through-hole. The portion of the semiconductor layer which overlaps the cavity portion as viewed in the lamination direction serves as the movable portion, and the through-hole is formed in the movable portion.

In a preferred embodiment, the sealing member seals the end of the through-hole on the obverse surface side of the semiconductor layer in the lamination direction.

In a preferred embodiment, the sealing member is made of a different material from the semiconductor layer.

In a preferred embodiment, the semiconductor layer is made of silicon, whereas the sealing member is made of silicon dioxide.

In a preferred embodiment, the pressure sensor further comprises an oxide film provided between the semiconductor layer and the semiconductor substrate.

In a preferred embodiment, the cavity portion is open at the reverse surface of the semiconductor substrate.

In a preferred embodiment, the piezoresistor is in the form of a strip including a bend.

In a preferred embodiment, the semiconductor substrate is provided with thirteen pairs of plate-like members projecting in the lamination direction and facing each other, and the movable portion and the cavity portion are sandwiched between the pair of plate-like members.

According to a sixth aspect of the present invention, there is provided a method for manufacturing a pressure sensor comprising a movable portion and a piezoresistor provided at the movable portion. The method comprises the steps of forming a semiconductor layer on an obverse surface side of a semiconductor substrate, forming a through-hole penetrating the semiconductor layer in a lamination direction and reaching the obverse surface of the semiconductor substrate, performing etching through the through-hole to form in the semiconductor substrate a cavity portion which is open at the obverse surface, and sealing the through-hole by filling a sealing member.

In a preferred embodiment, the semiconductor layer is made by using silicon, and the sealing member is made by using silicon dioxide.

In a preferred embodiment, the method further comprises the step of forming at a reverse surface of the semiconductor substrate an opening connected to the cavity portion.

In a preferred embodiment, the method further comprises the steps of forming a groove including a bend in the movable portion and forming a piezoresistor in the groove.

According to a seventh aspect of the present invention, there is provided a pressure sensor comprising a movable electrode and a fixed electrode arranged in parallel to each other. The pressure sensor further comprises a semiconductor substrate, a first insulating layer formed on the semiconductor substrate, a semiconductor layer formed on the semiconductor substrate with the first insulating layer intervening therebetween, a second insulating layer formed on the semiconductor layer, a first cavity portion formed in the semiconductor substrate, a second cavity portion overlapping the first cavity portion as viewed in a lamination direction and formed in contact with the second insulating layer. The fixed electrode faces the second insulating layer across the second cavity portion, and the movable electrode is provided at a portion of the semiconductor layer which is sandwiched between the first cavity portion and the second cavity portion.

In a preferred embodiment, the movable electrode includes a through-hole penetrating the semiconductor layer in the lamination direction, and the pressure sensor further comprises a sealing member which seals the through-hole.

In a preferred embodiment, the sealing member is made of a different material from the semiconductor layer.

In a preferred embodiment, the semiconductor layer is made of silicon, whereas the sealing member is made of silicon dioxide.

In a preferred embodiment, the pressure sensor further comprises a third insulating layer facing the second insulating layer across the second cavity portion. The fixed electrode is provided on the third insulating layer.

In a preferred embodiment, the pressure sensor further comprises a vent hole penetrating the fixed electrode in the lamination direction, and one end of the vent hole in the lamination direction reaches the second cavity portion.

In a preferred embodiment, the pressure sensor further comprises a movable electrode terminal electrically connected to the semiconductor layer.

In a preferred embodiment, the semiconductor substrate is provided with a pair of plate-like members projecting in the lamination direction and facing each other, and the movable electrode and the second cavity portion are sandwiched between the paired plate-like members.

In a preferred embodiment, the pressure sensor further comprises a protective layer formed on the paired plate-like members and including an opening which exposes the surface of at least one of the plate-like members, and a ground electrode terminal electrically connected to the semiconductor substrate via the opening.

According to an eighth embodiment of the present invention, there is provided a method for manufacturing a pressure sensor comprising a movable electrode and a fixed electrode arranged in parallel to each other. The method comprises the steps of forming a first insulating layer on a surface of a semiconductor substrate, forming a semiconductor layer on a surface of the first insulating layer, forming a recess in the semiconductor layer, forming a second insulating layer on a bottom surface of the recess, forming at a bottom of the recess a vent hole extending in a lamination direction and penetrating the second insulating layer, the semiconductor layer and

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the first insulating layer, performing etching through the vent hole to form a first cavity portion in the semiconductor substrate, sealing the through-hole, forming a sacrificial layer in the recess, forming a metal layer on the sacrificial layer, forming the fixed electrode from the metal layer, and removing the sacrificial layer to form a second cavity portion.

In a preferred embodiment, the method further comprises, between the step of forming a sacrificial layer in the recess and the step of forming a metal layer on the sacrificial layer, the steps of forming a third insulating layer on a surface of the sacrificial layer, and forming in the third insulating layer a through-hole penetrating in the lamination direction. The step of forming the fixed electrode from the metal layer comprises forming the fixed electrode to expose the through-hole. The step of removing the sacrificial layer to form a second cavity portion comprises etching the sacrificial layer through the through-hole.

In a preferred embodiment, the method for manufacturing a pressure sensor further comprises the step of forming a movable electrode terminal electrically connected to the semiconductor layer.

In a preferred embodiment, the method further comprises the step of processing the semiconductor substrate into a shape including a pair of plate-like members projecting from a surface in the lamination direction and facing each other. The step of forming a recess in the semiconductor layer comprises forming the recess in such a manner that the recess is sandwiched between the plate-like members in a direction in which the plate-like members face each other.

In a preferred embodiment, the step of processing into a shape including a pair of plate-like members comprises forming a protective layer to cover portions of the semiconductor substrate which correspond to the plate-like members as viewed in a lamination direction, and thinning in the lamination direction portions of the semiconductor substrate other than the portions covered with the protective layer. The method further comprises the steps of forming in the protective layer an opening which exposes part of the semiconductor substrate, and forming a ground electrode terminal electrically connected to the semiconductor substrate via the opening.

According to a ninth aspect of the present invention, there is provided a pressure sensor comprising a movable electrode and a fixed electrode arranged in parallel to each other. The pressure sensor further comprises a semiconductor substrate insulated from the movable electrode and supporting the movable electrode. The fixed electrode and the movable electrode face each other in an in-plane direction of the semiconductor substrate.

In a preferred embodiment, the movable electrode is made of a different material from the semiconductor substrate.

In a preferred embodiment, the fixed electrode is provided on a plate-like member projecting from the semiconductor substrate in a direction perpendicular to the in-plane direction.

In a preferred embodiment, the plate-like member comprises part of the semiconductor substrate.

In a preferred embodiment, the plate-like member is made of a same material as the movable electrode.

In a preferred embodiment, the pressure sensor further comprises, between the fixed electrode and the movable electrode in the in-plane direction, a closed space shut off from outside air.

In a preferred embodiment, the pressure sensor further comprises a wall portion standing from the semiconductor substrate. In the in-plane direction, the movable electrode is arranged between the wall portion and the fixed electrode

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such that the distance between the fixed electrode and the movable electrode is shorter than the distance between the movable electrode and the wall portion.

In a preferred embodiment, the wall portion comprises part of the semiconductor substrate.

In a preferred embodiment, the wall portion is made of a same material as the movable electrode.

In a preferred embodiment, the pressure sensor further comprises a gas supply space capable of taking in outside air. The gas supply space is provided between the movable electrode and the wall portion in the in-plane direction. The pressure sensor further comprises a closed space shut off from outside air. The closed space is provided between the fixed electrode and the movable electrode in the in-plane direction.

In a preferred embodiment, the pressure sensor further comprises a closed space shut off from outside air. The closed space is provided between the movable electrode and the wall portion in the in-plane direction. The pressure sensor further comprises a gas supply space capable of taking in outside air. The gas supply space is provided between the fixed electrode and the movable electrode in the in-plane direction.

In a preferred embodiment, the pressure sensor further comprises an additional movable electrode and an additional fixed electrode facing each other in the in-plane direction of the semiconductor substrate, and an additional wall portion standing from the semiconductor substrate. In the in-plane direction of the semiconductor substrate, the additional movable electrode is arranged between the additional wall portion and the additional fixed electrode such that the distance between the additional fixed electrode and the additional movable electrode is shorter than the distance between the additional movable electrode and the additional wall portion. An additional gas supply space capable of taking in outside air is provided between the additional movable electrode and the additional wall portion and between the additional fixed electrode and the additional movable electrode.

In a preferred embodiment, the pressure sensor further comprises an additional movable electrode and an additional fixed electrode facing each other in the in-plane direction of the semiconductor substrate, and an additional wall portion standing from the semiconductor substrate. In the in-plane direction of the semiconductor substrate, the additional movable electrode is arranged between the additional wall portion and the additional fixed electrode such that the distance between the additional fixed electrode and the additional movable electrode is shorter than the distance between the additional movable electrode and the additional wall portion. A closed space shut off from outside air is provided between the additional movable electrode and the additional wall portion and between the additional fixed electrode and the additional movable electrode.

In a preferred embodiment, the additional wall portion comprises part of the semiconductor substrate.

In a preferred embodiment, the wall portion, the additional movable electrode and the additional wall portion are made of a same material as the movable electrode.

In a preferred embodiment, the direction in which the additional movable electrode and the additional fixed electrode face each other is same as the direction in which the movable electrode and the fixed electrode face each other.

More preferably, the wall portion and the additional wall portion face each other in the direction in which the movable electrode and the fixed electrode face each other.

According to a tenth aspect of the present invention, there is provided a method for manufacturing a pressure sensor comprising a movable electrode and a fixed electrode arranged in parallel to each other. The method comprises the

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steps of performing etching in a first direction with respect to a semiconductor material, forming a fixed electrode including an electrode surface perpendicular to a second direction crossing the first direction at right angles, and forming a movable electrode including an electrode surface facing the electrode surface of the fixed electrode in the second direction.

In a preferred embodiment, the step of forming a movable electrode comprises forming a semiconductor layer on a remaining portion of the semiconductor material and performing etching in the first direction with respect to the semiconductor layer. The movable electrode is formed as a remaining portion of the semiconductor layer.

In a preferred embodiment, the fixed electrode is formed as a remaining portion of the semiconductor material in the step of performing etching with respect to the semiconductor material.

In another preferred embodiment, the fixed electrode is formed as a remaining portion of the semiconductor layer in the step of performing etching with respect to the semiconductor layer.

In a preferred embodiment, the step of performing etching with respect to the semiconductor material comprises forming a wall portion including a side surface facing the electrode surface of the fixed electrode in the second direction, as a remaining portion of the semiconductor material. The step of forming a movable electrode comprises forming a movable electrode between the wall portion and the fixed electrode in the second direction at a position closer to the fixed electrode than to the wall portion.

In another preferred embodiment, the semiconductor material comprises a semiconductor substrate and a semiconductor layer formed on the semiconductor substrate. The step of performing etching with respect to the semiconductor material comprises performing etching with respect to the semiconductor layer to form the fixed electrode and the movable electrode as a remaining portion of the semiconductor layer.

In a preferred embodiment, the step of performing etching with respect to the semiconductor material comprises forming a wall portion including a side surface facing the electrode surface of the fixed electrode in the second direction, as a remaining portion of the semiconductor layer. The movable electrode is formed between the wall portion and the fixed electrode in the second direction at a position closer to the fixed electrode than to the wall portion.

Other features and advantages of the present invention will become more apparent from the detailed description given below with reference to the accompanying drawings.

#### BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a plan view showing a pressure sensor according to a first embodiment of the present invention;

FIG. 2 is a sectional view taken along lines II-II in FIG. 1;

FIG. 3 is a sectional view showing a step of a method for manufacturing the pressure sensor shown in FIG. 2;

FIG. 4 is a sectional view showing a step subsequent to the step of FIG. 3;

FIG. 5 is a sectional view showing a step subsequent to the step of FIG. 4;

FIG. 6 is a sectional view showing a step subsequent to the step of FIG. 5;

FIG. 7 is a sectional view showing a step subsequent to the step of FIG. 6;

FIG. 8 is a sectional view showing a step subsequent to the step of FIG. 7;

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FIG. 9 is a sectional view showing a step subsequent to the step of FIG. 8

FIG. 10 is a sectional view showing a step subsequent to the step of FIG. 9;

FIG. 11 is a sectional view showing a step subsequent to the step of FIG. 10;

FIG. 12 is a sectional view showing a step subsequent to the step of FIG. 11;

FIG. 13 is a sectional view showing a step subsequent to the step of FIG. 12;

FIG. 14 is a sectional view showing a step subsequent to the step of FIG. 13;

FIG. 15 is a sectional view showing a step subsequent to the step of FIG. 14;

FIG. 16 is a sectional view showing a step subsequent to the step of FIG. 15;

FIG. 17 is a sectional view showing a step subsequent to the step of FIG. 16;

FIG. 18 is a sectional view showing a step subsequent to the step of FIG. 17;

FIG. 19 is a plan view showing a pressure sensor according to a second embodiment of the present invention;

FIG. 20 is a sectional view taken along lines XX-XX in FIG. 19;

FIG. 21 is a sectional view showing a step of a method for manufacturing the pressure sensor shown in FIG. 20;

FIG. 22 is a sectional view showing a step subsequent to the step of FIG. 21;

FIG. 23 is a sectional view showing a step subsequent to the step of FIG. 22;

FIG. 24 is a sectional view showing a step subsequent to the step of FIG. 23;

FIG. 25 is a sectional view showing a step subsequent to the step of FIG. 24;

FIG. 26 is a sectional view showing a step subsequent to the step of FIG. 25;

FIG. 27 is a sectional view showing a step subsequent to the step of FIG. 26;

FIG. 28 is a sectional view showing a step subsequent to the step of FIG. 27;

FIG. 29 is a sectional view showing a step subsequent to the step of FIG. 28;

FIG. 30 is a sectional view showing a step subsequent to the step of FIG. 29;

FIG. 31 is a sectional view showing a step subsequent to the step of FIG. 30;

FIG. 32 is a sectional view showing a step subsequent to the step of FIG. 31;

FIG. 33 is a sectional view showing a step subsequent to the step of FIG. 32;

FIG. 34 is a sectional view showing a step subsequent to the step of FIG. 33;

FIG. 35 is a sectional view showing a step subsequent to the step of FIG. 34;

FIG. 36 is a plan view showing a pressure sensor according to a third embodiment of the present invention;

FIG. 37 is a sectional view taken along lines XXXVII-XXXVII in FIG. 36;

FIG. 38 is a sectional view showing a step of a method for manufacturing the pressure sensor shown in FIG. 37;

FIG. 39 is a sectional view showing a step subsequent to the step of FIG. 38;

FIG. 40 is a sectional view showing a step subsequent to the step of FIG. 39;

FIG. 41 is a sectional view showing a step subsequent to the step of FIG. 40;

FIG. 42 is a sectional view showing a step subsequent to the step of FIG. 41;

FIG. 43 is a sectional view showing a step subsequent to the step of FIG. 42;

FIG. 44 is a sectional view showing a step subsequent to the step of FIG. 43;

FIG. 45 is a sectional view showing a step subsequent to the step of FIG. 44;

FIG. 46 is a sectional view showing a step subsequent to the step of FIG. 45;

FIG. 47 is a sectional view showing a step subsequent to the step of FIG. 46;

FIG. 48 is a sectional view showing a step subsequent to the step of FIG. 47;

FIG. 49 is a sectional view showing a step subsequent to the step of FIG. 48;

FIG. 50 is a sectional view showing a step subsequent to the step of FIG. 49;

FIG. 51 is a sectional view showing a step subsequent to the step of FIG. 50;

FIG. 52 is a sectional view showing a step subsequent to the step of FIG. 51;

FIG. 53 is a sectional view showing a step subsequent to the step of FIG. 52;

FIG. 54 is a plan view showing a pressure sensor according to a fourth embodiment of the present invention;

FIG. 55 is a sectional view taken along lines LV-LV in FIG. 54;

FIG. 56 is a sectional view showing a step of a method for manufacturing the pressure sensor shown in FIG. 55;

FIG. 57 is a plan view showing a step subsequent to the step of FIG. 56;

FIG. 58 is a sectional view taken along lines LVIII-LVIII in FIG. 57;

FIG. 59 is a sectional view showing a step subsequent to the step of FIG. 58;

FIG. 60 is a sectional view showing a step subsequent to the step of FIG. 59;

FIG. 61 is a sectional view showing a step subsequent to the step of FIG. 60;

FIG. 62 is a plan view showing a step subsequent to the step of FIG. 61;

FIG. 63 is a sectional view taken along lines LXIII-LXIII in FIG. 62;

FIG. 64 is a sectional view showing a step subsequent to the step of FIG. 63;

FIG. 65 is a sectional view showing a step subsequent to the step of FIG. 64;

FIG. 66 is a plan view showing a step subsequent to the step of FIG. 65;

FIG. 67 is a sectional view taken along lines LXVII-LXVII in FIG. 66;

FIG. 68 is a plan view showing a step subsequent to the step of FIG. 67;

FIG. 69 is a sectional view taken along lines LXIX-LXIX in FIG. 68;

FIG. 70 is a plan view showing a pressure sensor according to a fifth embodiment of the present invention;

FIG. 71 is a sectional view taken along lines LXXI-LXXI in FIG. 70;

FIG. 72 is a plan view showing a step of a method for manufacturing the pressure sensor shown in FIG. 70;

FIG. 73 is a sectional view taken along lines LXXIII-LXXIII in FIG. 72;

FIG. 74 is a sectional view showing a pressure sensor according to a sixth embodiment of the present invention;

FIG. 75 is a plan view showing a pressure sensor according to a seventh embodiment of the present invention;

FIG. 76 is a sectional view taken along lines LXXVI-LXXVI in FIG. 75;

FIG. 77 is a plan view showing a step of a method for manufacturing the pressure sensor shown in FIG. 75;

FIG. 78 is a sectional view taken along lines LXXVIII-LXXVIII in FIG. 77;

FIG. 79 is a sectional view showing a step subsequent to the step of FIG. 78;

FIG. 80 is a sectional view showing a step subsequent to the step of FIG. 79;

FIG. 81 is a sectional view showing a step subsequent to the step of FIG. 80;

FIG. 82 is a plan view showing a step subsequent to the step of FIG. 81;

FIG. 83 is a sectional view taken along lines LXXXIII-LXXXIII in FIG. 82;

FIG. 84 is a plan view showing a step subsequent to the step of FIG. 82;

FIG. 85 is a sectional view taken along lines LXXXV-LXXXV in FIG. 84;

FIG. 86 is a plan view showing a pressure sensor according to an eighth embodiment of the present invention;

FIG. 87 is a sectional view taken along lines LXXXVII-LXXXVII in FIG. 86;

FIG. 88 is a sectional view showing a step subsequent to the step of FIG. 87;

FIG. 89 is a plan view showing a step subsequent to the step of FIG. 88;

FIG. 90 is a sectional view taken along lines XC-XC in FIG. 89;

FIG. 91 is a sectional view showing a step subsequent to the step of FIG. 90;

FIG. 92 is a sectional view showing a step subsequent to the step of FIG. 91;

FIG. 93 is a plan view showing a step subsequent to the step of FIG. 92;

FIG. 94 is a sectional view taken along lines XCIV-XCIV in FIG. 93;

FIG. 95 is a sectional view showing a step subsequent to the step of FIG. 94;

FIG. 96 is a sectional view showing a step subsequent to the step of FIG. 95;

FIG. 97 is a sectional view showing a step subsequent to the step of FIG. 96;

FIG. 98 is a sectional view showing a step subsequent to the step of FIG. 97;

FIG. 99 is a sectional view showing a step subsequent to the step of FIG. 98;

FIG. 100 is a sectional view showing a step subsequent to the step of FIG. 99;

FIG. 101 is a sectional view showing a step subsequent to the step of FIG. 100;

FIG. 102 is a plan view showing a step subsequent to the step of FIG. 101;

FIG. 103 is a sectional view taken along lines CIII-CIII in FIG. 102;

FIG. 104 is a sectional view showing a step subsequent to the step of FIG. 103;

FIG. 105 is a plan view showing a step subsequent to the step of FIG. 104;

FIG. 106 is a sectional view taken along lines CVI-CVI in FIG. 105;

FIG. 107 is a sectional view showing a pressure sensor according to a ninth embodiment of the present invention;

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FIG. 108 is a sectional view showing a pressure sensor according to a tenth embodiment of the present invention;

FIG. 109 is a plan view showing a pressure sensor according to an eleventh embodiment of the present invention;

FIG. 110 is a sectional view taken along lines CX-CX in FIG. 109;

FIG. 111 is a plan view showing a step of a method for manufacturing the pressure sensor shown in FIG. 110;

FIG. 112 is a sectional view taken along lines CXII-CXII in FIG. 111;

FIG. 113 is a sectional view showing a step subsequent to the step of FIG. 112;

FIG. 114 is a sectional view showing a step subsequent to the step of FIG. 113;

FIG. 115 is a sectional view showing a step subsequent to the step of FIG. 114;

FIG. 116 is a sectional view showing a step subsequent to the step of FIG. 115;

FIG. 117 is a sectional view showing a step subsequent to the step of FIG. 116;

FIG. 118 is a sectional view taken along lines CXVIII-CXVIII in FIG. 117;

FIG. 119 is a sectional view showing the state after the steps shown in FIGS. 91-101 are performed after the step of FIG. 118;

FIG. 120 is a plan view showing a step performed after the state of FIG. 119 is obtained;

FIG. 121 is a sectional view taken along lines CXXI-CXXI in FIG. 120;

FIG. 122 is a sectional view showing a step subsequent to the step of FIG. 121;

FIG. 123 is a plan view showing a step subsequent to the step of FIG. 122;

FIG. 124 is a sectional view taken along lines CXXIV-CXXIV in FIG. 123;

FIG. 125 is a plan view showing a pressure sensor according to a twelfth embodiment of the present invention;

FIG. 126 is a sectional view taken along lines CXXVI-CXXVI in FIG. 125;

FIG. 127 is a plan view showing a step of a method for manufacturing the pressure sensor shown in FIG. 126;

FIG. 128 is a sectional view taken along lines CXXVIII-CXXVIII in FIG. 127;

FIG. 129 is a sectional view showing a step subsequent to the step of FIG. 128;

FIG. 130 is a sectional view showing a step subsequent to the step of FIG. 129;

FIG. 131 is a sectional view showing a step subsequent to the step of FIG. 130;

FIG. 132 is a sectional view showing a step subsequent to the step of FIG. 131;

FIG. 133 is a plan view showing a step subsequent to the step of FIG. 132;

FIG. 134 is a sectional view taken along lines CXXXIV-CXXXIV in FIG. 133;

FIG. 135 is a sectional view showing a step subsequent to the step of FIG. 134;

FIG. 136 is a sectional view showing a step subsequent to the step of FIG. 135;

FIG. 137 is a sectional view showing a step subsequent to the step of FIG. 136;

FIG. 138 is a sectional view showing a step subsequent to the step of FIG. 137;

FIG. 139 is a plan view showing a step subsequent to the step of FIG. 138;

FIG. 140 is a sectional view taken along lines CXL-CXL in FIG. 139;

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FIG. 141 is a sectional view showing a step subsequent to the step of FIG. 140;

FIG. 142 is a sectional view showing a step subsequent to the step of FIG. 141;

FIG. 143 is a sectional view taken along lines CXLIII-CXLIII in FIG. 142;

FIG. 144 is a sectional view showing a step subsequent to the step of FIG. 143;

FIG. 145 is a sectional view showing a step subsequent to the step of FIG. 144;

FIG. 146 is a plan view showing a pressure sensor according to a thirteenth embodiment of the present invention;

FIG. 147 is a sectional view taken along lines CXLVII-CXLVII in FIG. 146;

FIG. 148 is a sectional view showing a pressure sensor according to a thirteenth embodiment of the present invention;

FIG. 149 is a sectional view showing a step of a method for manufacturing the pressure sensor shown in FIG. 148;

FIG. 150 is a sectional view showing a pressure sensor according to a fifteenth embodiment of the present invention;

FIG. 151 is a sectional view showing a semiconductor material for the pressure sensor shown in FIG. 150;

FIG. 152 is a plan view showing a step of a method for manufacturing the pressure sensor shown in FIG. 150;

FIG. 153 is a sectional view taken along lines CLIII-CLIII in FIG. 152;

FIG. 154 is a sectional view showing an example of a method for manufacturing a conventional pressure sensor; and

FIG. 155 is a sectional view showing an example of a conventional pressure sensor.

#### BEST MODE FOR CARRYING OUT THE INVENTION

Preferred embodiments of the present invention are described below with reference to the accompanying drawings.

FIGS. 1 and 2 show a pressure sensor according to a first embodiment of the present invention. The pressure sensor 1 of this embodiment comprises a semiconductor substrate 10, and an insulating layer 20 and a semiconductor layer 30 formed on the semiconductor substrate. The pressure sensor is provided with a cavity portion 13, a movable portion 31 and electrodes 51, 52.

The semiconductor substrate 10 is e.g. a single-crystal silicon (Si) substrate and has a recess 11 extending inward in the lamination direction (vertical direction in FIG. 2) at the center. The cavity portion 13 is defined in the recess 11. The cavity portion 13 is in a vacuum state. The dimension of the cavity portion 13 in the vertical direction is e.g. 1 to 5  $\mu\text{m}$ , and that in the horizontal direction is e.g. 100 to 500  $\mu\text{m}$ .

The semiconductor layer 30 is made of e.g. polycrystalline silicon. The semiconductor layer 30 has a thickness of e.g. 2 to 10  $\mu\text{m}$ . The semiconductor layer 30 is formed over the substantially entire surface of the semiconductor substrate 10, except the right end in FIG. 2. It is to be noted that the semiconductor layer 30 is not provided at portions corresponding to vent holes formed in the manufacturing process, which will be described later.

The insulating layer 20 is made of e.g. silicon dioxide ( $\text{SiO}_2$ ). The insulating layer 20 is made up of insulating layers 21, 22, 23, 27, which are made in different steps in the manufacturing process, as will be described later.

The insulating layer 21 provides insulation between the semiconductor layer 30 and the semiconductor substrate 10 at

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portions where the recess 11 is not formed. The thickness of the insulating layer 21 is e.g. 0.3 to 2.0  $\mu\text{m}$ . The insulating layer 22 covers the surface of the recess 11. The thickness of the insulating layer 22 is e.g. 0.3 to 2.0  $\mu\text{m}$ . The insulating layer 23 covers the lower surface of the semiconductor layer 30 which faces the cavity portion 13. The thickness of the insulating layer 23 is e.g. 0.3 to 2.0  $\mu\text{m}$ . The insulating layer 27 covers the semiconductor layer 30 and the right end in FIG. 2 of the surface of the semiconductor substrate 10. The thickness of the insulating layer 27 on the semiconductor layer 30 is e.g. 0.3 to 2.0  $\mu\text{m}$ . The insulating layer 27 includes a plurality of sealing portions 27a which seal the portions corresponding to vent holes 13A formed in the manufacturing process, which will be described later. The sealing portions 27a are concave relative to the surrounding portions. The sealing portions 27a can be made flat by performing CMP (chemical mechanical polishing). The insulating layer 27 has a through-hole 27b penetrating in the lamination direction at the left end in FIG. 27 and a through-hole 27c penetrating in the lamination direction at the right end in FIG. 27.

The electrode 51 is formed to be electrically connected to the semiconductor layer 30 via the through-hole 27b. The electrode 52 is formed to be electrically connected to the semiconductor substrate 10 via the through-hole 27c.

The movable portion 31 comprises a portion of the semiconductor layer 30 which overlaps the cavity portion 13 in the lamination direction, and the insulating layers 23, 27 on and under this portion of the semiconductor layer. The movable portion 31 is movable up and down in the lamination direction.

A method for manufacturing the pressure sensor 1 is described below with reference to FIGS. 3-18.

First, a semiconductor substrate 10 made of single-crystal silicon is prepared. Specifically, a semiconductor substrate 10 having a thickness of 300 to 700  $\mu\text{m}$  is prepared. In the next step, as shown in FIG. 3, an insulating layer 21 of  $\text{SiO}_2$  is formed on the surface of the semiconductor substrate 10. This step can be performed by thermally oxidizing the surface of the semiconductor substrate 10.

In the next step, as shown in FIG. 4, an opening 21a for exposing the surface of the semiconductor substrate 10 is formed in the insulating layer 21. This step is performed by providing a resist of resin which exposes the portion where the opening 21a is to be formed and performing wet etching using aqueous solution of hydrogen fluoride.

In the next step, a recess 11 is formed in the semiconductor substrate 10, as shown in FIG. 5. This step can be performed by gas-phase etching using gas containing atomic fluorine (F). F reacts with silicon (Si) but does not react with  $\text{SiO}_2$ . Thus, the insulating layer 21 is not etched away, but the semiconductor substrate 10 is etched away at the portion exposed through the opening 21a, whereby the recess 11 is formed. In this step, by adjusting the time of dry etching, the recess 11 of a desired depth can be formed. The gas containing F can be obtained by decomposing carbon tetrafluoride ( $\text{CF}_4$ ) gas or sulfur hexafluoride ( $\text{SF}_6$ ) gas by discharge.

In the next step, an insulating layer 22 is formed, as shown in FIG. 6. This step can be performed by thermally oxidizing the surface of the recess 11.

In the next step, as shown in FIG. 7, a sacrificial layer 12 is formed in the recess 11. The sacrificial layer 12 is a layer of polycrystalline silicon. This step is performed by e.g. embedding polycrystalline silicon in the recess 11. The polycrystalline silicon to be embedded in the recess 11 is processed in advance such that the surface of the sacrificial layer 12 is flush with the surface of the insulating layer 21. Alternatively, the polycrystalline silicon may be abraded after being embedded

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in the recess such that the surface of the sacrificial layer 12 is flush with the surface of the insulating layer 21.

In the next step, an insulating layer 23 of  $\text{SiO}_2$  is formed, as shown in FIG. 8. This step can be performed by thermally oxidizing the surface of the sacrificial layer 12.

In the next step, a semiconductor layer 30 is formed, as shown in FIG. 9. This step can be performed by causing polycrystalline silicon to grow on the surfaces of the insulating layer 21, 23 by e.g. chemical vapor deposition (CVD).

In the next step, an insulating layer 24 of  $\text{SiO}_2$  is formed on the surface of the semiconductor layer 30, as shown in FIG. 10. For instance, this step can be performed by thermally oxidizing the surface of the semiconductor layer 30.

In the next step, a plurality of through-holes 24a are formed in the insulating layer 24, as shown in FIG. 11. At the same time, in this step, the right end in the figure of the insulating layer 24 is removed to expose the right end of the semiconductor layer 30. This step can be performed by gas-phase etching using the reaction between fluorine-containing molecular ions ( $\text{HF}_2^-$ ) and  $\text{SiO}_2$ .  $\text{HF}_2^-$  can be obtained by reacting hydrogen fluoride (HF) with water vapor. HF can be obtained by reacting F or molecular fluorine ( $\text{F}_2$ ), which is obtained by e.g. decomposing  $\text{CF}_4$  gas or  $\text{SF}_6$  gas, with water vapor. Since Si which is not oxidized does not easily react with  $\text{HF}_2^-$ , the semiconductor layer 30 is not removed by the etching and hence remains.

In the next step, as shown in FIG. 12, a plurality of through-holes 30a are formed in the semiconductor layer 30 so that each of the through-holes 30a is connected to a respective one of the through-holes 24a at the upper end and reaches the insulating layer 23 at the lower end. This step can be performed by gas-phase etching using gas containing HF. The gas containing HF can be prepared by e.g. decomposing by discharge a gas obtained by adding water vapor to  $\text{CF}_4$  gas or  $\text{SF}_6$  gas. By performing etching while keeping HF in a dry state and suppressing generation of  $\text{HF}_2^-$ ,  $\text{SiO}_2$  is prevented from being etched away. In this step, therefore, the insulating layers 23 and 24 remain. Further, in this step, the right end of the semiconductor layer 30 is removed, so that the insulating layer 21b, which is the right end portion of the insulating layer 21, is exposed.

In the next step, insulating layers 25 and 26 of  $\text{SiO}_2$  are formed, as shown in FIG. 13. The insulating layer 25 is formed on the inner circumferential surface of each of the through-holes 30a. The insulating layer 26 is formed on the semiconductor layer 30 at the portion that is not covered with the insulating layer 21, 24. This step is performed by thermally oxidizing the portion of the semiconductor layer 30 which is not covered with the insulating layer 21, 24.

In the next step, a resist 40 is applied, as shown in FIG. 14. The resist 40 is made of e.g. resin and covers the insulating layer 24 and the insulating layer 21b but does not cover the through-holes 24a. This step is performed by applying liquefied resin to the surfaces of the insulating layer 24 and the insulating layer 21b.

In the next step, vent holes 13A are formed, as shown in FIG. 15. The vent holes 13A are made by forming through-holes 23a in the insulating layer 23 such that each of the through-holes 23a is connected to one of the through-holes 24a and one of the through-hole 30a. This step can be performed by gas-phase etching using the reaction between  $\text{HF}_2^-$  and  $\text{SiO}_2$ . In this step, after the vent holes 13A are formed, the resist 40 is removed.

In the next step, a cavity portion 13 is formed by removing the sacrificial layer 12, as shown in FIG. 16. The removal of the sacrificial layer 12 is performed by gas-phase etching, i.e., sending gas containing F to the sacrificial layer 12 through the

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vent holes 13A. F can be obtained by e.g. decomposing  $\text{CF}_4$  gas or  $\text{SF}_6$  gas. Since F does not easily react with  $\text{SiO}_2$ , the insulating layers 21, 22, 23, 24, 25, 26 remain in this step, and the semiconductor substrate 10 and the semiconductor layer 30 protected by these insulating layers also remain. By forming the cavity portion 13 in this way, the portion of the semiconductor layer 30 which overlaps the cavity portion 13 as viewed in the lamination direction and the insulating layers 23, 24 on and under this portion become the movable portion 31.

In the next step, an insulating layer 27 and sealing portions 27a are formed, as shown in FIG. 17. In this step, for instance, plasma CVD is performed in a vacuum atmosphere. In this step,  $\text{SiO}_2$  is further deposited on the insulating layers 21b, 24, 25, 26. As a result of deposition of  $\text{SiO}_2$  on the insulating layer 25, the vent holes 13A are sealed to become sealing portions 27a. As a result of deposition of  $\text{SiO}_2$  on the insulating layers 21b, 24, 26, the insulating layer 27 is provided.

In the next step, through-holes 27b and 27c are formed, as shown in FIG. 18. Specifically, the through-holes 27b and 27c are formed by providing a resist of resin such that the portions where the through-holes 27b and 27c are to be formed are exposed and performing wet etching using aqueous solution of hydrogen fluoride or gas-phase etching using the reaction between  $\text{HF}_2^-$  and  $\text{SiO}_2$ . The through-hole 27b reaches the semiconductor layer 30, and the through-hole 27c reaches the semiconductor substrate 10.

After the above-described steps, electrodes 51 and 52 are provided, whereby the pressure sensor 1 shown in FIGS. 1 and 2 is completed. For instance, the electrodes 51 and 52 are provided by forming an aluminum (Al) layer in the through-holes 27b, 27c and on the insulating layer 27 and removing unnecessary portions of the Al layer by etching.

The operation and advantages of the pressure sensor 1 are described below.

According to this embodiment, when the movable portion 31 moves up and down, the capacitance between the semiconductor substrate 10 and the semiconductor layer 30 changes. The pressure sensor 1 detects such changes in capacitance between the semiconductor substrate 10 and the semiconductor layer 30 to detect changes in pressure applied to the movable portion 31. Since the cavity portion 13 is in a vacuum state, the pressure sensor 1 is suitable for measuring e.g. the absolute pressure applied to the movable portion 31.

According to the present invention, the cavity portion 13 is surrounded by the insulating layers 22 and 23. Thus, in the pressure sensor 1, the capacitance between the semiconductor substrate 10 and the semiconductor layer 30 is relatively large. A larger capacitance between the semiconductor substrate 10 and the semiconductor layer 30 allows more sensitive detection of changes in the capacitance. Thus, the pressure sensor 1 ensures more precise pressure measurement.

Further, according to this embodiment, the recess 11 is formed by etching, and the bottom of the recess 11 is made parallel to the surface of the semiconductor substrate 10. Further, the semiconductor layer 30 is formed on the insulating layer 21 formed by oxidizing the surface of the semiconductor substrate 10 and on the insulating layer 23 formed to conform to the insulating substrate 21. Accordingly, in the pressure sensor 1, the bottom surface of the recess 11 and the semiconductor layer 30 are parallel to each other, with the cavity portion 13 intervening between them. This arrangement allows the capacitance between the semiconductor substrate 10 and the semiconductor layer 30 to be set precisely to a predetermined value. Thus, the pressure sensor 1 ensures more precise pressure measurement.

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Moreover, according to the above-described manufacturing method, the pressure sensor 1 is produced from a single semiconductor substrate 10. Thus, the pressure sensor 1 realizes a simple manufacturing process and a low manufacturing cost.

Moreover, according to the above-described manufacturing method, the recess 11 having a desired depth can be made easily by adjusting the etching time, so that the dimension in the vertical direction of the cavity portion 13 can be set to a desirable value. Further, according to this manufacturing method, the thickness of the semiconductor layer 30 can be adjusted properly by adjusting the time period for performing CVD, so that the thickness of the semiconductor layer 30 can be set to a desired value.

In this embodiment, the recess 11 is formed by etching the semiconductor substrate 10. However, unlike this, the recess 11 may be formed by allowing single-crystal silicon to grow on portions of the semiconductor substrate 10 other than the center portion. The sealing of the vent holes 13A can be performed by a LP-CVD method.

FIGS. 19 and 20 show a pressure sensor according to a second embodiment of the present invention. The pressure sensor 2 of this embodiment is made up of a semiconductor substrate 10, and an insulating layer 20 and a semiconductor layer 30 formed on the semiconductor substrate. The pressure sensor is provided with a cavity portion 13, a movable portion 31 and electrodes 51, 52.

The semiconductor substrate 10 is e.g. a single-crystal silicon (Si) substrate. The center of the surface of the semiconductor substrate 10 is thermally oxidized to be formed with an insulating layer 22. The insulating layer 22 has a thickness of e.g. 0.3 to 1  $\mu\text{m}$ .

The semiconductor layer 30 is made of e.g. polycrystalline silicon (Si) and formed on the semiconductor substrate 10, with the insulating layer 21 or 23, which will be described later, intervening between them. The semiconductor layer 30 has a thickness of e.g. 2 to 10  $\mu\text{m}$ . The semiconductor layer 30 is formed over the substantially entire surface of the semiconductor substrate 10, except the right end in FIG. 20. It is to be noted that the semiconductor layer 30 is not provided at portions corresponding to vent holes 13A formed in the manufacturing process, which will be described below.

The insulating layer 20 is made of e.g. silicon dioxide ( $\text{SiO}_2$ ). The insulating layer 20 is made up of insulating layers 21, 22, 23, 27, which are made in different steps in the manufacturing process as will be described later, and has a vacuum cavity portion 13 in it. As noted before, the insulating layer 22 is provided on the surface of the semiconductor substrate 10.

The insulating layer 21 provides insulation between the semiconductor substrate 10 and the semiconductor layer 30. The insulating layer 21 is not provided on the semiconductor layer 10 at the portion where the insulating layer 22 is provided. The thickness of the insulating layer 21 is e.g. 1 to 2  $\mu\text{m}$ . The insulating layer 23 is provided on the lower surface of the semiconductor layer 30 to cover the portions of the lower surface which are not in contact with the insulating layer 21. The thickness of the insulating layer 23 is e.g. 0.3 to 0.5  $\mu\text{m}$ . The cavity portion 13 is in the form of a rectangular parallelepiped and provided inside the insulating layer 21 to be sandwiched between the semiconductor layers 22 and 23 in the vertical direction. The dimension of the cavity portion 13 in the vertical direction is e.g. 1 to 1.7  $\mu\text{m}$ , and that in the horizontal direction is e.g. 300 to 500  $\mu\text{m}$ . The insulating layer 27 covers the semiconductor layer 30 and the right end in FIG. 20 of the semiconductor substrate 10. The thickness of the insulating layer 27 on the semiconductor layer 30 is e.g. 0.3 to 0.5  $\mu\text{m}$ . The insulating layer 27 includes a plurality of

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sealing portions **27a** which seal the portions corresponding to vent holes **13A** formed in the manufacturing process, which will be described later. The sealing portions **27a** are formed to be concave relative to the surrounding portions. The sealing portions **27a** can be made flat by CMP. The insulating layer **27** includes a through-hole **27b** penetrating in the lamination direction at the left end in FIG. **27** and a through-hole **27c** penetrating in the lamination direction at the right end in FIG. **27**.

The electrode **51** is formed to be electrically connected to the semiconductor layer **30** via the through-hole **27b**. The electrode **52** is formed to be electrically connected to the semiconductor substrate **10** via the through-hole **27c**.

The movable portion **31** comprises a portion of the semiconductor layer **30** which overlaps the cavity portion **13** in the lamination direction, and portions of the insulating layers **23**, **27** on and under this portion of the semiconductor layer. The movable portion **31** is movable up and down in the lamination direction.

A method for manufacturing the pressure sensor **2** is described below with reference to FIGS. **21-35**.

First, a semiconductor substrate **10** made of single-crystal silicon is prepared. Specifically, a semiconductor substrate **10** having a thickness of 300 to 700  $\mu\text{m}$  is prepared. In the next step, as shown in FIG. **21**, an insulating layer **21** of  $\text{SiO}_2$  is formed on the surface of the semiconductor substrate **10**. This step can be performed by thermally oxidizing the upper surface of the semiconductor substrate **10**. In this step, the upper surface of the semiconductor substrate **10** can be heated uniformly so that the thickness of the insulating layer **21** is uniform. Moreover, in this step, the thickness of the insulating layer **21** can be adjusted appropriately by adjusting the heating time.

In the next step, as shown in FIG. **22**, an opening **21a** for exposing the surface of the semiconductor substrate **10** is formed in the insulating layer **21**. This step is performed by providing a resist of resin which exposes the portion where the opening **21a** is to be formed and performing wet etching using aqueous solution of hydrogen fluoride. Alternatively, this step can be performed by gas-phase etching using the reaction between fluorine-containing molecular ions ( $\text{HF}_2^-$ ) and  $\text{SiO}_2$ .  $\text{HF}_2^-$  can be obtained by reacting hydrogen fluoride (HF) with water vapor. HF can be obtained by reacting F or molecular fluorine ( $\text{F}_2$ ), which is obtained by e.g. decomposing by discharge carbon tetrafluoride ( $\text{CF}_4$ ) gas or sulfur hexafluoride ( $\text{SF}_6$ ) gas, with water vapor. Since Si which is not oxidized does not easily react with  $\text{HF}_2^-$ , the semiconductor substrate **10** is not removed by the etching.

In the next step, an insulating layer **22** is formed, as shown in FIG. **23**. This step can be performed by thermally oxidizing the portion of the semiconductor substrate **10** which is exposed through the opening **21a**.

In the next step, as shown in FIG. **24**, a sacrificial layer **12** is formed. The sacrificial layer **12** is a layer of polycrystalline silicon. This step is performed by e.g. embedding polycrystalline silicon in the opening **21a**. The polycrystalline silicon to be embedded in the opening **21a** is processed in advance such that the surface of the sacrificial layer **12** is flush with the surface of the insulating layer **21**.

In the next step, as shown in FIG. **25**, an insulating layer **23** of  $\text{SiO}_2$  is formed. This step can be performed by thermally oxidizing the surface of the sacrificial layer **12**. By this step, the sacrificial layer **12** is enclosed by the insulating layers **21**, **22**, **23**.

In the next step, a semiconductor layer **30** is formed, as shown in FIG. **26**. This step can be performed by causing

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polycrystalline silicon to grow on the surfaces of the insulating layer **21**, **23** by e.g. chemical vapor deposition (CVD).

In the next step, as shown in FIG. **27**, an insulating layer **24** of  $\text{SiO}_2$  is formed on the surface of the semiconductor layer **30**. This step can be performed by thermally oxidizing the surface of the semiconductor layer **30**.

In the next step, a plurality of through-holes **24a** are formed in the insulating layer **24**, as shown in FIG. **28**. At the same time, in this step, the right end in the figure of the insulating layer **24** is removed to expose the right end of the semiconductor layer **30**. This step can be performed by gas-phase etching using the reaction between fluorine-containing molecular ions ( $\text{HF}_2^-$ ) and  $\text{SiO}_2$ .  $\text{HF}_2^-$  can be obtained by reacting hydrogen fluoride (HF) with water vapor. HF can be obtained by reacting atomic fluorine (F) or molecular fluorine ( $\text{F}_2$ ), which is obtained by e.g. decomposing  $\text{CF}_4$  gas or  $\text{SF}_6$  gas, with water vapor. Since Si which is not oxidized does not easily react with  $\text{HF}_2^-$ , the semiconductor layer **30** is not removed by the etching and hence remains.

In the next step, as shown in FIG. **29**, a plurality of through-holes **30a** are formed in the semiconductor layer **30** so that each of the through-holes **30a** is connected to a respective one of the through-holes **24a** at the upper end and reaches the insulating layer **23** at the lower end. This step can be performed by gas-phase etching using gas containing HF. The gas containing HF can be prepared by e.g. decomposing by discharge a gas obtained by adding water vapor to  $\text{CF}_4$  gas or  $\text{SF}_6$  gas. By performing etching while keeping HF in a dry state and suppressing generation of  $\text{HF}_2^-$ ,  $\text{SiO}_2$  is prevented from being etched away. In this step, therefore, the insulating layers **23** and **24** remain. Further, in this step, the right end of the semiconductor layer **30** is removed, so that the insulating layer **21b**, which is the right end portion of the insulating layer **21**, is exposed.

In the next step, insulating layers **25** and **26** of  $\text{SiO}_2$  are formed, as shown in FIG. **30**. The insulating layer **25** is formed on the inner circumferential surface of each of the through-holes **30a**. The insulating layer **26** is formed on the semiconductor layer **30** at the portion that is not covered with the insulating layers **21**, **24**. This step is performed by thermally oxidizing the portion of the semiconductor layer **30** which is not covered with the insulating layers **21**, **24**.

In the next step, a resist **40** is applied, as shown in FIG. **31**. The resist **40** is made of e.g. resin and covers the insulating layer **24** and the insulating layer **21b** but does not cover the through-holes **24a**. This step is performed by applying liquefied resin to the surfaces of the insulating layer **24** and the insulating layer **21b**.

In the next step, vent holes **13A** are formed, as shown in FIG. **32**. The vent holes **13A** are made by forming through-holes **23a** in the insulating layer **23** such that each of the through-holes **23a** is connected to one of the through-holes **24a** and one of the through-hole **30a**. This step can be performed by gas-phase etching using the reaction between  $\text{HF}_2^-$  and  $\text{SiO}_2$ . In this step, the resist **40** is removed after the vent holes **13A** are formed.

In the next step, a cavity portion **13** is formed, as shown in FIG. **33**. This is performed by removing the sacrificial layer **12**. The removal of the sacrificial layer **12** is performed by gas-phase etching, i.e., sending gas containing F to the sacrificial layer **12** through the vent holes **13A**. F can be obtained by e.g. decomposing  $\text{CF}_4$  gas or  $\text{SF}_6$  gas. Since F does not easily react with  $\text{SiO}_2$ , the insulating layers **21**, **22**, **23**, **24**, **25**, **26** remain in this step, and the semiconductor substrate **10** and the semiconductor layer **30** protected by these insulating layers also remain. By forming the cavity portion **13** in this way, the portion of the semiconductor layer **30** which overlaps the



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cavity portion 13 as viewed in the lamination direction and the insulating layers 23, 24 on and under this portion become the movable portion 31.

In the next step, an insulating layer 27 and sealing portions 27a are formed, as shown in FIG. 34. In this step, for instance, plasma CVD is performed in a vacuum atmosphere. In this step, SiO<sub>2</sub> is further deposited on the insulating layers 21b, 24, 25, 26. As a result of deposition of SiO<sub>2</sub> on the insulating layer 25, the vent holes 13A are sealed to become sealing portions 27a. As a result of deposition of SiO<sub>2</sub> on the insulating layers 21b, 24, 26, the insulating layer 27 is provided.

In the next step, through-holes 27b and 27c are formed, as shown in FIG. 35. Specifically, the through-holes 27b and 27c are formed by providing a resist of resin such that the portions where the through-holes 27b and 27c are to be formed are exposed and performing wet etching using aqueous solution of hydrogen fluoride or gas-phase etching using the reaction between HF<sub>2</sub><sup>-</sup> and SiO<sub>2</sub>. The through-hole 27b reaches the semiconductor layer 30, and the through-hole 27c reaches the semiconductor substrate 10.

After the above-described steps, electrodes 51 and 52 are provided, whereby the pressure sensor 2 shown in FIGS. 19 and 20 is completed. For instance, the electrodes 51 and 52 are provided by forming an Al layer in the through-holes 27b, 27c and on the insulating layer 27 and then removing unnecessary portions of the Al layer by etching.

The operation and advantages of the pressure sensor 2 are described below.

According to this embodiment, when the movable portion 31 moves up and down, the capacitance between the semiconductor substrate 10 and the semiconductor layer 30 changes. The pressure sensor 2 detects such changes in capacitance between the semiconductor substrate 10 and the semiconductor layer 30 to detect changes in pressure applied to the movable portion 31. Since the cavity portion 13 is in a vacuum state, the pressure sensor 1 is suitable for measuring e.g. the absolute pressure applied to the movable portion 31.

According to the present invention, the cavity portion 13 is surrounded by the insulating layers 21, 22 and 23. Thus, in the pressure sensor 2, the capacitance between the semiconductor substrate 10 and the semiconductor layer 30 is relatively large. A larger capacitance between the semiconductor substrate 10 and the semiconductor layer 30 allows more sensitive detection of changes in the capacitance. Thus, the pressure sensor 2 ensures more precise pressure measurement.

Further, according to this embodiment, the insulating layer 22 is formed by oxidizing part of the surface of the semiconductor substrate 10, so that it is easy to make the thickness of the insulating layer uniform. The semiconductor layer 30 is formed on the insulating layers 21 and 23 which are made flush with each other. Thus, in the pressure sensor 2, the semiconductor substrate 10 and the semiconductor layer 30 are parallel to each other, with the cavity portion 13 intervening between them. This arrangement allows the capacitance between the semiconductor substrate 10 and the semiconductor layer 30 to be set precisely to a predetermined value. Thus, the pressure sensor 2 ensures more precise pressure measurement.

Moreover, according to the above-described manufacturing method, the pressure sensor 2 is produced from a single semiconductor substrate 10. Thus, the pressure sensor 2 realizes a simple manufacturing process and a low manufacturing cost.

Moreover, according to the above-described manufacturing method, the dimension in the vertical direction of the cavity portion 13 depends on the thickness of the insulating layer 21, and the thickness of the insulating layer 21 can be

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adjusted relatively easily by adjusting the time period for performing thermal oxidization. Further, according to this manufacturing method, the thickness of the semiconductor layer 30 can be adjusted properly by adjusting the time period for performing CVD, so that the thickness of the semiconductor layer 30 can be set to a desired value.

Although the sealing of the vent holes 13A is performed by plasma CVD in the above-described embodiment, the sealing can be performed by e.g. low pressure chemical vapor deposition (LPCVD).

FIGS. 36 and 37 show a pressure sensor according to a third embodiment of the present invention. The pressure sensor 3 of this embodiment is made up of a semiconductor substrate 10, and an insulating layer 20 and a semiconductor layer 30 laminated on the semiconductor substrate. The pressure sensor is provided with a cavity portion 13, a movable portion 31 and electrodes 51, 52.

The semiconductor substrate 10 is e.g. a single-crystal silicon (Si) substrate and has a recess 11 extending inward in the lamination direction (vertical direction in FIG. 37) at the center. The depth of the recess 11 is e.g. 5 to 15 μm. The cavity portion 13 and the semiconductor layer 30 are provided in the recess 11. The cavity portion 13 is in a vacuum state and provided adjacent to the bottom of the recess 11. The dimension of the cavity portion 13 in the vertical direction is e.g. 2 to 5 μm, and that in the horizontal direction is e.g. 300 to 500 μm. The semiconductor layer 30 is made of e.g. polycrystalline silicon and provided in such a manner as to close the recess 11. The semiconductor layer 30 has a thickness of e.g. 2 to 10 μm. The surface of the semiconductor layer 30 is made flush with the semiconductor substrate 10 at portions other than the portion where the recess 11 is provided.

The insulating layer 20 is made of e.g. silicon dioxide (SiO<sub>2</sub>). The insulating layer 20 is made up of insulating layers 22, 23, 27, which are made in different steps in the manufacturing process, as will be described later.

The insulating layer 22 covers the surface of the recess 11 which faces the cavity portion 13. The thickness of the insulating layer 22 is e.g. 0.3 to 1.0 μm. The insulating layer 23 covers the surface of the semiconductor layer 30 which faces the cavity portion 13. The thickness of the insulating layer 23 is e.g. 0.3 to 1.0 μm. The insulating layer 27 covers the surface of the semiconductor substrate 10 and the surface of the semiconductor layer 30. The thickness of the insulating layer 27 is e.g. 1 to 2 μm. The insulating layer 27 includes a plurality of sealing portions 27a which seal the portions corresponding to vent holes 13A formed in the manufacturing process, which will be described later. The sealing portions 27a are formed to be concave relative to the surrounding portions. The sealing portions 27a can be made flat by CMP. The insulating layer 27 includes a through-hole 27b penetrating in the lamination direction at the center in FIG. 37 and a through-hole 27c penetrating in the lamination direction at the right side in FIG. 37.

The electrode 51 is formed to be electrically connected to the semiconductor layer 30 via the through-hole 27b. The electrode 52 is formed to be electrically connected to the semiconductor substrate 10 via the through-hole 27c.

The movable portion 31 comprises the semiconductor layer 30 and the insulating layers 23, 27 on and under the semiconductor layer. The movable portion 31 is movable up and down in the lamination direction.

A method for manufacturing the pressure sensor 3 is described below with reference to FIGS. 38-53.

First, a semiconductor substrate 10 made of single-crystal silicon is prepared. Specifically, a semiconductor substrate 10 having a thickness of 300 to 700 μm is prepared. In the next

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step, as shown in FIG. 38, an insulating layer 21 of SiO<sub>2</sub> is formed on the surface of the semiconductor substrate 10. This step can be performed by thermally oxidizing the surface of the semiconductor substrate 10.

In the next step, as shown in FIG. 39, an opening 21a for exposing the surface of the semiconductor substrate 10 is formed in the insulating layer 21. This step is performed by providing a resist of resin which exposes the portion where the opening 21a is to be formed and performing wet etching using aqueous solution of hydrogen fluoride (HF).

In the next step, a recess 11 is formed in the semiconductor substrate 10, as shown in FIG. 40. This step can be performed by gas-phase etching using gas containing atomic fluorine (F). Fluorine (F) reacts with silicon (Si) but does not react with SiO<sub>2</sub>. Thus, the insulating layer 21 is not etched away, and the semiconductor substrate 10 is etched away at the portion exposed through the opening 21a, whereby the recess 11 is formed. In this step, by adjusting the time of dry etching, the recess 11 of a desired depth can be formed. The gas containing F can be obtained by decomposing carbon tetrafluoride (CF<sub>4</sub>) gas or sulfur hexafluoride (SF<sub>6</sub>) gas by discharge.

In the next step, an insulating layer 22 is formed, as shown in FIG. 41. This step can be performed by thermally oxidizing the surface of the recess 11.

In the next step, as shown in FIG. 42, a sacrificial layer 12A is formed in the recess 11. The sacrificial layer 12A is a layer of polycrystalline silicon. This step is performed by e.g. embedding polycrystalline silicon in the recess 11. In this step, the entirety of the interior of the recess 11 is filled with polycrystalline silicon. Further, in this step, the surface of the polycrystalline silicon is abraded such that the surface of the sacrificial layer 12 is flush with the surface of the insulating layer 21.

In the next step, a sacrificial layer 12 is made from the sacrificial layer 12A, as shown in FIG. 43. This step is performed by removing the portion close to the surface of the sacrificial layer 12A by gas-phase etching using gas containing HF. The gas containing HF can be prepared by e.g. decomposing by discharge a gas obtained by adding water vapor to CF<sub>4</sub> gas or SF<sub>6</sub> gas. By performing etching while keeping HF in a dry state and suppressing generation of HF<sub>2</sub><sup>-</sup>, SiO<sub>2</sub> is prevented from being etched away. Thus, the insulating layers 21 and 22 are not removed by this etching. In this step, the thickness of the sacrificial layer 12 can be adjusted by adjusting the etching time.

In the next step, as shown in FIG. 44, an insulating layer 23 of SiO<sub>2</sub> is formed. This step can be performed by thermally oxidizing the surface of the sacrificial layer 12.

In the next step, as shown in FIG. 45, the semiconductor layer 30 is formed. This step is performed by e.g. embedding polycrystalline silicon in an upper portion of the recess 11. The "upper portion of the recess 11" in this step means a portion of the recess 11 which is above the insulating layer 23.

In the next step, as shown in FIG. 46, an insulating layer 24 of SiO<sub>2</sub> is formed. First, in this step, the surface of the semiconductor layer 30 is thermally oxidized. Preferably, the thermal oxidation is performed through the thickness portion which is substantially the same as that of the insulating layer 21. By heating the surface of the semiconductor layer 30 uniformly, an oxide layer having a uniform thickness is formed. Then, low pressure chemical vapor deposition (LPCVD) using tetraethoxysilane (TEOS) is performed so that SiO<sub>2</sub> is further deposited on the already formed oxide layer and the insulating layer 21, whereby the insulating layer

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24 is formed. The insulating layer 24 is formed such that its thickness is sufficiently larger than the thickness of the insulating layer 23.

In the next step, as shown in FIG. 47, a plurality of through-holes 24a are formed in the insulating layer 24. This step can be performed by gas-phase etching using the reaction between fluorine-containing molecular ions (HF<sub>2</sub><sup>-</sup>) and SiO<sub>2</sub>. HF<sub>2</sub><sup>-</sup> can be obtained by reacting hydrogen fluoride (HF) with water vapor. HF can be obtained by reacting F or molecular fluorine (F<sub>2</sub>), which is obtained by e.g. decomposing CF<sub>4</sub> gas or SF<sub>6</sub> gas, with water vapor. Since Si which is not oxidized does not easily react with HF<sub>2</sub><sup>-</sup>, the semiconductor layer 30 is not removed by the etching and hence remains.

In the next step, as shown in FIG. 48, a plurality of through-holes 30a are formed in the semiconductor layer 30 so that each of the through-holes 30a is connected to a respective one of the through-holes 24a at the upper end and reaches the insulating layer 23 at the lower end. This step can be performed by gas-phase etching using gas containing HF. The gas containing HF can be prepared by e.g. decomposing by discharge a gas obtained by adding water vapor to CF<sub>4</sub> gas or SF<sub>6</sub> gas. By performing etching while keeping HF in a dry state and suppressing generation of HF<sub>2</sub><sup>-</sup>, SiO<sub>2</sub> is prevented from being etched away. In this step, therefore, the insulating layers 23 and 24 remain.

In the next step, an insulating layer 25 of SiO<sub>2</sub> is formed, as shown in FIG. 49. The insulating layer 25 is formed on the inner circumferential surface of each of the through-holes 30a. This step is performed by thermally oxidizing the portion of the semiconductor layer 30 which is not covered with the insulating layer 24.

In the next step, vent holes 13A are formed, as shown in FIG. 50. The vent holes 13A are made by forming through-holes 23a in the insulating layer 23 such that each of the through-holes 23a is connected to one of the through-holes 24a and one of the through-hole 30a. This step can be performed by gas-phase etching using the reaction between HF<sub>2</sub><sup>-</sup> and SiO<sub>2</sub>. This step can be performed by utilizing the difference in thickness between the insulating layer 23 and the insulating layer 24, without providing a resist. By this step, part of the insulating layer 24 is removed.

In the next step, a cavity portion 13 is formed, as shown in FIG. 51. This step can be performed by removing the sacrificial layer 12. The removal of the sacrificial layer 12 is performed by gas-phase etching, i.e., by sending gas containing F to the sacrificial layer 12 through the vent holes 13A. F can be obtained by e.g. decomposing CF<sub>4</sub> gas or SF<sub>6</sub> gas. Since F does not easily react with SiO<sub>2</sub>, the insulating layers 22, 23, 24, 25 remain in this step, and the semiconductor substrate 10 and the semiconductor layer 30 protected by these insulating layers also remain. By forming the cavity portion 13 in this way, the portion of the semiconductor layer 30 which overlaps the cavity portion 13 as viewed in the lamination direction and the insulating layers 23, 24 on and under this portion become the movable portion 31.

In the next step, an insulating layer 27 and sealing portions 27a are formed, as shown in FIG. 52. In this step, for instance, plasma CVD is performed in a vacuum atmosphere. In this step, SiO<sub>2</sub> is further deposited on the insulating layers 24 and 25. As a result of deposition of SiO<sub>2</sub> on the insulating layer 25, the vent holes 13A are sealed to become sealing portions 27a. As a result of deposition of SiO<sub>2</sub> on the insulating layer 24, the insulating layer 27 is provided.

In the next step, through-holes 27b and 27c are formed, as shown in FIG. 53. Specifically, the through-holes 27b and 27c are formed by providing a resist of resin such that the portions where the through-holes 27b and 27c are to be formed are

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exposed and performing wet etching using aqueous solution of hydrogen fluoride or gas-phase etching using the reaction between  $\text{HF}_2^-$  and  $\text{SiO}_2$ . The through-hole 27b reaches the semiconductor layer 30, and the through-hole 27c reaches the semiconductor substrate 10.

After the above-described steps, electrodes 51 and 52 are provided, whereby the pressure sensor 3 shown in FIGS. 36 and 37 is completed. For instance, the electrodes 51 and 52 are provided by forming an Al layer in the through-holes 27b, 27c and on the insulating layer 27 and then removing unnecessary portions of the Al layer by etching.

The operation and advantages of the pressure sensor 3 are described below.

According to this embodiment, when the movable portion 31 moves up and down, the capacitance between the semiconductor substrate 10 and the semiconductor layer 30 changes. The pressure sensor 3 detects such changes in capacitance between the semiconductor substrate 10 and the semiconductor layer 30 to detect changes in pressure applied to the movable portion 31. Since the cavity portion 13 is in a vacuum state, the pressure sensor 3 is suitable for e.g. measuring the absolute pressure applied to the movable portion 31.

According to the present invention, the cavity portion 13 is surrounded by the insulating layers 22 and 23. Thus, in the pressure sensor 3, the capacitance between the semiconductor substrate 10 and the semiconductor layer 30 is relatively large. A larger capacitance between the semiconductor substrate 10 and the semiconductor layer 30 allows more sensitive detection of changes in the capacitance. Thus, the pressure sensor 3 ensures more precise pressure measurement.

Further, according to this embodiment, the recess 11 is formed by etching so that the bottom surface of the recess is parallel to the surface of the semiconductor substrate 10. Moreover, the sacrificial layer 12 is formed by etching the sacrificial layer 12A which has been abraded to correspond to the surface of the semiconductor substrate 10. Thus, the surface of the insulating layer 23, which is formed by thermally oxidizing the surface of the sacrificial layer 12, is parallel to the surface of the semiconductor substrate 10. Accordingly, in the pressure sensor 3, the bottom surface of the recess 11 and the semiconductor layer 30 are parallel to each other, with the cavity portion 13 intervening between them. This arrangement allows the capacitance between the semiconductor substrate 10 and the semiconductor layer 30 to be set precisely to a predetermined value. Thus, the pressure sensor 3 ensures more precise pressure measurement.

Moreover, according to the above-described manufacturing method, the pressure sensor 3 is produced from a single semiconductor substrate 10. Thus, the pressure sensor 3 realizes a simple manufacturing process and a low manufacturing cost.

Moreover, according to the above-described manufacturing method, the depth of the recess 11 and the thickness of the sacrificial layer 12 can be easily adjusted by adjusting the etching time in each step. Thus, the dimension in the vertical direction of the cavity portion 13 and the thickness of the semiconductor layer 30 can be set to a desirable value.

In this embodiment, the recess 11 is formed by etching the semiconductor substrate 10. However, unlike this, the recess 11 may be formed by allowing single-crystal silicon to grow on portions of the semiconductor substrate 10 other than the center portion. The sealing of the vent holes 13A can be performed by a LPCVD method.

The pressure sensor according to the present invention is not limited to the foregoing embodiments. The specific structure of each part of the pressure sensor according to the

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present invention can be varied in design in many ways. For instance, although a capacitive pressure sensor is shown in the foregoing embodiments, the present invention is also applicable to a pressure sensor that uses a piezoresistor. Although the cavity portion 13 is in a vacuum state in the foregoing embodiments, the cavity portion may be filled with a gas of a given pressure.

In the foregoing embodiments, the semiconductor substrate 10 is made of single-crystal silicon, whereas the semiconductor layer 30 is made of polycrystalline silicon. Unlike this, however, the semiconductor substrate 10 may be made of polycrystalline silicon, whereas the semiconductor layer 30 may be made of single-crystal silicon. Moreover, the sacrificial layer 12 may be made of single-crystal silicon.

FIGS. 54 and 55 show a pressure sensor according to a fourth embodiment of the present invention. The pressure sensor 101 of this embodiment is made up of a semiconductor substrate 110, and an oxide film 121 and a semiconductor layer 130 formed on the semiconductor substrate. The pressure sensor is provided with sealing members 141, a movable portion 161, and piezoresistors 171, 172, 173, 174. The pressure sensor 101 is further provided with a bridge circuit in which the piezoresistors 171, 172, 173, 174 are included. The bridge circuit is arranged on the semiconductor layer 130 and includes output terminals Vout+, Vout-, a bias voltage application terminal Vdd, ground terminals 151, 152, 153 and leads 154, 155, 156, 157, 158. The ground terminals 151, 152, 153 are grounded.

The semiconductor substrate 110 is a single-crystal silicon (Si) substrate having a thickness of about 300  $\mu\text{m}$  in the lamination direction (vertical direction in FIG. 55), and includes a cavity portion 111 the inside of which is in a vacuum state or at a given pressure. The cavity portion 111 is open at the surface of the semiconductor substrate 110 and has a depth of 1 to 50  $\mu\text{m}$  in the lamination direction. The cavity portion 111 is circular as viewed in the thickness direction and has a diameter of e.g. 100 to several thousand micrometers. The shape of the cavity portion 111 as viewed in the lamination direction is not limited to a circular shape, but may be a polygonal shape such as a rectangle.

The semiconductor layer 130 is made of e.g. single-crystal silicon and formed on the semiconductor substrate 110 to have a thickness of about 1 to 50  $\mu\text{m}$ . The semiconductor layer 130 has a plurality of through-holes 130a in an area overlapping the cavity portion 111 as viewed in the lamination direction. Each of the through-holes 130a penetrates the semiconductor layer 130 in the lamination direction, and an oxide film 131 having a thickness of about 0.2  $\mu\text{m}$  is formed on the inner circumferential surface of the through-hole. As viewed in the lamination direction, the through-hole 130a has a circular shape with a diameter of 0.2 to 5  $\mu\text{m}$  or an oval shape having a similar size.

The oxide film 121 is made of e.g. a silicon dioxide ( $\text{SiO}_2$ ) and formed between the semiconductor substrate 110 and the semiconductor layer 130 to have a thickness of about 0.1 to 3  $\mu\text{m}$ . The oxide film 121 has a plurality of through-holes 121a that overlap the through-holes 130a as viewed in the lamination direction. Each of the through-holes 121a penetrates the oxide film 121 in the lamination direction and reaches one of the through-holes 130a at the upper end and reaches the cavity portion 111 at the lower end.

The sealing members 141 are made of e.g. silicon dioxide ( $\text{SiO}_2$ ) and seal the upper end of each through-hole 130a.

The movable portion 161 comprises portions of the semiconductor layer 130 and the oxide film 121 which overlap the cavity portion 111 as viewed in the lamination direction. Since the movable portion 161 overlaps the cavity portion

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111, the movable portion is deformable in the lamination direction. The shape of the movable portion 161 as viewed in the lamination direction is the same as that of the cavity portion 111.

As shown in FIG. 54, each of the piezoresistors 171, 172, 173, 174 is in the form of a meandering strip including a plurality of bends, and embedded in the semiconductor layer 130. The thickness of the piezoresistors 171, 172, 173, 174 in the lamination direction is e.g. about 0.1 to 1  $\mu\text{m}$ . The piezoresistor 171 is arranged at the upper end of the movable portion 161 in FIG. 54. The piezoresistor 172 is arranged at the left end of the movable portion 161 in FIG. 54. The piezoresistor 173 is arranged at the lower end of the movable portion 161 in FIG. 54. The piezoresistor 174 is arranged at the right end of the movable portion 161 in FIG. 54. The piezoresistors 171 and 173 are located within the area of the movable portion 161, whereas the piezoresistors 172 and 174 are located at the edge of the movable portion 161. The piezoresistors 171, 172, 173, 174 are made of doped polysilicon or by doping a P-type or N-type element.

The piezoresistor 171 is connected at one end to the ground terminal 151 via the lead 154 and connected at the other end to the output terminal Vout+.

The piezoresistor 172 is connected at one end to the output terminal Vout+ via the lead 155 and connected at the other end to the bias voltage application terminal Vdd via the lead 156.

The piezoresistor 173 is connected at one end to the bias voltage application terminal Vdd via the lead 156 and connected at the other end to the output terminal Vout-.

The piezoresistor 174 is connected at one end to the output terminal Vout- via the lead 157 and connected at the other end to the ground terminal 152 via the lead 158.

The operation and advantages of the pressure sensor 101 are described below.

In the pressure sensor 101, when pressure is applied to the surface of the movable portion 161, the movable portion 161 is deformed, so that distortion occurs in the piezoresistors 171, 172, 173, 174. The resistance of the piezoresistors 171, 172, 173, 174 changes due to the distortion. Such a change in resistance of the piezoresistors 171, 172, 173, 174 is detected through the output terminals Vout+, Vout- as a change in voltage relative to the bias voltage applied to the bias voltage application terminal Vdd by using the bridge circuit. Based on the detection result, the pressure applied to the movable portion 161 is calculated. When the cavity portion 111 is in a vacuum state, the pressure applied to the movable portion 161 is the absolute pressure of the ambient gas. When the cavity portion 111 is at a given pressure, the pressure applied to the movable portion 161 is the relative pressure between the ambient gas and the gas within the cavity portion 111.

A method for manufacturing the pressure sensor 101 is described below with reference to FIGS. 56-69.

First, as shown in FIG. 56, a semiconductor substrate 110 having a semiconductor layer 130 on the surface is prepared. The semiconductor layer 130 has an oxide layer 122 on the surface.

In the next step, as shown in FIGS. 57 and 58, a plurality of through-holes 122a are formed in the oxide layer 22. The shape of the through-holes 122a as viewed in the lamination direction is the same as that of the above-described through-holes 130a. In this step, for instance, after a resist of resin that exposes the portions where the through-holes 122a are to be formed is provided, gas-phase etching using the reaction between fluorine-containing molecular ions ( $\text{HF}_2^-$ ) and  $\text{SiO}_2$  is performed.  $\text{HF}_2^-$  can be obtained by reacting hydrogen fluoride (HF) with water vapor. HF can be obtained by reacting F or molecular fluorine ( $\text{F}_2$ ), which is obtained by e.g.

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decomposing trifluoromethane ( $\text{CHF}_3$ ) gas, with water vapor. Since Si which is not oxidized does not easily react with  $\text{HF}_2^-$ , the semiconductor layer 130 is not removed by the etching and hence remains. Instead of the gas-phase etching, wet etching using aqueous solution of hydrogen fluoride (HF) may be performed.

In the next step, as shown in FIG. 59, a plurality of through-holes 130a are formed in the semiconductor layer 130. This step can be performed by gas-phase anisotropic etching using gas containing HF. The gas containing HF can be prepared by e.g. decomposing by discharge a gas obtained by adding water vapor to  $\text{CHF}_3$ . By performing etching while keeping HF in a dry state and suppressing generation of  $\text{HF}_2^-$ ,  $\text{SiO}_2$  is prevented from being etched away. In this step, therefore, the oxide film 121 and the oxide layer 122 remain.

In the next step, as shown in FIG. 60, the inner circumferential surface of each through-hole 130a is oxidized to form an oxide film 131. This step can be performed by e.g. thermal oxidization. The oxide film 131 is provided to protect the semiconductor layer 130 during the etching, which will be performed in a later step. The same protection effect is provided by depositing  $\text{SiO}_2$  on the inner circumferential surface of the through-holes 130a by CVD to form a protective film.

In the next step, vent holes 111A are formed, as shown in FIGS. 61 and 62. Each vent hole 111A is made up of through-holes 121a, 122a, 130a. This step can be performed by gas-phase anisotropic etching using the reaction between  $\text{HF}_2^-$  and  $\text{SiO}_2$ . In this gas-phase anisotropic etching,  $\text{SiO}_2$  is removed by an amount corresponding to the thickness of the oxide film 121 in the lamination direction. In this step, through-holes 121a are formed in the oxide film 121, while at the same time, the surface portion of the oxide layer 122 is removed.

In the next step, as shown in FIG. 63, a cavity portion 111 is formed. For instance, this step can be performed by gas-phase etching using gas containing atomic fluorine (F). Fluorine (F) easily reacts with silicon (Si) but does not easily react with  $\text{SiO}_2$ . Thus, by sending gas containing F to the semiconductor substrate 110 through the vent holes 111A covered with  $\text{SiO}_2$ , the semiconductor substrate 110 is etched and the cavity portion 111 is formed before the semiconductor layer 130 is etched. The gas containing F can be obtained by decomposing  $\text{CHF}_3$  gas by discharge.

The cavity portion 111 can be formed by etching using xenon fluoride gas. The difference between Si and  $\text{SiO}_2$  in reactivity with xenon fluoride gas is larger than that in reactivity with  $\text{CHF}_3$  gas. Thus, the oxide film 131 can be made thinner by using xenon fluoride gas.

In the next step, as shown in FIG. 64, vent holes 111A are sealed. This step is performed by low pressure chemical vapor deposition (LPCVD) using tetraethoxysilane (TEOS). By this step,  $\text{SiO}_2$  is deposited on the oxide layer 122 and in the vent holes 111A, so that the oxide layer 123 and sealing portions 140 are formed. By sealing the vent holes 111A with the sealing portions 140 in a vacuum state or in an atmosphere of a given pressure, the cavity portion 111 is brought into a vacuum state or at a given pressure. Of each sealing portion 140, the portion that closes the vent hole 111A tends to be concave at the center, because  $\text{SiO}_2$  grows radially from the inner circumferential surface of the vent hole 111A.

The sealing of the vent hole 111A can be performed by other methods, such as thermal oxidation to utilize bulging of the oxidized portion.

In the next step, as shown in FIG. 65, the oxide layer 123 is removed. This step can be performed by abrading or gas-phase etching. In this step, at the same time, part of the sealing portions 140 are removed, so that sealing members 141

remain on the upper ends of the through-holes 130a. As shown in FIG. 65, the sealing members 141 are flat at the upper ends and concave toward the center at the lower end. By this step, the movable portion 161 is provided.

In the next step, piezoresistors 171, 172, 173, 174 are formed. Specifically, for instance, the piezoresistors 171, 172, 173, 174 are formed by embedding polycrystalline silicon in the semiconductor layer 130. Firstly, in this step, grooves 132, 133, 134, 135 are formed, as shown in FIGS. 66 and 67. Specifically, gas-phase etching using gas containing HF is performed using a resist of resin which exposes portions corresponding to the grooves 132, 133, 134, 135. Each of the grooves 132, 133, 134, 135 is formed to have a meandering shape including a plurality of bends.

In the next step, as shown in FIGS. 68 and 69, polycrystalline silicon is embedded in the grooves 132, 133, 134, 135. The polycrystalline silicon embedded in the grooves 132, 133, 134, 135 in this step becomes the piezoresistors 171, 172, 173, 174. Alternatively, the piezoresistors 171, 172, 173, 174 can be provided by forming diffused resistors by performing implantation with respect to the semiconductor layer 130.

Thereafter, e.g. an aluminum (Al) layer is formed on the semiconductor layer 130. Then, etching is performed with respect to the Al layer, whereby output terminals Vout+, Vout-, a bias voltage application terminal Vdd, ground terminals 151, 152, 153 and leads 154, 155, 156, 157, 158 are formed.

By the above-described steps, the pressure sensor 101 shown in FIGS. 54 and 55 is completed.

The operation and advantages of the pressure sensor 101 are described below.

According to the above-described manufacturing method, the cavity portion 111 and the movable portion 161 are formed by making vent holes 111A in the semiconductor layer 130 and etching the semiconductor substrate 110 through the vent holes 111A. Thus, unlike the conventional method which uses a plurality of semiconductor substrates, the pressure sensor 101 is produced from a single semiconductor substrate 110. Thus, the pressure sensor 101 realizes a simple manufacturing process and a low manufacturing cost.

Moreover, according to the present embodiment, the piezoresistors 171, 172, 173, 174 have a meandering shape including a plurality of bends, which allows distortion due to deformation of the movable portion 161 to occur easily. As a result, the piezoresistors 171, 172, 173, 174 show remarkable changes in resistance when the movable portion 161 is deformed. Thus, the pressure sensor 101 ensures more precise pressure measurement.

FIGS. 70-85 show other embodiments of the present invention. In these figures, the elements which are identical or similar to those of the foregoing embodiments are designated by the same reference signs as those used for the foregoing embodiments.

FIGS. 70 and 71 show a pressure sensor according to a fifth embodiment of the present invention. The pressure sensor 102 shown in FIGS. 70 and 71 differs from the pressure sensor 101 in that the semiconductor layer 130 is made of polycrystalline silicon and in structure of the grooves 132, 133, 134, 135 and piezoresistors 171, 172, 173, 174. As shown in FIG. 71, an insulator 136 is filled between the grooves 132, 133, 134, 135 and the piezoresistors 171, 172, 173, 174. The structures of other parts of the pressure sensor 102 are the same as those of the pressure sensor 101.

FIGS. 72 and 73 show the step of forming grooves 132, 133, 134, 135 in manufacturing the pressure sensor 102. As shown in FIGS. 72 and 73, each of the grooves 132, 133, 134,

135 is formed such that part of the semiconductor layer 130 remains within the groove. The portion of the semiconductor layer 130 which remains in each of the grooves 132, 133, 134, 135 is separated from the main portion of the semiconductor layer 130 by the groove 132, 133, 134, 135. As shown in FIG. 72, each groove is formed such that the remaining portion has a meandering shape including a plurality of bends. Such grooves 132, 133, 134, 135 can be formed by performing gas-phase etching using gas containing HF and an appropriate resist of resin. In the pressure sensor 102, the portion of the semiconductor layer 130 which remains within each of the grooves 132, 133, 134, 135 becomes the piezoresistor 171, 172, 173, 174.

In the process of manufacturing the pressure sensor 102, after the step shown in FIGS. 72 and 73, the step of embedding an insulator 136 in the grooves 132, 133, 134, 135 is performed. In this step, the piezoresistors 171, 172, 173, 174 may be covered with the insulator 136. Thus, an Al layer is formed after etching is performed with respect to the insulator 136 to expose the piezoresistors 171, 172, 173, 174. This ensures electrical connection between the piezoresistors 171, 172, 173, 174 and the output terminals Vout+, Vout- and leads 154, 155, 156, 157, 158, which are made of the Al layer. In etching the insulator 136, the portion of the insulator 136 which covers the piezoresistors 171, 172, 173, 174 does not need to be removed entirely. It is sufficient if only portions for allowing connection to the output terminals Vout+, Vout- and leads 154, 155, 156, 157, 158 are secured in the piezoresistors 171, 172, 173, 174.

Similarly to the pressure sensor 101, the pressure sensor 102 is produced from a single semiconductor substrate 110, without the need for using a plurality of semiconductor substrates. Thus, the pressure sensor 102 realizes a simple manufacturing process and a low manufacturing cost.

Moreover, according to this embodiment again, the piezoresistors 171, 172, 173, 174 have a meandering shape including a plurality of bends, which allows distortion due to deformation of the movable portion 161 to occur easily. As a result, the piezoresistors 171, 172, 173, 174 of this embodiment also show remarkable changes in resistance when the movable portion 161 is deformed. Thus, the pressure sensor 102 ensures more precise pressure measurement.

FIG. 74 shows a pressure sensor according to a sixth embodiment of the present invention. In the pressure sensor 103 of this embodiment, the cavity portion 111 is open to the reverse surface of the semiconductor substrate 110, and to the opening 111a is connected a pipe 163. The pipe 163 is connected to a gas supply chamber 162. The structures of the other parts of the pressure sensor 103 are the same as those of the pressure sensor 101.

For instance, the opening 111a can be formed by performing etching from the reverse surface of the semiconductor substrate 110 after the cavity portion 111 is formed.

In the pressure sensor 103, the gas supply chamber 162 is filled with a gas of a given pressure, and the gas is supplied to the cavity portion 111 through the pipe 163. With this arrangement, the pressure applied to the reverse surface of the movable portion 161 is known. In this case, the pressure applied to the movable portion 161 is the relative pressure between the pressure of the outside gas applied to the obverse surface side of the movable portion 161 and the known pressure applied to the reverse surface side. Thus, with the pressure sensor 103, the pressure of the outside gas can be found by detecting the relative pressure of the outside gas with respect to the gas within the cavity portion 111.

Alternatively, the pressure sensor may be designed such that gas of a given pressure is applied to the obverse surface of

the movable portion **161**, while the gas supply chamber **162** is filled with a gas of an unknown pressure. In this case, the pressure of the gas in the gas supply chamber can be measured by supplying the gas to the cavity portion **111** through the pipe **163**.

FIGS. **75** and **76** show a pressure sensor according to a seventh embodiment of the present invention. The pressure sensor **104** shown in FIGS. **75** and **76** includes a pair of plate-like members **112** and **113** projecting from the semiconductor substrate **110** in the lamination direction and facing each other. The height of the plate-like members **112** and **113** in the lamination direction is e.g. in the range of from several micrometers to several tens of micrometers. In the pressure sensor **104**, the movable portion **161** and the cavity portion **111** are in the form of an elongated rectangle as viewed in the lamination direction. The movable portion **161** and the cavity portion **111** are sandwiched between the paired plate-like members **112** and **113**. In this embodiment, piezoresistors **175**, **176**, **177**, **178** each in the form of a thin film are used instead of the piezoresistors **171**, **172**, **173**, **174** of the pressure sensors **101-103**. Though not shown in FIGS. **75** and **76**, a bridge circuit including the piezoresistors **175**, **176**, **177**, **178** are formed on the semiconductor layer **130**. The structures of other parts of the pressure sensor **104** are the same as those of the pressure sensor **101**.

FIGS. **77-85** show some of the steps of the process of manufacturing the pressure sensor **104**.

FIGS. **77** and **78** show the step of making a pair of plate-like members **112** and **113**. This step comprises preparing a semiconductor substrate **110** in the form of a flat plate, forming oxide layers **112a** and **113a** having a thickness of 0.5  $\mu\text{m}$  on the surface of the semiconductor substrate **110**, and etching Si. The oxide layers **112a** and **113a** are formed to cover the portions where the plate-like members **112** and **113** are to be formed, as viewed in the lamination direction. For instance, the oxide layers **112a** and **113a** are formed by thermally oxidizing the surface of the prepared semiconductor substrate **110** and then etching away unnecessary portions. In the step of Etching Si, gas-phase etching is performed using gas containing F obtained by decomposing  $\text{CHF}_3$  gas by discharge. In this etching, the portions covered with the oxide layers **112a** and **113a** in the lamination direction remain, so that the shape as shown in FIG. **78** is obtained.

In the next step, an oxide film **121** is formed, as shown in FIG. **79**. This step can be performed by thermally oxidizing the surface of the semiconductor substrate **110**.

In the next step, a semiconductor layer **130** is formed, as shown in FIG. **80**. Specifically, the semiconductor layer **130** is formed by causing polycrystalline silicon to grow by e.g. chemical vapor deposition (CVD). Further, in this step, CMP (chemical mechanical polishing) is performed so that the surface of the semiconductor layer **130** is flush with the surface of the oxide layers **112a** and **113a**.

In the next step, as shown in FIG. **81**, the surface of the semiconductor layer **130** is thermally oxidized to form an oxide layer **122**.

In the next step, as shown in FIGS. **82** and **83**, through-holes **122a** are formed in the oxide layer **122**. Then, as described above by referring to FIGS. **59-63** with respect to the fourth embodiment, the step of forming through-holes **130a**, the step of oxidizing the inner circumferential surfaces of the through-holes **130a**, the step of forming vent holes **111A** and the step of forming cavity portion **111** are performed, whereby the state shown in FIGS. **84** and **85** is obtained. Thereafter, the step of sealing the vent holes **111A**, the step of removing the oxide layer **122** on the semiconductor layer **130** and the oxide layers **112a**, **113a**, the step of

forming piezoresistors **175**, **176**, **177**, **178** and the step of forming a bridge circuit are performed, whereby the pressure sensor **104** shown in FIGS. **75** and **76** is completed.

The step of forming piezoresistors **175**, **176**, **177**, **178** can be performed by e.g. doping the material for the piezoresistors **175**, **176**, **177**, **178** in the surface the semiconductor layer **130** and diffusing the material.

In the pressure sensor **104**, similarly to the pressure sensor **101**, the cavity portion **111** and the movable portion **161** are formed by making vent holes **111A** in the semiconductor layer **130** and etching the semiconductor substrate **110** through the vent holes **111A**. Thus, unlike the conventional method which uses a plurality of semiconductor substrates, the pressure sensor **104** is produced from a single semiconductor substrate **110**. Thus, the pressure sensor **104** realizes a simple manufacturing process and a low manufacturing cost.

The pressure sensor according to the present invention is not limited to the foregoing embodiments. The specific structure of each part of the pressure sensor according to the present invention can be varied in design in many ways. For instance, although the pressure sensor **103** has a structure based on the pressure sensor **101**, it may have a structure based on the pressure sensor **102**. The sealing members **141** may fill the entirety of the through-holes **130a** and may further extend into the through-holes **121a**.

The pressure sensor **104** may be provided with an opening **111a**, a pipe **163** and a gas supply chamber **162**, similarly to the pressure sensor **103**. The piezoresistors **175**, **176**, **177**, **178** shown for the pressure sensor **104** may be provided in the pressure sensors **101** and **102**, instead of the piezoresistors **171**, **172**, **173**, **174**. Conversely, the piezoresistors **171**, **172**, **173**, **174** shown for the pressure sensor **102** may be used for the pressure sensor **104**, instead of the piezoresistors **175**, **176**, **177**, **178**.

For instance, although the semiconductor substrate **110** is made of single-crystal silicon Si in the foregoing embodiments, polycrystalline silicon may be used instead.

FIGS. **86** and **87** show a pressure sensor according to an eighth embodiment of the present invention. The pressure sensor **201** of this embodiment includes a semiconductor substrate **221**, a (first) insulating layer **221**, an insulating cover **222**, a (third) insulating cover **223**, an intermediate layer **230** and an electrode layer **240**.

The semiconductor substrate **210** is e.g. a single-crystal silicon (Si) substrate having a thickness of about 300  $\mu\text{m}$  in the lamination direction (vertical direction in FIG. **87**) and includes a cavity portion **211** the inside of which is in a vacuum state or at a given pressure. The cavity portion **211** is open to the obverse surface of the semiconductor substrate **210** and its depth in the lamination direction is e.g. 5 to 100  $\mu\text{m}$ . As viewed in the lamination direction, the cavity portion **211** is in the form of a square, an elongated rectangle, a circle or an oval and has a length of e.g. 50  $\mu\text{m}$  to several millimeters in the horizontal direction in FIG. **86**.

The intermediate layer **230** is formed on the semiconductor substrate **210** and has a thickness of about 1 to 50  $\mu\text{m}$ . The intermediate layer comprises a semiconductor layer **230A**, a recess **231**, a (second) insulating layer **232**, a plurality of through-holes **223** formed in the semiconductor layer **230A**, a protective film **234**, a sealing member **235** and a cavity portion **237**. The semiconductor layer **230A**, which is made of polycrystalline silicon, constitutes most part of the intermediate layer **230**. The remaining part of the intermediate layer is formed by processing the semiconductor layer **230A**, as described later in explaining the manufacturing method.

The recess **231** is provided at a position overlapping the cavity portion **211** as viewed in the lamination direction. The

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recess **231** extends e.g. about 2  $\mu\text{m}$  inward from the surface of the intermediate layer **230** in the lamination direction. The cavity portion **237** is defined in the recess **231**.

The insulating layer **232** covers the surface of the recess **231**. The thickness of the insulating layer **232** is e.g. about 1.0  $\mu\text{m}$ . For instance, the insulating layer **232** is made of e.g. silicon dioxide ( $\text{SiO}_2$ ).

The through-holes **233** are formed in an area overlapping the recess **231** as viewed in the lamination direction and extend from the surface of the intermediate layer **230** toward the recess **231** in the lamination direction. As viewed in the lamination direction, each of the through-holes **233** has a circular shape with a diameter of 0.5 to 5.0  $\mu\text{m}$  or an oval shape having a similar size.

The protective film **234** is a  $\text{SiO}_2$  film having a thickness of about 0.2  $\mu\text{m}$  formed on the inner circumferential surface of each of the through-holes **233**.

The sealing member **235** is made of e.g.  $\text{SiO}_2$  and seals the upper end of each of the through-holes **233** in the lamination direction. The sealing member **235** is integral with the insulating layer **232** and the protective film **234**.

The insulating layer **221** is provided between the semiconductor substrate **210** and the intermediate layer **230** and made of e.g.  $\text{SiO}_2$ . The thickness of the insulating layer **221** is e.g. 0.1 to 1.0  $\mu\text{m}$ . The insulating layer **221** has through-holes **221a** connected to the through-holes **233**.

The insulating cover **222** covers the surface of the intermediate layer **230** except the surface of the recess **231**, and is made of e.g.  $\text{SiO}_2$ . The thickness of the insulating cover **222** is e.g. 0.1 to 1  $\mu\text{m}$ . The insulating cover **222** has an opening **222b** exposing the semiconductor layer **230A**. For instance, the opening **222b** is provided at the right end in FIG. **86**.

The insulating cover **223** is made of e.g.  $\text{SiO}_2$  and provided to close the cavity portion **237**. The thickness of the insulating cover **223** is e.g. 0.1 to 1.0  $\mu\text{m}$ . The shape of the insulating cover **223** as viewed in the lamination direction is the same as that of the bottom surface of the recess **231** and the edges of the insulating cover is integral with the insulating cover **222** and the insulating layer **232**. The insulating cover **223** has a plurality of through-holes **223a** reaching the hollow portion **237** at the lower ends in the lamination direction.

The electrode layer **240** is formed on the insulating cover **222** or the insulating cover **223** and includes a fixed electrode terminal **241**, a fixed electrode **242**, a movable electrode terminal **243**, a connection line **244** and a filling portion **245**. The electrode layer **240** is made of e.g. aluminum (Al).

The fixed electrode terminal **241** is provided at an appropriate portion on the insulating cover **222** and used for electrical connection to the outside, for example. The fixed electrode **242** is formed on the insulating cover **223** and electrically connected to the fixed electrode terminal **241**. The fixed electrode **242** has a plurality of through-holes **242a** respectively connected to the through-holes **223a** at the lower ends in the lamination direction. The fixed electrode **242** covers the entirety of the insulating cover **223**.

The movable electrode terminal **243** is electrically insulated from the fixed electrode terminal **241** and the fixed electrode **242** and provided on the insulating cover **222** to be electrically connected to the filling portion **245** via the connection line **244**. The filling portion **245** fills the opening **222b** and is in contact with the semiconductor layer **230A**. Thus, the movable electrode terminal **243** is electrically connected to the semiconductor layer **230A** via the connection line **244** and the filling portion **245**.

The operation and advantages of the pressure sensor **201** are described below.

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In the pressure sensor **201**, the portion sandwiched between the cavity portions **211** and **237** in the lamination direction serves as a deformable movable portion **261**. With the above-described arrangement, since the insulating cover **223** and the fixed electrode **242** have the through-holes **223a**, **242a**, the cavity portion **237** is filled with gas flowing from the outside. On the other hand, as noted before, the cavity portion **211** is in a vacuum state or at a given pressure. Thus, the movable portion **261** is pressed by the gas flowing into the cavity portion **237** and is hence deformed. Since part of the semiconductor layer **230A** is included in the movable portion **261**, when the movable portion **261** is deformed, the capacitance between the fixed electrode **242** and the semiconductor layer **230A** changes. As noted before, the semiconductor layer **230A** is electrically connected to the movable electrode terminal **243**, and the fixed electrode **242** is electrically connected to the fixed electrode terminal **241**. Thus, in the pressure sensor **201**, the semiconductor layer **230A** in the movable portion **261** functions as a movable electrode, and changes in capacitance between the movable portion **261** and the fixed electrode **242** is outputted through the fixed electrode terminal **241** and the movable electrode terminal **243**, whereby the absolute pressure of the gas flowing into the cavity portion **237** is measured.

A method for manufacturing the pressure sensor **201** is described with reference to FIGS. **88** to **106**.

First, the state shown in FIG. **88** is obtained by performing the step of preparing a semiconductor substrate **210** in the form of a flat plate, the step of forming an insulating layer **221** on the surface of the semiconductor substrate **210**, the step of forming a semiconductor layer **230A** on the insulating layer **221** and the step of forming an insulating cover **222** on the semiconductor layer **230A**. The step of forming the insulating layer **221** is performed by e.g. thermally oxidizing the surface of the semiconductor substrate **210**. The step of forming the semiconductor layer **230A** is performed by causing polycrystalline silicon to grow by e.g. chemical vapor deposition (CVD). The step of forming the insulating cover **222** is performed by thermally oxidizing the surface of the semiconductor layer **230A**.

In the next step, as shown in FIGS. **89** and **90**, an opening **222a** is formed in the insulating cover **222**. The opening **222a** is formed to expose the portion of the semiconductor layer **230A** where the recess **231** is to be formed. This step is performed by providing a resist of resin which exposes the portion where the opening **222a** is to be formed and performing gas-phase etching using the reaction between fluorine-containing molecular ions ( $\text{HF}_2^-$ ) and  $\text{SiO}_2$ .  $\text{HF}_2^-$  can be obtained by reacting hydrogen fluoride (HF) with water vapor. For instance, HF can be obtained by reacting atomic fluorine (F) and molecular fluorine ( $\text{F}_2$ ), which is obtained by decomposing e.g.  $\text{CHF}_3$  gas, with water vapor. Since Si which is not oxidized does not easily react with  $\text{HF}_2^-$ , the semiconductor layer **230A** is not removed by the etching and hence remains. Instead of the gas-phase etching, wet etching using aqueous solution of hydrogen fluoride (HF) may be performed.

In the next step, a recess **231** is formed, as shown in FIG. **91**. This step can be performed by gas-phase anisotropic etching using gas containing HF. The gas containing HF can be prepared by e.g. decomposing by discharge a gas obtained by adding water vapor to  $\text{CHF}_3$  gas. By performing etching while keeping HF in a dry state and suppressing generation of  $\text{HF}_2^-$ ,  $\text{SiO}_2$  is prevented from being etched away. In this step, therefore, the insulating cover **222** remains.

In the next step, as shown in FIG. **92**, an insulating layer **232** is formed. This step is performed by thermal oxidation



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or by causing SiO<sub>2</sub> to grow by CVD. In this step, whichever method is used, the insulating cover 222 becomes thicker at the same time as the insulating layer 232 is formed.

In the next step, a plurality of through-holes 232a are formed, as shown in FIGS. 93 and 94. Each of the through-holes 232a is formed to penetrate the insulating layer 232 in the lamination direction to expose the surface of the semiconductor layer 230A. This step is performed by gas-phase anisotropic etching using the reaction between HF<sub>2</sub><sup>-</sup> and SiO<sub>2</sub>, similarly to the step of forming the opening 222a. In this case, a resist of resin having a plurality of openings corresponding to the through-holes 232a is used.

In the next step, a plurality of through-holes 233 are formed, as shown in FIG. 95. This step can be performed by gas-phase anisotropic etching using gas containing HF, similarly to the step of forming the recess 231.

In the next step, a protective film 234 is formed, as shown in FIG. 96. This step is performed by thermal oxidization or by causing SiO<sub>2</sub> to grow by CVD.

In the next step, a vent hole 211A is formed, as shown in FIG. 97. The vent hole 211A is used to introduce etching gas from the outside to the semiconductor substrate 210 and comprises through-holes 221a, 232a and 233. Since the through-holes 232a and 233 are formed in the previous steps, a plurality of through-holes 221a are formed in this step. This step is performed by gas-phase etching using the reaction between HF<sub>2</sub><sup>-</sup> and SiO<sub>2</sub>. In this step, the insulating cover 222 and part of the insulating layer 232 are also etched to become thinner. When the insulating cover 222 or the insulating layer 232 does not have a sufficient thickness, a resist having the same shape as that used for forming the through-holes 232a can be used.

In the next step, a cavity portion 211 is formed, as shown in FIG. 98. This step is performed by gas-phase etching using gas containing atomic fluorine (F). Fluorine (F) easily reacts with silicon (Si) but does not easily react with SiO<sub>2</sub>. Thus, by sending gas containing F to the semiconductor substrate 210 through the vent holes 211A covered with SiO<sub>2</sub>, the semiconductor substrate 210 is etched and the cavity portion 211 is formed before the semiconductor layer 230A is etched. The gas containing F can be obtained by decomposing CHF<sub>3</sub> gas by discharge.

The step of forming the cavity portion 211 can be performed by etching using xenon fluoride gas. The difference between Si and SiO<sub>2</sub> in reactivity with xenon fluoride gas is larger than that in reactivity with CHF<sub>3</sub> gas. Thus, the protective film 234 can be made thinner by using xenon fluoride gas.

In the next step, the vent hole 211A is sealed, as shown in FIG. 99. By this step, part of the insulating layer 232 becomes thicker, while the sealing member 235 is formed. Specifically, in this step, low pressure chemical vapor deposition (LPCVD) using tetraethoxysilane is performed, whereby SiO<sub>2</sub> is deposited on the insulating layer 232 and in the vent holes 211A. By sealing the vent hole 211A in a vacuum state or in an atmosphere of a given pressure, the cavity portion 211 is brought into a vacuum state or at a given pressure.

The sealing of the vent hole 211A can be performed by other methods, such as thermal oxidation to utilize bulging of the oxidized portion or by plasma CVD.

In the next step, a sacrificial layer 236 is formed, as shown in FIG. 100. This step is performed by e.g. embedding polycrystalline silicon in the recess 231 and the opening 222a. In this step, abrading is performed in advance such that the surface of the sacrificial layer 236 is flush with the surface of the insulating cover 222.

In the next step, an insulating cover 223 is formed, as shown in FIG. 101. This step can be performed by thermally

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oxidizing the surface of the sacrificial layer 236. The thermal oxidization is performed such that the thickness of the insulating cover 223 becomes substantially equal to that of the insulating cover 222. In the state after this step, the opening 222a is filled with the insulating cover 223, while the recess 231 is filled with the sacrificial layer 236.

In the next step, through-holes 223a and an opening 222b are formed, as shown in FIGS. 102 and 103. This step is performed by providing a resist of resin having openings corresponding to the through-holes 223a and the opening 222b and performing gas-phase etching using the reaction between HF<sub>2</sub><sup>-</sup> and SiO<sub>2</sub>.

In the next step, a metal layer 240A is formed, as shown in FIG. 104. The metal layer 240A is a layer made of Al and formed to cover the insulating cover 222 and the insulating cover 223. In the through-holes 223a, the metal layer 240A is formed directly on the sacrificial layer 236. In the opening 222b, the metal layer is formed directly on the semiconductor layer 230A. For instance, this step can be performed by depositing Al by CVD.

In the next step, as shown in FIGS. 105 and 106, the metal layer 240A is processed to provide an electrode layer 240. For instance, this step is performed by arranging a resist having the same shape as that of the electrode layer 240 as viewed in the lamination direction and performing gas-phase etching to remove unnecessary portions. The fixed electrode 242 has through-holes 242a overlapping the through-holes 223a as noted before, so that after this step etching of the sacrificial layer 236 by using the through-holes 223a and the through-holes 242a as vent holes is possible. Thus, after this step, the sacrificial layer 236 is removed to form the cavity portion 237. The removal of the sacrificial layer 236 is performed by gas-phase etching using gas containing HF. The intermediate layer 230 is completed by the formation of the cavity portion 237, whereby the pressure sensor 201 shown in FIGS. 86 and 87 is completed.

The operation and advantages of the pressure sensor 201 are described below.

According to the manufacturing method described above, the cavity portion 211 is formed by etching the semiconductor substrate 210 through the vent hole 211A, and the cavity portion 237 is formed by etching the sacrificial layer 236 embedded in the recess 231. Thus, unlike the conventional method which uses a plurality of semiconductor substrates, the pressure sensor 201 is produced from a single semiconductor substrate 210. Thus, the pressure sensor 1 realizes a simple manufacturing process and a low manufacturing cost.

According to this embodiment, the recess 231 is formed by gas-phase etching so that the bottom surface naturally becomes parallel to the surface of the insulating cover 222. Meanwhile, the fixed electrode 242 is formed on the insulating cover 223, which is formed to be flush with the surface of the insulating cover 222. Thus, the reverse surface of the fixed electrode 242 and the bottom surface of the recess 231 which corresponds to the surface of the movable electrode of the pressure sensor 201 naturally become parallel to each other. Moreover, the depth of the recess 231 is easily adjusted by adjusting the etching time. This allows the capacitance between the fixed electrode 242 and the movable portion 261 to be set precisely to a predetermined value. Thus, the pressure sensor 201 ensures more precise pressure measurement.

Moreover, according to the present invention, the recess 231 is covered with the insulating layer 232, and the reverse surface of the fixed electrode 242 is covered with the insulating cover 223. Thus, the capacitance between the fixed electrode 242 and the movable portion 261 is relatively large. A larger capacitance between the fixed electrode 242 and the



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movable portion **261** allows more sensitive detection of changes in the capacitance. Thus, the pressure sensor **201** ensures more precise pressure measurement.

FIGS. **107-124** show other embodiments of the present invention. In these figures, the elements which are identical or similar to those of the foregoing embodiments are designated by the same reference signs as those used for the foregoing embodiments.

FIG. **107** shows a pressure sensor according to a ninth embodiment of the present invention. The pressure sensor **202** of this embodiment has the same structure as that of the pressure sensor **201** except that it does not have the insulating cover **223** provided in the pressure sensor **201**. Since the insulating cover **223** is not provided, the fixed electrode **242** of the pressure sensor **202** is made larger than the recess **231** as viewed in the lamination direction and supported on the insulating cover **222**. The pressure sensor **202** is manufactured by omitting the steps of forming the insulating cover **223** and forming through-holes **223a** from the method for manufacturing the pressure sensor **201**. Thus, the pressure sensor **202** realizes a more simple manufacturing process.

FIG. **108** shows a pressure sensor according to a tenth embodiment of the present invention. In the pressure sensor **203** of this embodiment, the cavity portion **211** is open to the reverse surface of the semiconductor substrate **210**, and to the opening **211a** is connected a pipe **263**. The pipe **263** is connected to a gas supply chamber **262**. The structures of the other parts of the pressure sensor **203** are the same as those of the pressure sensor **201**.

To form the opening **211a**, before the semiconductor layer **230A** is formed on the semiconductor substrate **210**, etching is performed with respect to the reverse surface of the semiconductor substrate **210** and a recess for connection to the cavity portion **211**, which is formed later, is formed.

The gas supply chamber **262** is used to supply gas of a given pressure to the cavity portion **211**. Thus, unlike the pressure sensor **201**, the inside of the cavity portion **211** of the pressure sensor **203** is filled with a gas of the given pressure. The movable portion **261** receives pressure from each of the gas in the cavity portion **211** and the gas in the cavity portion **237** and is deformed in accordance with the relative pressure. Thus, the pressure sensor **230** can measure the relative pressure between the pressure of the outside gas and the pressure of the gas in the cavity portion **211** which is supplied from the gas supply chamber **262**.

When the pressure sensor **203** is placed in a vacuum atmosphere, gas of an unknown pressure can be supplied from the gas supply chamber **262** into the cavity portion **211** so that the absolute pressure of the supplied gas can be measured. Similarly, when the cavity portion **237** is sealed to provide a vacuum after the pressure sensor **203** is completed, the absolute pressure of the gas in the cavity portion **211** can be measured.

FIGS. **109** and **110** show a pressure sensor according to an eleventh embodiment of the present invention. The pressure sensor **204** shown in FIGS. **109** and **110** includes a pair of plate-like members **212**, **213**, protective layers **224**, a ground electrode terminal **246**, a connection line **247** and a filling portion **248**. The structure of other portions is the same as that of the pressure sensor **201**. The ground electrode terminal **246**, the connection line **247** and the filling portion **248** are part of the electrode layer **240**.

As shown in FIG. **110**, the paired plate-like members **212** and **213** project about 7  $\mu\text{m}$  in the lamination direction from the surface of the semiconductor substrate **210**. In the hori-

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zontal direction in FIG. **110**, a movable portion **261** and a cavity portion **237** are provided between the paired plate-like member **212** and **213**.

The protective layers **224** cover the top surfaces of the paired plate-like members **212**, **213** in the lamination direction. The protective layers **224** are made of e.g.  $\text{SiO}_2$ . The protective layer **224** formed on the plate-like member **212** has an opening **224a**. The filling portion **248** is provided to fill the opening **224a**.

The ground electrode terminal **246** is a terminal for connection to external ground and provided at an appropriate position on the insulating cover **222**. The ground electrode terminal **246** is electrically connected to the filling portion **248** via the connection line **247**. The ground electrode terminal **246**, the connection line **247** and the filling portion **248** are made of e.g. Al and arranged to be electrically insulated from the fixed electrode terminal **241** and the movable electrode terminal **243**.

A method for manufacturing the pressure sensor **204** is described below with reference to FIGS. **111-124**, mainly as to the difference from the method for manufacturing the pressure sensor **201**.

First, a semiconductor substrate **210** in the form of a plate having an uniform thickness of about 100 to 1000  $\mu\text{m}$  is prepared, and the semiconductor substrate **210** is processed to have a pair of plate-like members **212** and **213** described above. In this process, a step of forming protective layers **224** as shown in FIGS. **111** and **112** and a step of thinning the semiconductor substrate **210** in the lamination direction as shown in FIG. **113** are performed. The step of forming the protective layers **224** is performed by forming an  $\text{SiO}_2$  layer having a thickness of about 0.5  $\mu\text{m}$  on the surface of the semiconductor substrate **210** by CVD or thermal oxidation and then etching away unnecessary portions. The etching may be gas-phase anisotropic etching using the reaction between  $\text{HF}_2^-$  and  $\text{SiO}_2$ . Thinning the semiconductor substrate **210** in the lamination direction can be performed by gas-phase anisotropic etching using gas containing atomic fluorine.

In the next step, an insulating layer **221** is formed, as shown in FIG. **114**. This step is performed by e.g. thermally oxidizing the surface of the semiconductor substrate **210**. In this step, the insulating layer **221** is formed on the side surfaces of the plate-like members **212**, **213** as well.

In the next step, a semiconductor layer **230A** is formed, as shown in FIG. **115**. This step is performed by embedding a polycrystalline silicon material on the semiconductor substrate **210** except the portions where the plate-like members **212**, **213** exist, and allowing it to grow. Further, in this step, after the semiconductor layer **230A** has grown sufficiently, the surface of the semiconductor layer **230A** is flattened by CMP, using the surface of the protective layer **224** as the reference.

In the next step, an insulating cover **222** is formed, as shown in FIG. **116**. For instance, this step is performed by thermally oxidizing the surface of the semiconductor layer **230A**. The thickness of the insulating cover **222** formed in this step is e.g. 0.5  $\mu\text{m}$ .

In the next step, an opening **222a** is formed, as shown in FIGS. **117** and **118**. The opening **222a** is formed to be sandwiched between the protective layers **224** on the paired support members **212** and **213**. Thereafter, the steps shown in FIGS. **91-101** of the method for manufacturing the pressure sensor **201** are performed, whereby the state shown in FIG. **119** is obtained.

In the next step, through-holes **223a**, an opening **222b** and an opening **224a** are formed, as shown in FIGS. **120** and **121**.

This step is performed by arranging a resist of resin having openings corresponding to the through-holes **223a** and the openings **222b**, **224a** and performing gas-phase etching using the reaction between  $\text{HF}_2^-$  and  $\text{SiO}_2$ .

In the next step, a metal layer **240A** is formed, as shown in FIG. **122**. The metal layer **240A** is a layer made of Al and formed to cover the insulating cover **222**, the insulating cover **223** and the protective layer **224**. In the opening **224a**, the metal layer **240A** is formed directly on the plate-like member **212**. For instance, this step is performed by depositing Al by CVD.

In the next step, the metal layer **240A** is processed to provide an electrode layer **240**, as shown in FIGS. **123** and **124**. For instance, this step is performed by arranging a resist having the same shape as that of the electrode layer **240** as viewed in the lamination direction and removing unnecessary portions by gas-phase etching. Thereafter, the sacrificial layer **236** is removed, whereby the pressure sensor **204** shown in FIGS. **109** and **110** is completed.

In the pressure sensor **204**, the semiconductor substrate **210** can be connected to external ground via the ground electrode terminal **246**. This arrangement of the pressure sensor **204** allows the capacitance between the fixed electrode **242** and the movable portion **261** to be set precisely to a predetermined value. Thus, the pressure sensor **204** ensures more precise pressure measurement.

Further, the plate-like members **212** and **213** having a relatively high strength are arranged in such a manner as to penetrate the intermediate layer **230** in the lamination direction, so that the strength of the pressure sensor **204** is enhanced. In particular, since the movable portion **261** is held between the plate-like members **212** and **213**, the movable portion **261** is not easily deformed improperly even when undesirable pressure is applied to the intermediate layer **230**. This arrangement allows the capacitance between the fixed electrode **242** and the movable portion **261** to be set precisely to a predetermined value. Thus, the pressure sensor **204** ensures more precise pressure measurement.

The pressure sensor according to the present invention is not limited to the foregoing embodiments. The specific structure of each part of the pressure sensor according to the present invention can be varied in design in many ways. For instance, although the pressure sensors **202** and **203** have a structure based on the pressure sensor **201**, they may have a structure based on the pressure sensor **204**.

In the foregoing embodiment, the semiconductor substrate **210** is made of single-crystal silicon, whereas the semiconductor layer **230A** is made of polycrystalline silicon. Unlike this, however, the semiconductor substrate **210** may be made of polycrystalline silicon, whereas the semiconductor layer **230A** may be made of single-crystal silicon. Moreover, the sacrificial layer **236** may be made of single-crystal silicon or a resin having a low reactivity with  $\text{HF}_2^-$ .

FIGS. **125** and **126** show a pressure sensor according to a twelfth embodiment of the present invention. The pressure sensor **301** of this embodiment includes a semiconductor structure **310**, an insulating layer **320**, semiconductor films **331**, **332**, connection terminals **341**, **344**, **345**, connection lines **342**, **346**, conductive portions **343**, **347** and gas supply spaces **351**, **352**, **354** and a closed space **353**. The gas supply spaces **351**, **352**, **354** are filled with air from the outside of the pressure sensor **301**. The closed space **353** is in a vacuum state.

The semiconductor structure **310** is made of e.g. a single semiconductor material made of single-crystal silicon (Si) and comprise a semiconductor substrate **311** in the form of a flat plate, a plate-like member **312** and wall portions **313**, **314**.

On the surface of the semiconductor substrate **311**, an oxide film **311a** made of e.g. silicon dioxide ( $\text{SiO}_2$ ) and having a thickness of about  $0.2\text{ }\mu\text{m}$  is provided. In the description given below, the x direction is one of the in-plane directions of the semiconductor substrate **311**, the y direction is the in-plane direction of the semiconductor substrate **311** which is perpendicular to the x direction, and the z direction is the direction perpendicular to both of the x direction and the y direction. As shown in FIG. **125**, as viewed in the z direction, the semiconductor structure **310** is in the form of a rectangle elongated in the x direction. As shown in FIG. **126**, the z direction corresponds to the lamination direction of the semiconductor substrate **311**.

The plate-like member **312** stands vertically in the z direction from the center of the semiconductor substrate **311** in the x direction. The plate-like member **312** extends along the substantially entire length of the semiconductor substrate **311** in the y direction. The dimension of the plate-like member **312** in the direction x is e.g.  $10\text{ }\mu\text{m}$ , and that in the z direction is e.g.  $100\text{ }\mu\text{m}$ . Oxide films **312a** made of e.g.  $\text{SiO}_2$  and having a thickness of about  $0.2\text{ }\mu\text{m}$  are formed on the two side surfaces of the plate-like member **312** which are spaced from each other in the x direction.

The wall portion **313** stands vertically in the direction z from the left end of the semiconductor substrate **311** in the x direction in FIG. **126**. The wall portion **313** extends along the substantially entire length of the semiconductor substrate **311** in the y direction. An oxide film **313a** made of e.g.  $\text{SiO}_2$  and having a thickness of about  $0.2\text{ }\mu\text{m}$  is formed on the right side surface of the wall portion **313** in the x direction.

The wall portion **314** projects vertically in the direction z from the right end of the semiconductor substrate **311** in the x direction in FIG. **126**. The wall portion **314** extends along the substantially entire length of the semiconductor substrate **311** in the y direction. An oxide film **314a** made of e.g.  $\text{SiO}_2$  and having a thickness of about  $0.2\text{ }\mu\text{m}$  is formed on the left side surface of the wall portion **314** in the x direction.

Though not shown in FIGS. **125** and **126**, the semiconductor substrate **311** have wall portions similar to the wall portions **313**, **314** at the ends spaced from each other in the y direction. Thus, the semiconductor structure **310** has two hollow portions partitioned by the plate-like member **312** in an area surrounded by the four wall portions. The semiconductor film **331** and the gas supply spaces **351**, **352** are positioned in the hollow portion sandwiched between the plate-like member **312** and the wall portion **313** in the x direction. The semiconductor film **332**, the closed space **353** and the gas supply space **354** are positioned in the hollow portion sandwiched between the plate-like member **312** and the wall portion **314** in the x direction.

The semiconductor film **331** is a film made of polycrystalline silicon and having a thickness of about  $4\text{ }\mu\text{m}$  in the x direction. The semiconductor film **331** has a length of e.g.  $10\text{ }\mu\text{m}$  in the z direction and extends along the substantially entire length of the semiconductor substrate **311** in the y direction. Oxide films **331a** made of e.g.  $\text{SiO}_2$  and having a thickness of about  $0.2\text{ }\mu\text{m}$  are formed on the two side surfaces of the semiconductor film **331** which are spaced from each other in the x direction. The semiconductor film **331** is positioned between the plate-like member **312** and the wall portion **313** in the x direction. The right side surface of the semiconductor film **331** in the x direction in FIG. **126** is parallel to the left side surface of the plate-like member **312**, and the distance between these two surfaces is e.g.  $2\text{ }\mu\text{m}$ . The distance between the left side surface of the semiconductor film **331** and the right side surface of the wall portion **313** is e.g.  $3\text{ to }8\text{ }\mu\text{m}$ .

The semiconductor film 331 partitions one of the above-described hollow portions into two spaces, i.e., the gas supply space 351 between the wall portion 313 and the semiconductor film 331 and the gas supply space 352 between the semiconductor film 331 and the plate-like member 312.

The semiconductor film 332 is a film made of polycrystalline silicon and having a thickness of about 4  $\mu\text{m}$  in the x direction. The semiconductor film 332 has a length of e.g. 10  $\mu\text{m}$  in the z direction and extends along the substantially entire length of the semiconductor substrate 311 in the y direction. Oxide films 332a made of e.g.  $\text{SiO}_2$  and having a thickness of about 0.2  $\mu\text{m}$  are formed on the two side surfaces of the semiconductor film 331 which are spaced from each other in the x direction. The semiconductor film 332 is positioned between the plate-like member 312 and the wall portion 314 in the x direction. The left side surface of the semiconductor film 332 in the x direction in FIG. 126 is parallel to the right side surface of the plate-like member 312, and the distance between these two surfaces is e.g. 2  $\mu\text{m}$ . The distance between the right side surface of the semiconductor film 332 and the left side surface of the wall portion 314 is e.g. 3 to 8  $\mu\text{m}$ .

The semiconductor film 332 partitions the other one of the above-described hollow portions into two spaces, i.e., the closed space 353 between the semiconductor film 332 and the plate-like member 312 and the gas supply space 354 between the semiconductor film 332 and the wall portion 314.

The insulating layer 320 is made of e.g.  $\text{SiO}_2$  and formed on the semiconductor structure 310. The insulating layer 320 has openings 320a, 320b and 320c above the gas supply spaces 351, 352 and 354. Outside air can flow into the gas supply spaces 351, 352, 354 through the openings 320a, 320b, 320c. The insulating layer 320 further has openings 320d that expose the connection terminals 341, 344, 345, the connection lines 342, 346 and the conductive portions 343, 347.

The connection terminal 341 is a terminal used for electrical connection to the outside and connected to the conductive portion 343 via the connection line 342. The conductive portion 343 is electrically connected to the semiconductor film 331.

The connection terminal 344 is a terminal used for electrical connection to the outside and electrically connected to e.g. the upper end of the wall portion 314 in the z direction. Since the semiconductor structure 310 is formed as a single integral unit, the connection terminal 344 is electrically connected to the plate-like member 312 as well.

The connection terminal 345 is a terminal used for electrical connection to the outside and connected to the conductive portion 347 via the connection line 346. The conductive portion 347 is electrically connected to the semiconductor film 332.

The operation and advantages of the pressure sensor 301 are described below.

In the pressure sensor 301, the semiconductor films 331 and 332 are not fixed in the x direction but are deformable due to the small thickness in the x direction, thereby functioning as movable electrodes. Since the semiconductor film 331 is closer to the plate-like member 312 than to the wall portion 313, the left side surface of the plate-like member 312 in the x direction functions as the fixed electrode relative to the semiconductor film 331. Similarly, since the semiconductor film 332 is closer to the plate-like member 312 than to the wall portion 314, the right side surface of the plate-like member 312 in the x direction functions as the fixed electrode relative to the semiconductor film 332. The plate-like member 312 is electrically connected to the connection terminal 344, and the semiconductor films 331 and 332 are electrically connected

to the connection terminals 341 and 345, respectively. This arrangement allows proper detection of capacitance between each of the fixed electrodes and each of the movable electrodes.

As described above, the distance between the left side surface of the plate-like member 312 in the x direction and the semiconductor film 331 and the distance between the right side surface of the plate-like member 312 in the x direction and the semiconductor film 332 are equal to each other, and the semiconductor films 331 and 332 have the same size and shape as viewed in the x direction. Thus, when the semiconductor films 331 and 332 are not deformed, the output values from the connection terminal 341 and the connection terminal 342 are substantially the same.

The semiconductor film 331 receives pressure in the x direction from both of the gas introduced into the gas supply space 351 and the gas introduced into the gas supply space 352. In this embodiment, the same outside air is introduced into the two gas supply spaces 351 and 352, so that the pressure applied to the semiconductor film 331 is balanced. Thus, the capacitance between the semiconductor film 331 and the plate-like member 312 does not change, so that the output from the connection terminal 341 serves as a constant reference value.

On the other hand, the semiconductor film 332 is sandwiched in the x direction between the vacuum closed space 353 and the gas supply space 354 in which outside air is introduced. Thus, the semiconductor film 332 receives, from the outside air introduced into the gas supply space 354, a pressure corresponding to the pressure of the outside air, and is hence deformed. Thus, the capacitance between the semiconductor film 332 and the plate-like member 312 changes in accordance with the pressure of the outside air, and the output from the connection terminal 345 is a value corresponding to the changing capacitance. By comparing this value with the reference value obtained through the connection terminal 341, the change in capacitance between the semiconductor film 332 and the plate-like member 312 is calculated, and based on the change in capacitance, the pressure of the outside air is calculated. Thus, the pressure sensor 301 is suitable for measuring the absolute pressure of the outside air.

A method for manufacturing the pressure sensor 301 is described below with reference to FIGS. 127-145.

First, a semiconductor material 310A made of a single-crystal silicon and in the form of a rectangular parallelepiped is prepared, and the semiconductor material 310A is processed to provide a semiconductor structure 310.

To process the semiconductor material 310A, an insulating layer 321 of  $\text{SiO}_2$  is formed on the surface of the semiconductor material 310A. This step can be performed by thermally oxidizing the surface of the semiconductor material 310A. Alternatively, chemical vapor deposition (CVD) may be employed.

In the next step, as shown in FIGS. 127 and 128, openings 322 and 323 are formed in the insulating layer 321 to expose the surface of the semiconductor material 310A. The opening 322 is formed in an area that overlaps the area where the gas supply spaces 351, 352 and the semiconductor film 331 are to be formed, as viewed in the z direction. The opening 323 is formed in an area that overlaps the area where the closed space 353, the gas supply space 354 and the semiconductor film 332 are to be formed, as viewed in the z direction. For instance, this step is performed by providing a resist of resin which exposes the portions where the openings 322 and 323 are to be formed and performing gas-phase etching using the reaction between fluorine-containing molecular ions ( $\text{HF}_2^-$ ) and  $\text{SiO}_2$ . For instance,  $\text{HF}_2^-$  can be obtained by reacting

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hydrogen fluoride (HF) with water vapor. For instance, HF can be obtained by reacting atomic fluorine (F) or molecular fluorine (F<sub>2</sub>), which is obtained by e.g. decomposing carbon tetrafluoride (CF<sub>4</sub>) gas or trifluoromethane (CHF<sub>3</sub>) gas, with water vapor. Since Si which is not oxidized does not easily react with HF<sub>2</sub><sup>-</sup>, the semiconductor layer 310A is not removed by the etching and hence remains. Instead of the gas-phase etching, wet etching using aqueous solution of hydrogen fluoride (HF) may be performed.

In the next step, etching in the z direction is performed with respect to the semiconductor material 310A, as shown in FIG. 129. Through this step, the semiconductor structure 310 is obtained as a remaining portion of the semiconductor material 310A. This step can be performed by Si-DRIE (deep reactive ion etching) utilizing the Bosch (registered trademark) process. The Bosch process is a process in which etching and side wall protection are performed repeatedly and which allows etching with a high aspect ratio. As a result of this step, the portions of the semiconductor material 310A which are covered with the insulating layer 321 remain, whereby the plate-like member 312, the wall portions 313, 314 and the wall portions spaced in the y direction are provided. The etching time is adjusted so as not to penetrate the semiconductor material 310 in the z direction, so that the bottom of the semiconductor material 310A remains to become the semiconductor substrate 311.

In the next step, oxide films 311a, 312a, 313a and 314a are formed, as shown in FIG. 130. This step can be performed by thermally oxidizing the surface of the semiconductor structure 310. The films can be formed by depositing SiO<sub>2</sub> by CVD.

In the next step, a semiconductor layer 331A and a semiconductor layer 332A are formed, as shown in FIG. 131. The semiconductor layer 331A is made of polycrystalline silicon and formed to fill the space between the wall portion 313 and the plate-like member 312. The semiconductor layer 332A is made of polycrystalline silicon and formed to fill the space between the wall portion 314 and the plate-like member 312. This step is performed by e.g. epitaxial growth of polycrystalline silicon on the semiconductor substrate 311 by CVD. Also in this step, the surfaces of the semiconductor layers 331A and 332A are flattened. The flattening can be performed by e.g. chemical mechanical polishing (CMP).

In the next step, as shown in FIG. 132, an insulating layer 324A is formed on the surface of the semiconductor layer 331A, and an insulating layer 325A is formed on the surface of the semiconductor layer 332A. The insulating layer 324A is formed to cover the entire portion of the semiconductor layer 331A which is not covered with the insulating layer 321. The insulating layer 325A is formed to cover the entire portion of the semiconductor layer 332A which is not covered with the insulating layer 321. The insulating layers 324A and 325A are made of SiO<sub>2</sub> and have a thickness of e.g. about 0.8 μm. This step can be performed by thermal oxidation or CVD. By this step, the openings 322 and 323 are closed by the insulating layers 324A and 325A.

In the next step, insulating layers 324, 325 and openings 322a, 322b, 323a, 323b are formed, as shown in FIGS. 133 and 134. The insulating layer 324 is formed in an area that overlaps the area where the semiconductor film 331 is to be formed, as viewed in the z direction. The insulating layer 325 is formed in an area that overlaps the area where the semiconductor film 332 is to be formed, as viewed in the z direction. The opening 322a is formed to expose the semiconductor layer 331A in an area that overlaps the area where the gas supply space 352 is to be formed, as viewed in the z direction. The opening 322b is formed to expose the semiconductor

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layer 331A in an area that overlaps the area where the gas supply space 351 is to be formed, as viewed in the z direction. The opening 323a is formed to expose the semiconductor layer 332A in an area that overlaps the area where the closed space 353 is to be formed, as viewed in the z direction. The opening 323b is formed to expose the semiconductor layer 332A in an area that overlaps the area where the gas supply space 354 is to be formed, as viewed in the z direction. This step can be performed by the same technique as that used for forming the openings 322 and 323.

In the next step, a semiconductor film 331 and a semiconductor film 332 are formed, as shown in FIG. 135. In this step, etching in the z direction is performed with respect to the semiconductor layers 331A and 332A. For instance, the etching in this step can be performed by Si-DRIE utilizing the Bosch (registered trademark) process. In this step, the semiconductor layer 30 under the insulating layers 324, 25 remains, whereby semiconductor films 331, 332 are provided.

In the next step, oxide films 331a, 32a are formed, as shown in FIG. 136. For instance, this step can be performed by thermal oxidation or CVD.

In the next step, sacrificial layers 326A, 327A, 328A and 329A are formed, as shown in FIG. 137. For instance, the sacrificial layers 326A, 327A, 328A and 329A are made of polycrystalline silicon or a resin such as polyimide. The sacrificial layer 326A is formed to fill the space where the gas supply space 351 is to be formed. The sacrificial layer 327A is formed to fill the space where the gas supply space 352 is to be formed. The sacrificial layer 328A is formed to fill the space where the closed space 353 is to be formed. The sacrificial layer 329A is formed to fill the space where the gas supply space 354 is to be formed.

In the next step, insulating layers 326, 327, 328 and 329 are formed on the surfaces of the sacrificial layers 326A, 327A, 328A and 329A as shown in FIG. 138. This step can be performed by thermal oxidation or CVD.

In the next step, as shown in FIGS. 139 and 140, openings 326a, 327a, 328a and 329a are formed in the insulating layers 326, 327, 328 and 329, an opening 324a is formed in the insulating layer 324, an opening 325a is formed in the insulating layer 325, and an opening 321a is formed in the insulating layer 321. This step is performed by gas-phase etching using the reaction between HF<sub>2</sub><sup>-</sup> and SiO<sub>2</sub> by using a resist of resin having openings corresponding to the openings 321a, 324a, 325a, 326a, 327a, 328a and 329a.

In the next step, a metal layer 340 is formed, as shown in FIG. 141. The metal layer 340 is made of e.g. Al and formed to cover the insulating layers 321, 324, 325, 326, 327, 328 and 329. For instance, this step can be performed by depositing Al by CVD.

In the next step, as shown in FIGS. 142 and 143, the metal layer 340 is processed to provide connection terminals 341, 344, 345, connection lines 342, 346 and conductive portions 343, 347. For instance, this step is performed by arranging a resist having a shape corresponding to the shapes of the connection terminals 341, 344, 345, connection lines 342, 346 and conductive portions 343, 347 and removing unnecessary portions of the Al metal layer by gas-phase etching.

In the next step, sacrificial layers 326A, 327A, 328A and 329A are removed, as shown in FIG. 144. For instance, this step can be performed by gas-phase etching using gas containing xenon fluoride (XeF<sub>2</sub>). By the removal of the sacrificial layers 326A, 327A, 328A and 329A, cavity portions 351A, 352A, 353A and 354A are provided.

In the next step, openings 326a, 327a, 328a and 329a are sealed, and an insulating layer 320 is formed, as shown in

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FIG. 145. This step is performed by depositing SiO<sub>2</sub> on the insulating layers 321, 324, 325, 326, 327, 328 and 329 by low pressure chemical vapor deposition (LPCVD) or plasma CVD in a vacuum atmosphere. In this step, SiO<sub>2</sub> grows from the edges of the openings 326a, 327a, 328a and 329a toward the center, so that the sealing portion formed in this step tends to be thin at the center. In this embodiment, the insulating layer 320 is deposited to a thickness sufficient to cover the connection terminals 341, 344, 345, the connection lines 342, 346 and the conductive portions 343, 347. When a mask is used, SiO<sub>2</sub> may not be deposited on the connection terminals 341, 344, 345, the connection lines 342, 346 and the conductive portions 343, 347.

In the next step, openings 320a, 320b, 320c and 320d are formed, whereby the pressure sensor 301 shown in FIGS. 125 and 126 is completed. The step of forming the openings 320a, 320b, 320c and 320d is performed by gas-phase etching using the reaction between HF<sub>2</sub><sup>-</sup> and SiO<sub>2</sub> by using a resist of resin having openings corresponding to the openings 320a, 320b, 320c and 320d. In this embodiment, SiO<sub>2</sub> is deposited on the connection terminals 341, 344, 345, the connection lines 342, 346 and the conductive portions 343, 347 in the previous step. Thus, by forming the opening 320d, the connection terminals 341, 344, 345 are exposed outside the insulating layer 320. According to this manufacturing method, as shown in FIG. 126, the surfaces of the connection terminals 341, 344, 345, the connection lines 342, 346 and the conductive portions 343, 347 become lower than the surface of the insulating layer 320. When a mask is provided on the connection terminals 341, 344, 345, the connection lines 342, 346 and the conductive portions 343, 347 in the previous step, SiO<sub>2</sub> may not be deposited on the connection terminals 341, 344, 345, the connection lines 342, 346 and the conductive portions 343, 347. In this case, opening 320d may not need to be formed.

The operation and advantages of the pressure sensor 301 are described below.

As noted before, in the pressure sensor 301, the right and left side surfaces, which are spaced from each other in the direction x, of the plate-like member 312 standing from the surface of the semiconductor substrate 311 function as fixed electrodes, whereas the side surfaces of the semiconductor films 331, 332 which face the plate-like member 312 in the x direction function as movable electrodes. In this way, in the pressure sensor 301, the fixed electrodes and the movable electrodes stand on the semiconductor substrate 311 in the z direction. With this arrangement, fixed electrodes and movable electrodes can be made in a relatively small area of the semiconductor substrate 311, as viewed in the z direction. Accordingly, the area of the pressure sensor 301 as viewed in the z direction can be made smaller, which leads to size reduction of the pressure sensor 301. Thus, the pressure sensor can be set in a small area in e.g. an electronic device.

According to the manufacturing method of this embodiment, the plate-like member 312 standing in the z direction is formed easily by performing etching in the z direction with respect to the semiconductor material 310A. Moreover, the semiconductor films 331 and 332 are formed easily by performing etching in the z direction with respect to the semiconductor layers 331A, 332A.

In the foregoing embodiment, the space between the plate-like member 312 and the semiconductor film 332 is the closed space 353, whereas the space between the semiconductor film 332 and the wall portion 314 is the gas supply space 354. However, these may be replaced with each other. The pressure sensor may be designed to enclose gas of a given pressure in the closed space 353 and measure the relative pressure between the gas and the pressure of the outside air.

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FIGS. 146-153 show other embodiments of the present invention. In these figures, the elements which are identical or similar to those of the foregoing embodiments are designated by the same reference signs as those used for the foregoing embodiments.

FIGS. 146 and 147 show a pressure sensor according to a thirteenth embodiment of the present invention. The pressure sensor 302 of this embodiment includes a gas supply space 353' instead of the closed space 353, and openings 320e, 320f instead of the openings 320a, 320b, 320c. The structures of other parts of the pressure sensor 302 are the same as those of the pressure sensor 301.

The openings 320e are provided between the wall portion 313 and the semiconductor film 331 and between the plate-like member 312 and the semiconductor film 332 in the x direction. The opening 320e is connected via e.g. a pipe to a gas source capable of supplying gas of a given pressure. Thus, the gas supply spaces 351 and 353' are filled with the gas of a given pressure supplied from the gas source.

The openings 320f are provided between the semiconductor film 331 and the plate-like member 312 and between the semiconductor film 332 and the wall portion 314. Outside air is taken in through the openings 320f, so that outside air whose pressure is to be measured is introduced into the gas supply spaces 352, 354.

In the pressure sensor 302, the semiconductor film 331 is deformed due to the pressure difference between the gas of a given pressure introduced into the gas supply space 351 and the outside air introduced into the gas supply space 352. The deformation causes a change in capacitance between the semiconductor film 331 and the plate-like member 312, and the change is detected through the connection terminal 341. On the other hand, the semiconductor film 332 is deformed due to the pressure difference between the gas of a given pressure introduced into the gas supply space 353' and the outside air introduced into the gas supply space 354. The deformation causes a change in capacitance between the semiconductor film 332 and the plate-like member 312, and the change is detected through the connection terminal 345.

For instance, when the pressure of the gas from the gas source is higher than the pressure of the outside air, the semiconductor film 331 is deformed toward the plate-like member 312 in the x direction, whereas the semiconductor film 332 is deformed to be away from the plate-like member 312. Thus, the capacitance between the semiconductor film 331 and the plate-like member 312 increases in accordance with the pressure difference between the gas from the gas source and the outside air, whereas the capacitance between the semiconductor film 332 and the plate-like member 312 decreases in accordance with the pressure difference. The capacitances show the opposite behavior when the pressure of the gas from the gas source is lower than the pressure of the outside air.

Thus, the difference between the change in capacitance detected through the connection terminal 341 and that detected through the connection terminal 345 is twice the change in capacitance at one of the semiconductor films 331 and 332. In the pressure sensor 302, therefore, the difference between the changes in capacitance detected respectively through the connection terminal 341 and the connection terminal 345 is halved, and the pressure of the outside air relative to the pressure of the gas from the gas supply is calculated based on the halved value.

In the pressure sensor 302 having the above-described structure, a change in capacitance, which is usually of a small value, is detected as doubled, which allows more precise measurement.

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Unlike the above, outside air may be introduced through the openings **320e**, while gas of a given pressure may be introduced through the openings **320f**.

FIG. **148** shows a pressure sensor according to a fourteenth embodiment of the present invention. In the pressure sensor **303** of this embodiment, the plate-like member **312** does not comprise part of the semiconductor structure **310**, but is made of polycrystalline silicon. The structures of the other parts of the pressure sensor **303** are the same as those of the pressure sensor **301**. In the pressure sensor **303**, the plate-like member **312** is not electrically connected to the wall portion **314**. Thus, the connection terminal **344** is formed directly on the plate-like member **312** in the *z* direction for electrical connection to the plate-like member **312**.

In the process of manufacturing the pressure sensor **303**, etching of the semiconductor material **310A** is performed such that the portion between the wall portion **313** and the wall portion **314** in the *x* direction is entirely etched away. Thereafter, a semiconductor layer **330A** is formed to fill the space between the wall portion **313** and the wall portion **314**, and an insulating layer **321'** is formed, along with insulating layers **324**, **325**, on the semiconductor layer **330A**, as shown in FIG. **149**. Thereafter, etching in the *z* direction is performed with respect to the semiconductor layer **330A**, whereby the plate-like member **312** as well as the semiconductor films **331**, **332** are provided as remaining portions of the semiconductor layer **330A**.

With this pressure sensor **303**, movable electrodes and fixed electrodes, which require precise processing, are formed at the same time. Thus, the manufacturing process is simple.

FIG. **150** shows a pressure sensor according to a fifteenth embodiment of the present invention. In the pressure sensor **304** shown in FIG. **150**, the plate-like member **312** and the wall portions **313**, **314** are made of polycrystalline silicon, and the connection terminal **344** is formed directly on the plate-like member **312** in the *z* direction for electrical connection to the plate-like member **312**. In the pressure sensor **304**, the wall portions provided at the ends spaced in the *y* direction in the pressure sensor **301** are not provided, to insulate the plate-like member **312** from the semiconductor films **331**, **332**. The structures of the other parts of the pressure sensor **304** are the same as those of the pressure sensor **301**.

The pressure sensor **304** is made of the semiconductor material **310B** shown in FIG. **151**, instead of the semiconductor material **310A** of single-crystal silicon shown in FIG. **128**. The semiconductor material **310B** comprises a semiconductor substrate **311** in the form of a flat plate, an oxide film **311a** formed on the semiconductor substrate **311**, and a semiconductor layer **330A** formed on the oxide film **311a**.

To manufacture the pressure sensor **304**, an insulating layer **321** as shown in FIGS. **152** and **153** is formed, and etching in the *z* direction is performed with respect to the semiconductor layer **330A**. The insulating layer **321** of this embodiment has openings **322c**, **322d**, **323c** and **323d** penetrating in the *y* direction, instead of the openings **322a**, **322b**, **323a**, **323b**. Thus, by the etching, the semiconductor films **331**, **332**, the plate-like member **312** and the wall portions **313**, **314** are formed at one time, as remaining portions of the semiconductor layer **330A**. The subsequent steps are the same as those for manufacturing the pressure sensor **301**. In this embodiment, however, in or before forming the insulating layer **320**, the space between the semiconductor film **332** and the plate-like member **312** are closed by an insulating material at the ends spaced from each other in the *y* direction to form the closed space **353**.

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As compared with the pressure sensor **301**, the pressure sensor **304** can be manufactured through a smaller number of etching steps and hence realizes a simple manufacturing process.

A pressure sensor similar to the pressure sensors **301**, **303** can be manufactured by processing the semiconductor material **310B** in a manner similar to the semiconductor material **310A**. In this case, in forming the semiconductor structure **310**, the step of etching the semiconductor material **310A** using gas containing F is replaced with the step of etching the semiconductor material **310B** using gas containing HF.

The pressure sensor according to the present invention is not limited to the foregoing embodiments. The specific structure of each part of the pressure sensor and the specific way of each step of its manufacturing method according to the present invention can be varied in design in many ways. For instance, although the pressure sensors **303** and **304** have a structure based on the pressure sensor **301**, it may have a structure based on the pressure sensor **302**.

Although the pressure sensor **301** includes a semiconductor film **331** for outputting a reference value, a capacitor capable of outputting the value equal to the reference value may be provided in the circuit in which the pressure sensor is arranged. In this case, the left half in FIG. **126** of the pressure sensor **301** can be omitted.

The invention claimed is:

1. A pressure sensor comprising a movable electrode and a fixed electrode arranged in parallel to each other, further comprising:

- a semiconductor substrate;
- a first insulating layer formed on the semiconductor substrate;
- a semiconductor layer formed on the semiconductor substrate, with the first insulating layer intervening therebetween;
- a second insulating layer formed on the semiconductor layer;
- a first cavity portion formed in the semiconductor substrate;
- a second cavity portion overlapping the first cavity portion as viewed in a lamination direction and formed in contact with the second insulating layer, wherein:
  - the fixed electrode faces the second insulating layer across the second cavity portion;
  - the movable electrode is provided at a portion of the semiconductor layer which is sandwiched between the first cavity portion and the second cavity portion;
  - the movable electrode includes a through-hole penetrating the semiconductor layer in the lamination direction; and
  - the pressure sensor further comprises a sealing member which is disposed within the through-hole and seals the through-hole.

2. The pressure sensor according to claim 1, wherein the sealing member is made of a different material from the semiconductor layer.

3. The pressure sensor according to claim 2, wherein the semiconductor layer is made of silicon, whereas the sealing member is made of silicon dioxide.

4. The pressure sensor according to claim 1, further comprising a third insulating layer facing the second insulating layer across the second cavity portion, wherein the fixed electrode is provided on the third insulating layer.

5. The pressure sensor according to claim 1, further comprising a vent hole penetrating the fixed electrode in the lamination direction, one end of the vent hole in the lamination direction reaching the second cavity portion.

6. The pressure sensor according to claim 1, further comprising a movable electrode terminal electrically connected to the semiconductor layer.

7. The pressure sensor according to claim 1, wherein the semiconductor substrate is provided with a pair of plate-like members projecting in the lamination direction and facing each other, and

the movable electrode and the second cavity portion are sandwiched between the paired plate-like members.

8. The pressure sensor according to claim 7, further comprising a protective layer formed on the paired plate-like members and including an opening which exposes a surface of at least one of the plate-like members, and a ground electrode terminal electrically connected to the semiconductor substrate via the opening.

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